

THE ISOMORPHISMS OF SYMPLECTIC GROUPS OVER Φ -SURJECTIVE RINGS

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Abstract

Let R and R_1 are Φ -surjective rings with 2 as a unit. Then $\Delta: S_{p_n}(R) \rightarrow S_{p_{n_1}}(R_1)$ is a group isomorphism if and only if $n=n_1$, there exists a ring homomorphism $\sigma: R \rightarrow R_1$ and Δ has the standard form $\Delta X = P X \sigma P^{-1}$, for all X in $S_{p_n}(R)$, where P is a generalized symplectic matrix.

Let R be a commutative ring with 1, $\text{Max}(R)$ be the set of all its maximal ideals. For any ideal A in R , we have a natural ring homomorphism of R onto R/A which is denoted by λ_A . As is well known

$$R \rightarrow \prod_{M \in \text{Max}(R)} R/M \text{ by } x \mapsto (\dots, \lambda_M x, \dots)$$

is a ring homomorphism. This homomorphism, in general, is not surjective. If there exists $\{M_t\}_{t \in T} \subseteq \text{Max}(R)$ such that

$$\Phi: R \rightarrow \prod_{t \in T} R/M_t$$

is a surjective homomorphism, and $M \subseteq \bigcup_{t \in T} M_t$ for each M in $\text{Max}(R)$, then we call R a Φ -surjective ring. Clearly, the semi-local rings, the infinite complete direct product of fields are all Φ -surjective rings.

The set $\{M_t\}_{t \in T}$ in above definition is called the defining system of ideals of the Φ -surjective ring R .

It is easy to see that, $\text{Ker } \Phi = J(R)$ and $x \in R^* \Leftrightarrow \Phi(x) \in (\prod_{t \in T} R/M_t)^* \Leftrightarrow \lambda_t x \neq 0$ for all $t \in T$, where $J(R)$ is the Jacobson radical of R , R^* the set of units in R .

In this note, we always assume that R and R_1 are Φ -surjective rings with 2 as a unit, $S_{p_n}(R)$ and $S_{p_{n_1}}(R_1)$ are symplectic groups with $n, n_1 \geq 4$, and $\{M_t\}_{t \in T}, \{N_s\}_{s \in S}$ are the defining system of ideals of R and R_1 respectively.

We shall determine the isomorphisms between two symplectic groups. The main result is the following

Theorem Under the above assumption, $\Delta: S_{p_n}(R) \rightarrow S_{p_{n_1}}(R)$ is a group isomor-

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*) The matrices in $GR_{p_n}(R)$ are called generalized symplectic.

$$T_1, J_{1j}, J_{j1}, (j=2, \dots, \nu), T_{1,\nu+1}(a) (a \in R), \begin{pmatrix} I^{(\nu)} \\ -I^{(\nu)} \end{pmatrix}.$$

Lemma 2. Suppose that G is a normal subgroup of $S_{p_n}(R)$, and $O(G) = R$. Then $G = S_{p_n}(R)$.

Proof (1) If there is a matrix $X \in G$ such that $O(X) = R$, then the normal subgroup generated by X coincides with $S_{p_n}(R)$ by [2]. Hence $G = S_{p_n}(R)$.

(2) If $X_1, X_2 \in G$, $T_i = \{t \in T \mid X_i \notin GS_{p_n}(R, M_t)\}$, $T_i \neq \emptyset$, $T_1 \cap T_2 = \emptyset$, then there exists $Y \in G$ such that $Y \notin GS_{p_n}(R, M_t)$ if $t \in T_1 \cup T_2$ and $Y \in GS_{p_n}(R, M_t)$ if $t \in T - (T_1 \cup T_2)$.

Pick $a \in R$ as follows: $\lambda_t a = 0$ for $t \in T_1$, and $\lambda_t a = 1$ for $t \in T - T_1$. Then we can see that $O\left(X_1 \begin{pmatrix} I^{(\nu)} & aE_{11} \\ & I^{(\nu)} \end{pmatrix}\right) = R$. Thus, by step (1), there exist $P_i \in S_{p_n}(R)$ and $m \in \mathbb{Z}^+$ such that

$$\begin{pmatrix} I & E_{11} \\ & I \end{pmatrix} = \prod_{i=1}^m P_i \left(X_1 \begin{pmatrix} I & aE_{11} \\ & I \end{pmatrix} \right)^{\pm 1} P_i^{-1}.$$

Let $Y_1 = \prod_{i=1}^m P_i X_1^{\pm 1} P_i^{-1}$. Then $\lambda_t Y_1 = \begin{pmatrix} I & E_{11} \\ & I \end{pmatrix}$ for t in T_1 and $\lambda_t Y_1$ is in the center of $S_{p_n}(R/M_t)$ for t in $T - T_1$, that is, $Y_1 \notin GS_{p_n}(R, M_t)$, $t \in T_1$ and $Y_1 \in GS_{p_n}(R, M_t)$, $t \in T - T_1$.

Consider X_2 . By the same reason, we can find $Y_2 \in G$ such that $Y_2 \notin GS_{p_n}(R, M_t)$ for t in T_2 and $Y_2 \in GS_{p_n}(R, M_t)$ for t in $T - T_2$. Let $Y = Y_1 Y_2$. Then $Y \in G$ and $Y \notin GS_{p_n}(R, M_t)$ for $t \in T_1 \cup T_2$ and $Y \in GS_{p_n}(R, M_t)$ for $t \in T - (T_1 \cup T_2)$.

(3) By $O(G) = R$, there exist $X_i \in G$, $i=1, \dots, k$ such that

$$\sum_{i=1}^k O(X_i) = R.$$

Let $T = \{t \in T \mid X_i \notin GS_{p_n}(R, M_t), i=1, \dots, k\}$. Without loss of generality, we can assume that $T_i \neq \emptyset$, $T_i \cap (T_1 \cup \dots \cup T_{i-1} \cup T_{i+1} \cup \dots \cup T_k) = \emptyset$, $1 \leq i \leq k$ and $T = T_1 \cup \dots \cup T_k$.

Since X_1, X_2 satisfy the condition in (2), there is $Y \in G$ such that $Y \notin GS_{p_n}(R, M_t)$ for $t \in T_1 \cup T_2$ and $Y \in GS_{p_n}(R, M_t)$ for $t \in T - (T_1 \cup T_2)$. It is clear that Y and X_3 also satisfy the condition which X_1 and X_2 satisfy. So we have $Z \in G$ such that $Z \notin GS_{p_n}(R, M_t)$ if $t \in T_1 \cup T_2 \cup T_3$ and $Z \in GS_{p_n}(R, M_t)$ if $t \in T - (T_1 \cup T_2 \cup T_3)$. Repeat step (2), we shall have our lemma.

Lemma 3. For any ideal A in R , we have

$$SS_{p_n}(R, A) = [SS_{p_n}(R, A), S_{p_n}(R)] = [GS_{p_n}(R, A), S_{p_n}(R)].$$

Proof Let $G = [SS_{p_n}(R, A), S_{p_n}(R)]$.

(1) Suppose $n \geq 6$. Take $a \in A$. Since

$$X_1 = \begin{pmatrix} T_{v1}^{(p)}(1) & & \\ & T_{1v}^{(p)}(-1) & \\ & & \end{pmatrix} \begin{pmatrix} I & aE_{11} \\ & I \end{pmatrix} \begin{pmatrix} T_{v1}^{(p)}(1) & & \\ & T_{1v}^{(p)}(-1) & \\ & & \end{pmatrix}^{-1} \begin{pmatrix} I & aE_{11} \\ & I \end{pmatrix}^{-1}$$

$$= \begin{pmatrix} I & aE_{\nu\nu} + aE_{1\nu} + aE_{\nu 1} \\ & I \end{pmatrix} \in G,$$

$$X_2 = \begin{pmatrix} T_{\nu 2}^{(\nu)}(1) & & \\ & T_{2\nu}^{(\nu)}(-1) & \\ & & I \end{pmatrix} \begin{pmatrix} I & aE_{12} + aE_{21} \\ & I \end{pmatrix} \begin{pmatrix} T_{\nu 2}^{(\nu)}(1) & & \\ & T_{2\nu}^{(\nu)}(-1) & \\ & & I \end{pmatrix}^{-1}$$

$$\times \begin{pmatrix} I & aE_{12} + aE_{21} \\ & I \end{pmatrix}^{-1} = \begin{pmatrix} I & aE_{1\nu} + aE_{\nu 1} \\ & I \end{pmatrix} \in G.$$

We have

$$\begin{pmatrix} I & aE_{11} \\ & I \end{pmatrix} = \begin{pmatrix} & & 1 & & \\ & I & & & \\ 1 & & & & \\ & & & 1 & \\ & & I & & \\ & & & & 1 \end{pmatrix} X_1 X_2^{-1} \begin{pmatrix} & & 1 & & \\ & I & & & \\ 1 & & & & \\ & & & 1 & \\ & & I & & \\ & & & & 1 \end{pmatrix}^{-1} \in G.$$

Therefore, the normal subgroup generated by $\begin{pmatrix} I & aE_{11} \\ & I \end{pmatrix}$ is contained in G . So $S_{p_n}(R, A) \subseteq G$ by [2], and

$$SS_{p_n}(R, A) = [S_{p_n}(R, A), S_{p_n}(R)].$$

(2) If $n=4$, since $R/M \neq F_2$, $\forall t \in T$, we can pick an ε in R^* such that $\varepsilon(\varepsilon-1) \in R^*$. So for any $a \in A$, we have

$$Y_1 = \begin{pmatrix} \varepsilon & & & \\ & 1 & & \\ & & \varepsilon^{-1} & \\ & & & 1 \end{pmatrix} \begin{pmatrix} I & 0 & a \\ & a & 0 \\ & & I \end{pmatrix} \begin{pmatrix} \varepsilon & & & \\ & 1 & & \\ & & \varepsilon^{-1} & \\ & & & 1 \end{pmatrix}^{-1} \begin{pmatrix} I & 0 & a \\ & a & 0 \\ & & I \end{pmatrix}^{-1}$$

$$= \begin{pmatrix} I & 0 & (\varepsilon-1)a \\ & (\varepsilon-1)a & 0 \\ & & I \end{pmatrix} \in G,$$

$$Y_2 = \begin{pmatrix} \varepsilon-1 & & & \\ & 1 & & \\ & & (\varepsilon-1)^{-1} & \\ & & & 1 \end{pmatrix} \begin{pmatrix} I & 0 & a \\ & a & 0 \\ & & I \end{pmatrix} \begin{pmatrix} \varepsilon-1 & & & \\ & 1 & & \\ & & (\varepsilon-1)^{-1} & \\ & & & 1 \end{pmatrix}^{-1}$$

$$= \begin{pmatrix} I & 0 & (\varepsilon-1)a \\ & (\varepsilon-1)a & a \\ & & I \end{pmatrix} \in G.$$

Hence, we also have

$$\begin{pmatrix} I & aE_{11} \\ & I \end{pmatrix} = \begin{pmatrix} & & 1 & \\ & 1 & & \\ & & & 1 \\ & & & & 1 \end{pmatrix} Y_2 Y_1^{-1} \begin{pmatrix} & & 1 & \\ & 1 & & \\ & & & 1 \\ & & & & 1 \end{pmatrix} \in G.$$

So $SS_{p_n}(R, A) = [SS_{p_n}(R, A), S_{p_n}(R)]$. $G = [GS_{p_n}(R, A), S_{p_n}(R)]$ is trivial.

Lemma 4. If Δ is a group isomorphism of $S_{p_n}(R)$ onto $S_{p_{n_1}}(R_1)$, then there is a bijection τ between $\text{Max}(R)$ and $\text{Max}(R_1)$ such that

$$\Delta SS_{p_n}(R, M) = S_{p_{n_1}}(R, \tau(M)), \quad \forall M \in \text{Max}(R). \quad (*)$$

Further, the isomorphism Δ induces a set of isomorphisms $\Delta_{\tau(M)}$ of $S_{p_n}(R/M)$ onto $S_{p_{n_1}}(R_1/\tau(M))$ with

$$\Delta_{\tau(M)}(\lambda_M X) = \lambda_{\tau(M)}(\lambda X), \quad \forall X \in S_{p_n}(R), M \in \text{Max}(R).$$

Proof For each $M \in \text{Max}(R)$, there is an N in $\text{Max}(R_1)$ such that

$$\Delta SS_{p_n}(R, M) \subseteq GS_{p_{n_1}}(R_1, N),$$

since $\Delta SS_{p_n}(R, M)$ is a normal subgroup of $S_{p_{n_1}}(R_1)$. But

$$SS_{p_n}(R, M) = [S_{p_n}(R), GS_{p_n}(R, M)] = [S_{p_n}(R), SS_{p_n}(R, M)]$$

by lemma 3. So we have

$$\Delta SS_{p_n}(R, M) \subseteq [S_{p_{n_1}}(R_1), GS_{p_{n_1}}(R_1, N)] = SS_{p_{n_1}}(R_1, N).$$

Similarly, there exists $M_1 \in \text{Max}(R)$ such that

$$\Delta^{-1} SS_{p_{n_1}}(R_1, N) \subseteq SS_{p_n}(R, M_1).$$

Hence $\Delta SS_{p_n}(R, M) \subseteq SS_{p_{n_1}}(R_1, N) \subseteq \Delta SS_{p_n}(R, M_1)$. Consequently $M \subseteq M_1$, $M = M_1$, i. e.

$$\Delta SS_{p_n}(R, M) = SS_{p_{n_1}}(R_1, N).$$

Now let $\tau: M \rightarrow N$. It is easy to see that τ is a bijection of $\text{Max}(R)$ onto $\text{Max}(R_1)$ and

$$S_{p_n}(R)/SS_{p_n}(R, M) \simeq S_{p_{n_1}}(R_1)/SS_{p_{n_1}}(R_1, \tau(M)). \quad (1)$$

Hence

$$S_{p_n}(R/M) \xrightarrow{\Delta_{\tau(M)}} S_{p_{n_1}}(R_1/\tau(M)). \quad (2)$$

The $\Delta_{\tau(M)}(\lambda_M X) = \lambda_{\tau(M)}(\lambda X)$ can be obtained by (1) and (2) immediately.

Lemma 5. Suppose that $\Delta: S_{p_n}(R) \rightarrow S_{p_{n_1}}(R_1)$ is an isomorphism, $\{M_t\}_{t \in T}$ is a defining system of ideals of R . Then the $\{\tau(M_t)\}_{t \in T} = \{N_{s_t}\}_{t \in T}$ obtained from $\tau: \text{Max}(R) \rightarrow \text{Max}(R_1)$ by restriction is a defining system of ideals of R_1 .

Proof For each $t \in T$, take a b_t in R_1/N_{s_t} . There is an X_t in $S_{p_n}(R/M_t)$ such that $\Delta_{s_t} X_t = T_{1, \nu+1}(b_t)$. But we have an X in $S_{p_n}(R)$ such that $\lambda_t X = X_t$ for all $t \in T$. Therefore we have $\Delta_{s_t}(\lambda_t X) = \lambda_{s_t}(\Delta X) = T_{1, \nu+1}(b_t)$. Let b be the element of ΔX in $(1, \nu+1)$ position. Then we have $\lambda_{s_t} b = b_t$ for all $t \in T$ by

$$\lambda_{s_t}(\Delta X) = T_{1, \nu+1}(b_t).$$

Thus $b \mapsto (\dots \lambda_{s_t} b \dots)$ is a surjective homomorphism of R_1 onto $\prod_{t \in T} R_1/N_{s_t}$, i.e. $\{N_{s_t}\}_{t \in T}$ is a defining system of ideals of R_1 .

By this lemma, if $S_{p_n}(R) \simeq S_{p_{n_1}}(R_1)$ and $\{M_t\}_{t \in T}$ is a defining system of ideals of R , then we can assume that the defining system of R_1 is $\{N_{s_t}\}_{t \in T}$, which satisfy

$$\Delta SS_{p_n}(R, M_t) = SS_{p_{n_1}}(R_1, N_{s_t}), \quad \forall t \in T.$$

Besides, by the proof of this lemma, we have $n = n_1$ whenever

$$S_{p_n}(R) \simeq S_{p_{n_1}}(R_1).$$

Lemma 6. (1) If $X = \begin{pmatrix} a & b \\ c & d \end{pmatrix} \in SL_2(R)$, and $a-1 \in J(R)$, then $X = I$.

(2) If $X = \begin{pmatrix} a & b \\ c & d \end{pmatrix} \in SL_2(R)$, $X^2 = -I$ and $c \in R^*$, then

$$\begin{pmatrix} 1 & -c^{-1}a \\ & c^{-1} \end{pmatrix} X \begin{pmatrix} 1 & -c^{-1}a \\ & c^{-1} \end{pmatrix}^{-1} = \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix}.$$

If $X^2 = -I$, then

$$\begin{pmatrix} 1 & -c^{-1}a \\ & c^{-1} \end{pmatrix} X \begin{pmatrix} 1 & -c^{-1}a \\ & c^{-1} \end{pmatrix}^{-1} = \begin{pmatrix} 0 & -1 \\ 1 & 1 \end{pmatrix}.$$

(3) If $X \in S_{p_n}(R)$, $X^2 = I$ and $\lambda_0 X = T_1$ for all $t \in T$, then there exists $P \in SL_n(R)$ such that

$$PXP^{-1} = T_1, \lambda_t P = I, \forall t \in T.$$

Proof the Proof of (3) can be found in [5]. (1) and (2) can be proved by calculation.

For convenience, we denote

$$\Lambda_P X = PXP^{-1}, \text{ for } P \in GL_n(R).$$

Besides, Let, $S_{0,1}$ be the set in $S_{p_n}(R)$ (or in $S_{p_{n_1}}(R_1)$), whose entries just consist of 0, 1 or -1.

Lemma 7. Suppose that $\Lambda: SL_2(R) \rightarrow SL_2(R_1)$ is an isomorphism.

(1) If $\Lambda \begin{pmatrix} 1 & 1 \\ 0 & 1 \end{pmatrix} = \begin{pmatrix} 1 & 1 \\ & 1 \end{pmatrix}$, $\Lambda \begin{pmatrix} 1 & \\ 1 & 1 \end{pmatrix} = \begin{pmatrix} 1 & \\ 1 & 1 \end{pmatrix}$,

then there exists a ring isomorphism $\sigma: R \rightarrow R_1$ such that

$$\Lambda X = X^\sigma, \forall X \in SL_2(R);$$

(2) If $\Lambda \begin{pmatrix} 1 & 1 \\ & 1 \end{pmatrix} = \begin{pmatrix} 1 & 1 \\ & 1 \end{pmatrix}$ and $\lambda_{s_t}(\Lambda X) = \lambda_{s_t} X$ for all $t \in T$ and $X \in S_{0,1}$, then

there exist an isomorphism $\sigma: R \rightarrow R_1$ and $P = \begin{pmatrix} 1 & a \\ & 1 \end{pmatrix} \in SL_2(R_1)$, $\lambda_{s_t} P = I$, $\forall t \in T$

such that

$$\Lambda_P \Lambda X = X^\sigma, \forall X \in SL_2(R).$$

Proof As for the proof of (1), see [6]. We prove (2) as follows. Since $-I$ is in the center of $SL_2(R)$, there is $x \in R^*$ such that $\Lambda(-I) = xI$, $x^2 = 1$. But $-I \in S_{0,1}$. So $\lambda_{s_t} x = -1$ for all $t \in T$. Therefore $x = -1$ by $x^2 - 1 = 0$ and $2 \in R_1^*$.

Let $\Lambda \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix} = \begin{pmatrix} x & y \\ z & u \end{pmatrix}$. We have $\begin{pmatrix} x & y \\ z & u \end{pmatrix}^2 = -I$. So $\lambda_{s_t} z = 1$ for all $t \in T$ i. e.

$z \in R^*$. Therefore we can take $P = \begin{pmatrix} 1 & -z^{-1}x \\ & z^{-1} \end{pmatrix}$ such that

$$\Lambda_P \Lambda \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix} = \begin{pmatrix} & -1 \\ 1 & \end{pmatrix}$$

by lemma 6. $A_p A \begin{pmatrix} 1 & 1 \\ & 1 \end{pmatrix} = \begin{pmatrix} 1 & z \\ & 1 \end{pmatrix}$ by calculation. Clearly

$$\left(\begin{pmatrix} & -1 \\ 1 & \end{pmatrix} \begin{pmatrix} 1 & 1 \\ & 1 \end{pmatrix} \right)^3 = -I.$$

So we have

$$\left(\begin{pmatrix} & -1 \\ 1 & \end{pmatrix} \begin{pmatrix} 1 & Z \\ & 1 \end{pmatrix} \right)^3 = -I.$$

Hence $z=1$, i. e.

$$A_p A \left(\begin{pmatrix} 1 & 1 \\ & 1 \end{pmatrix} \right) = \begin{pmatrix} 1 & 1 \\ & 1 \end{pmatrix}.$$

We also have

$$A_p A \begin{pmatrix} 1 & 0 \\ 1 & 1 \end{pmatrix} = \begin{pmatrix} 1 & 0 \\ 1 & 1 \end{pmatrix} \quad \text{by} \quad \begin{pmatrix} 1 & \\ 1 & 1 \end{pmatrix} = \begin{pmatrix} & -1 \\ 1 & \end{pmatrix} \begin{pmatrix} 1 & 1 \\ & 1 \end{pmatrix}^{-1} \begin{pmatrix} & -1 \\ 1 & \end{pmatrix}^{-1}.$$

Then (2) follows from (1) in this lemma.

Lemma 3. Suppose $AT_i = T_i$ for some $i (1 \leq i \leq \nu)$.

(1) The centralizer of T_i in $S_{p_n}(R)$ is

$$C_{T_i} = \left\{ \begin{pmatrix} A_1 & 0 & A_2 & B_1 & 0 & B_2 \\ 0 & a & 0 & 0 & b & 0 \\ A_3 & 0 & A_4 & B_3 & 0 & B_4 \\ C_1 & 0 & C_2 & D_1 & 0 & D_2 \\ 0 & c & 0 & 0 & d & 0 \\ C_3 & 0 & C_4 & D_3 & 0 & D_4 \end{pmatrix}^{(i)} \left| \begin{pmatrix} a & b \\ c & d \end{pmatrix} \in SL_2(R), \right. \right. \\ \left. \left. \begin{pmatrix} A_1 & A_2 & B_1 & B_2 \\ A_3 & A_4 & B_3 & B_4 \\ C_1 & C_2 & D_1 & D_2 \\ C_3 & C_4 & D_3 & D_4 \end{pmatrix} \in S_{p_{n-2}}(R) \right\} \right.$$

(2) Suppose $\lambda_{s_t}(AX) = \lambda_{s_t}X$, $\forall t \in T$, $X \in S_{0,1}$ and

$$a_i = \left\{ \begin{pmatrix} I & & & 0 \\ & a & & b \\ & & I & 0 \\ 0 & & & I \\ & c & & d \\ & & 0 & I \end{pmatrix}^{(i)} \left| \begin{pmatrix} a & b \\ c & d \end{pmatrix} \in SL_2(R) \right. \right\} \\ b_i = \left\{ \begin{pmatrix} I & & & 0 \\ & x & & y \\ & & I & 0 \\ 0 & & & I \\ & z & & u \\ & & 0 & I \end{pmatrix}^{(i)} \left| \begin{pmatrix} x & y \\ z & u \end{pmatrix} \in SL_2(R) \right. \right\}.$$

Then

$$\Lambda a_i = b_i (1 \leq i \leq \nu).$$

Proof Since 2 is a unit, by direct calculation we obtain (1). Then we prove (2). It is clear that $Q_{i, \nu+i} \in C_{T_i}$, $Q_{i, \nu+i} T_{i, \nu+i}(1) \in C_{T_i}$, so both $\Lambda Q_{i, \nu+i}$ and $\Lambda(Q_{i, \nu+i} T_{i, \nu+i}(1))$ are the elements of $C_{\Lambda T_i} = C_{T_i}$. Hence, by (1), we have

$$\begin{aligned} \Lambda Q_{i, \nu+i} &= \begin{pmatrix} E_1 & 0 & E_2 & F_1 & 0 & F_2 \\ 0 & e_1 & 0 & 0 & f_1 & 0 \\ E_3 & 0 & E_4 & F_3 & 0 & F_4 \\ G_1 & 0 & G_2 & H_1 & 0 & H_2 \\ 0 & g_1 & 0 & 0 & h_1 & 0 \\ G_3 & 0 & G_4 & H_3 & 0 & H_4 \end{pmatrix}, \\ \Lambda Q_{i, \nu+i} T_{i, \nu+i}(1) &= \begin{pmatrix} E_5 & 0 & E_6 & F_5 & 0 & F_6 \\ 0 & e_2 & 0 & 0 & f_2 & 0 \\ E_7 & 0 & E_8 & F_7 & 0 & F_8 \\ G_5 & 0 & G_6 & H_5 & 0 & H_6 \\ 0 & g_2 & 0 & 0 & h_2 & 0 \\ G_7 & 0 & G_8 & H_7 & 0 & H_8 \end{pmatrix}, \end{aligned}$$

where $\lambda_{s_i} g_k = 1$, $\lambda_{s_i} e_k = 0$ for all $t \in T$, $k = 1, 2$. Since $Q_{i, \nu+i}^2 = T_i(Q_{i, \nu+i} T_{i, \nu+i}(1))^3 = T_i$, we have

$$\begin{pmatrix} e_1 & g_1 \\ f_1 & h_1 \end{pmatrix}^2 = -I, \quad \begin{pmatrix} e_2 & f_2 \\ g_2 & h_2 \end{pmatrix}^2 = -I.$$

So, by lemma 6, there are matrices

$$P_k = \begin{pmatrix} & 0 & & \\ I & & e_k & \\ & & 0 & \\ & & & g_k I \end{pmatrix}, \quad k = 1, 2,$$

where $P_k \in GS_{2n}(R_1)$, $\lambda_{s_i} P_k = I$, $\forall t \in T$, such that

$$\begin{aligned} \Lambda Q_{i, \nu+i} &= P_1 \begin{pmatrix} E_1 & 0 & E_2 & g_1 F_1 & 0 & g_1 F_2 \\ 0 & 0 & 0 & 0 & -1 & 0 \\ E_3 & 0 & E_4 & g_1 F_3 & 0 & g_1 F_4 \\ g_1^{-1} G_1 & 0 & g_1^{-1} G_2 & H_1 & 0 & H_2 \\ 0 & 1 & 0 & 0 & 0 & 0 \\ g_1^{-1} G_3 & 0 & g_1^{-1} G_4 & H_3 & 0 & H_4 \end{pmatrix} P_1^{-1}, \\ \Lambda Q_{i, \nu+i} T_{i, \nu+i}(1) &= P_2 \begin{pmatrix} E_5 & 0 & E_6 & g_2 F_5 & 0 & g_2 F_6 \\ 0 & 0 & 0 & 0 & -1 & 0 \\ E_7 & 0 & E_8 & g_2 F_7 & 0 & g_2 F_8 \\ g_2^{-1} G_5 & 0 & g_2^{-1} G_6 & H_5 & 0 & H_6 \\ 0 & 1 & 0 & 0 & 1 & 0 \\ g_2^{-1} G_7 & 0 & g_2^{-1} G_8 & H_7 & 0 & H_8 \end{pmatrix} P_2^{-1}. \end{aligned}$$

Use C to denote the contralizer of $Q_{i,v+i}$ and $Q_{i,v+i}, T_{i,v+i}(1)$ in C_T . It is easy to see that

$$C(R) = \left\{ \begin{pmatrix} A_1 & 0 & A_2 & B_1 & 0 & B_2 \\ 0 & a & 0 & 0 & 0 & 0 \\ A_3 & 0 & A_4 & B_3 & 0 & B_4 \\ C_1 & 0 & C_2 & D_1 & 0 & D_2 \\ 0 & 0 & 0 & 0 & a & 0 \\ C_3 & 0 & C_4 & D_3 & 0 & D_4 \end{pmatrix} \left| \begin{pmatrix} A_1 & A_2 & B_1 & B_2 \\ A_3 & A_4 & B_3 & B_4 \\ C_1 & C_2 & D_1 & D_2 \\ C_3 & C_4 & D_3 & D_4 \end{pmatrix} \in S_{p_{n-2}}(R), a^2=1 \right. \right\}.$$

Suppose

$$\pi_i(R) = \left\{ \begin{pmatrix} A_1 & 0 & A_2 & B_1 & 0 & B_2 \\ 0 & 1 & 0 & 0 & 0 & 0 \\ A_3 & 0 & A_4 & B_3 & 0 & B_4 \\ C_1 & 0 & C_2 & D_1 & 0 & D_2 \\ 0 & 0 & 0 & 0 & 1 & 0 \\ C_3 & 0 & C_4 & D_3 & 0 & D_4 \end{pmatrix} \left| \begin{pmatrix} A_1 & A_2 & B_1 & B_2 \\ A_3 & A_4 & B_3 & B_4 \\ C_1 & C_2 & D_1 & D_2 \\ C_3 & C_4 & D_3 & D_4 \end{pmatrix} \in S_{p_{n-2}}(R) \right. \right\}.$$

Then $\pi_i(R) \subseteq C(R)$. So $\Lambda\pi_i(R) \subseteq \Lambda C(R)$ and $\Lambda C(R)$ are the centralizer of $\Lambda Q_{i,v+1}$ and $\Lambda(Q_{i,v+1}, T_{i,v+1}(1))$ in $C_{\Lambda T_i}$.

Let

$$X = \begin{pmatrix} X_1 & 0 & X_2 & Y_1 & 0 & Y_2 \\ 0 & x & 0 & 0 & y & 0 \\ X_3 & 0 & X_4 & Y_3 & 0 & Y_4 \\ Z_1 & 0 & Z_2 & U_1 & 0 & U_2 \\ 0 & z & 0 & 0 & u & 0 \\ Z_3 & 0 & Z_4 & U_3 & 0 & U_4 \end{pmatrix}$$

be any element in $\Lambda C(R)$. Then $\begin{pmatrix} x & y \\ z & u \end{pmatrix} \in SL_2(R_1)$ which commute with the following matrices

$$C_1 = \begin{pmatrix} 1 & e_1 \\ & g_1 \end{pmatrix} \begin{pmatrix} & -1 \\ 1 & \end{pmatrix} \begin{pmatrix} 1 & e_1 \\ & g_1 \end{pmatrix}^{-1}, \quad C_2 = \begin{pmatrix} 1 & e_2 \\ & g_2 \end{pmatrix} \begin{pmatrix} 0 & -1 \\ 1 & 1 \end{pmatrix} \begin{pmatrix} 1 & e_2 \\ & g_2 \end{pmatrix}^{-1}.$$

So we have

$$\begin{pmatrix} 1 & e_1 \\ & g_1 \end{pmatrix}^{-1} \begin{pmatrix} x & y \\ z & u \end{pmatrix} \begin{pmatrix} 1 & e_1 \\ & g_1 \end{pmatrix} = \begin{pmatrix} x_1 & y_1 \\ -y_1 & x_1 \end{pmatrix}$$

and

$$\begin{pmatrix} 1 & e_2 \\ & g_2 \end{pmatrix}^{-1} \begin{pmatrix} x & y \\ z & u \end{pmatrix} \begin{pmatrix} 1 & e_2 \\ & g_2 \end{pmatrix} = \begin{pmatrix} x_2 & y_2 \\ -y_2 & x_2 - y_2 \end{pmatrix},$$

with $x_i, y_i \in R_1$. Hence $y_1 = y_2 = 0, x_1 = x_2$ by $e_k \in J(R_1)$. Therefore we have $x = u, y = z = 0, \Lambda C(R) \subseteq C(R_1)$, and $\Lambda\pi_i(R) \subseteq C(R_1)$. It is clear that $\pi_i^2(R) \simeq S_{p_{n-2}}^2(R)$ by $\pi_i(R) \simeq S_{p_{n-2}}(R)$. So since $2 \in R^*$ and $S_{p_n}(R)$ is generated by symplectic trasvection,

we have $S_{p_{n-2}}^2(R) = S_{p_{n-2}}(R)$, $\pi_i^2(R) = \pi_i(R)$. Thus

$$\Lambda\pi_i(R) = \Lambda\pi_i^2(R) = (\Lambda\pi_i(R))^2 \subseteq O^2(R_1) = \pi_i(R_1).$$

The condition $\lambda_{S_t}(\Lambda X) = \lambda_{S_t}X$, $\forall t \in T$, $X \in S_{0,1}$ implies $\lambda_t(\Lambda^{-1}X) = \lambda_t X$, $\forall t \in T$ and $X \in S_{0,1}$. So we have $\Lambda^{-1}\pi_i(R_1) \subseteq \pi_i(R)$ by the same reason. Therefore

$$\Lambda\pi_i(R) = \pi_i(R_1).$$

Let C_{π_i} denote the centralizer of π_i in C_T . We have $\mathbf{a}_i \subseteq C_{\pi_i(R)}$. So

$$\Lambda\mathbf{a}_i \subseteq \Lambda C_{\pi_i(R)} = C_{\Lambda\pi_i(R)} = C_{\pi_i(R_1)}.$$

It is easy to see that

$$C_{\pi_i(R_1)} = \left\{ \begin{pmatrix} xI & & 0 & \\ & x_1 & & y_1 \\ & & xI & 0 \\ 0 & & & xI \\ & z_1 & & u_1 \\ & & 0 & xI \end{pmatrix} \mid x^2=1, \begin{pmatrix} x_1 & y_1 \\ z_1 & u_1 \end{pmatrix} \in SL_2(R_1) \right\}.$$

Recall that $\mathbf{a}_i \simeq SL_2(R)$, so $\mathbf{a}_i^2 = \mathbf{a}_i$. Hence

$$\Lambda\mathbf{a}_i = \Lambda\mathbf{a}_i^2 = (\Lambda\mathbf{a}_i)^2 \subseteq O_{\pi_i(R_1)}^2 \subseteq \mathbf{b}_i.$$

Similarly, we have $\Lambda^{-1}\mathbf{b}_i \subseteq \mathbf{a}_i$, that is, $\Lambda\mathbf{a}_i = \mathbf{b}_i$.

Lemma 9. Suppose that $\lambda_{S_t}(\Lambda X) = \lambda_{S_t}X$ for all $t \in T$ and $X \in S_{0,1}$, then there exists $P \in S_{p_n}(R_1)$ such that

$$\Lambda_p \Lambda T_i = T_i, \quad i=1, \dots, \nu.$$

Proof Clearly, $(\Lambda T_i)^2 = I$ and $\lambda_{S_t}(\Lambda T_i) = \lambda_{S_t}T_i$, $i=1, \dots, \nu$. By lemma 6, we have $Q \in S_{p_n}(R_1)$ such that $\Lambda_Q \Lambda T_1 = T_1$, $\lambda_{S_t}Q = I$, $\forall t \in T$. So we also have

$$\lambda_{S_t}(\Lambda_Q \Lambda X) = \lambda_{S_t}X$$

for all $t \in T$, $X \in S_{0,1}$. Now assume that there exists P_1 in $S_{p_n}(R_1)$ such that

$$\Lambda_{p_1} \Lambda T_i = T_i, \quad i=1, \dots, k-1, \quad k \geq 2,$$

and $\lambda_{S_t}(\Lambda_{p_1} \Lambda X) = \lambda_{S_t}X$ for all $t \in T$, $X \in S_{0,1}$. Consider T_k . Since

$$T_k T_i = T_i T_k, \quad i=1, \dots, k-1,$$

by Lemma 8, we have

$$\Lambda_{p_1} \Lambda T_k = \begin{pmatrix} a_1 & & & b_1 & & \\ & \ddots & & & \ddots & \\ & & a_{k-1} & & & b_{k-1} \\ & & & A & & B \\ c_1 & & & & d_1 & \\ & \ddots & & & & \ddots \\ & & c_{k-1} & & & d_{k-1} \\ & & & C & & D \end{pmatrix},$$

where $\lambda_{S_t}a_i = \lambda_{S_t}d_i = 1$, $\lambda_{S_t}b_i = \lambda_{S_t}c_i = 0$ for all $t \in T$ and $i=1, \dots, k-1$. But $(\Lambda_{p_1} \Lambda T_k)^2 = I$, so we have $a_i = d_i = 1$, $b_i = c_i$ by lemma 6.

* For any group G , we mean that $G^2 = \langle gh | g, h \in G \rangle$.

Hence

$$\Lambda_{p_1} \Lambda T_k = \begin{pmatrix} I^{(k-1)} & O^{(k-1)} & & \\ & A & B & \\ O^{(k-1)} & & I^{(k-1)} & \\ & C & & D \end{pmatrix},$$

where

$$\begin{pmatrix} A & B \\ C & D \end{pmatrix} \in S_{p_{n-2k+2}}(R_1), \quad \begin{pmatrix} A & B \\ C & D \end{pmatrix}^2 = I$$

and

$$\lambda_{s_t} \begin{pmatrix} A & B \\ C & D \end{pmatrix} = \begin{pmatrix} -1 & & & \\ & I & & \\ & & -1 & \\ & & & I \end{pmatrix}$$

for all $t \in T$. Therefore, applying Lemma 6 again, we have

$$Q_1 = \begin{pmatrix} Q_{11} & Q_{12} \\ Q_{21} & Q_{22} \end{pmatrix} \in S_{p_{n-2k+2}}(R_1)$$

such that

$$Q_1 \begin{pmatrix} A & B \\ C & D \end{pmatrix} Q_1^{-1} = \begin{pmatrix} -1 & & & \\ & I & & \\ & & -1 & \\ & & & I \end{pmatrix}.$$

Put

$$P_2 = \begin{pmatrix} I & & 0 & \\ & Q_{11} & & Q_{12} \\ 0 & & I & \\ & Q_{21} & & Q_{22} \end{pmatrix}.$$

Then $P_2 \in S_{p_n}(R_1)$ and $\Lambda_{p_1} \Lambda_{p_1} \Lambda T_i = T_i$, $i=1, \dots, k$. Our lemma therefore follows from the above discussion.

Lemma 10. Suppose $\Lambda T_i = T_i$, $i=1, \dots, \nu$, $\lambda_{s_t}(\Lambda X) = \lambda_{s_t} X$ for all $t \in T$ and $X \in S_{0,1}$. Then there exists $P \in GS_{p_n}(R_1)$ such that

$$\Lambda_P \Lambda Y = Y,$$

where Y may be any one of the following symplectic matrices

$$T_i, T_{i,\nu+i}(1), T_{\nu+i,i}(1), J_{1j}, J_{j1}, i=1, \dots, \nu, j=2, \dots, \nu.$$

Proof It is clear that $J_{12} T_i = T_i J_{12}$ for $i > 2$ and $T_{1,\nu+1}(1) \in \mathfrak{a}_1$. So by Lemma 8, we have

$$\Lambda J_{12} = \begin{pmatrix} x_1 & x_{12} & & y_1 & y_{12} & & \\ x_{21} & x_2 & & y_{21} & y_2 & & \\ & \ddots & & & \ddots & & \\ & & x_\nu & & & y_\nu & \\ z_1 & z_{12} & & u_1 & u_{12} & & \\ z_{21} & z_2 & & u_{21} & u_2 & & \\ & \ddots & & & \ddots & & \\ & & z_\nu & & & u_\nu & \end{pmatrix}, \quad \Lambda T_{1,\nu+1}(1) = \begin{pmatrix} a & b & & \\ & I & & 0 \\ c & & d & \\ & 0 & & I \end{pmatrix}.$$

By $(\Lambda J_{12})^2 = I$ and (1) in Lemma 6, we have $x_i = u_i = 1$, $z_i = y_i = 0$ for

$$i > 2, y_1 = y_2 = z_1 = z_2 = 0$$

and

$$\begin{pmatrix} u_1 & u_{12} \\ u_{21} & u_2 \end{pmatrix}' = \begin{pmatrix} x_1 & x_{12} \\ x_{21} & x_2 \end{pmatrix}, \quad y_{21} = -z_{12}, \quad y_{21} = -z_{12},$$

that is

$$\Delta J_{12} = \begin{pmatrix} x_1 & x_{12} & 0 & y_{12} \\ x_{21} & x_2 & -y_{21} & 0 \\ & & I & 0 \\ 0 & z_{12} & x_1 & x_{21} \\ -z_{21} & 0 & x_{12} & x_2 \\ & & 0 & I \end{pmatrix}.$$

By using $J_{12} \in S_{0,1}$, it is easy to see that $x_1+1, x_{12}+1, x_2, y_{12}, z_{12}$ are all in $J(R_1)$. In particular $x_{12}, x_1 \in R_1^*$.

Obviously, $T_{1,\nu+1}(1)J_{12} = J_{12}T_{1,\nu+1}(1)$. So

$$\Delta T_{1,\nu+1}(1)\Delta J_{12} = \Delta J_{12}\Delta T_{1,\nu+1}(1), \quad (1)$$

therefore, we have

$$\begin{cases} a = 1 - z_{12}x_{12}^{-1}b, \\ c = -z_{12}^2x_{12}^{-2}b, \\ d = 1 + z_{12}x_{12}^{-1}b, \end{cases} \quad (2)$$

where $\lambda_{s_i}b = 1, \forall t \in T$. Hence $b \in R_1^*$. Put

$$P_1 = \begin{pmatrix} I & \\ & bI \end{pmatrix} \begin{pmatrix} I & \\ -z_{12}x_{12}^{-1} & \\ & 0 & I \end{pmatrix} = \begin{pmatrix} I & \\ -bz_{12}x_{12}^{-1} & \\ & 0 & b & I \end{pmatrix} \in GS_{p_n}(R_1).$$

Clearly $\lambda_{s_i}P_1 = I, \forall t \in T$. So, using the equalities (2), we have

$$\Delta_{p_1}\Delta T_{1,\nu+1}(1) = T_{1,\nu+1}(1), \quad \Delta_{p_1}\Delta T_i = T_i, \quad i=1, \dots, \nu.$$

Furthermore, we have

$$\Delta_{p_1}\Delta J_{12} = \begin{pmatrix} -1 & x_{12} & 0 & b^{-1}y_{12} \\ & 1 & -b^{-1}y_{12} & 0 \\ & & I & 0 \\ & & -1 & \\ & & x_{12} & 1 \\ & & & I \end{pmatrix}$$

by equality (1). Let

$$P_2 = T_{2,\nu+2}(b^{-1}y_{12}x_{12}^{-1}) \begin{pmatrix} 1 & & & \\ & -x_{12} & & \\ & & I & \\ & & & 1 \\ & & & & -x_{12}^{-1} \\ & & & & & I \end{pmatrix}.$$

Then $P_2 \in S_{p_n}(R_1)$, $\lambda_{s_i}P_2 = I$ for all $t \in T$. It is easy to see that

$$\Delta_{p_2}\Delta_{p_1}\Delta T_i = T_i, \quad i=1, \dots, \nu,$$

$$A_{p_2} A_{p_1} A T_{1, \nu+1}(1) = T_{1, \nu+1}(1),$$

$$A_{p_2} A_{p_1} A J_{12} = J_{12},$$

and $\lambda_{S_t}(A_{p_2} A_{p_1} A X) = \lambda_{S_t} X$ for all $t \in T$ and $X \in S_{0,1}$. By lemma 8, $A_{p_2} A_{p_1} A \alpha_1 = b_1$. So there is a $P_3 = T_{1, \nu+1}(x)$, $\lambda_{S_t} x = 0$ for all $t \in T$ such that

$$A_{p_2} A_{p_1} A T_{1, \nu+1}(1) = T_{1, \nu+1}(1), \quad A_{p_2} A_{p_1} A T_{\nu+1, 1}(1) = T_{\nu+1, 1}(1)$$

and $A_{p_2} A_{p_1} A$ still preserves J_{12} , $T_i (i=1, \dots, \nu)$.

Using the equalities $J_{21} T_i = T_i J_{21}$, $i > 2$, $J_{21} T_{\nu+1, 1}(1) = T_{\nu+1, 1}(1) J_{21}$, $J_{21}^2 = I$, $\lambda_{S_t} A J_{21} = \lambda_{S_t} J_{21}$, $\forall t \in T$ and $T_{\nu+1, 1}(1) \in \mathfrak{a}$, we know that there is matrix

$$P_4 = \begin{pmatrix} I & -y_{12} x_{21}^{-1} & & \\ & 0 & & \\ & & c^{-1} I & \end{pmatrix}, \quad \lambda_{S_t} c = 1, \quad \lambda_{S_t} x_{21} = -1, \quad \lambda_{S_t} y_{12} = 0, \quad \forall t \in T$$

such that

$$A_{p_4 p_3 p_2 p_1} A J_{21} = \begin{pmatrix} -1 & & & & \\ y & 1 & & & \\ & & I & & \\ & z & & -1 & y \\ -z & & & & 1 \\ & & 0 & & I \end{pmatrix},$$

where $\lambda_{S_t} y = -1$, $\lambda_{S_t} z = 0$ for all $t \in T$. Let $P_5 = T_{\nu+2, 2}(y^{-1}z)$. we have

$$A_{p_5 p_4 p_3 p_2 p_1} A J_{21} = \begin{pmatrix} -1 & & & & \\ y & 1 & & & \\ & & I & & \\ & & & -1 & y \\ & & & & 1 \\ & & & & I \end{pmatrix}$$

and $A_{p_5 p_4 p_3 p_2 p_1} A$ still preserves T_i , J_{12} , $T_{1, \nu+1}(1)$, $T_{\nu+1, 1}(1)$, $i=1, \dots, \nu$, and

$\lambda_{S_t} A_{p_5 p_4 p_3 p_2 p_1} A X = \lambda_{S_t} X$ for all $t \in T$, $X \in S_{0,1}$.

But $(T_1 J_{12} T_1 J_{21})^3 = T_1 T_2$, so $(T_1 J_{12} T_1 A_{p_5 p_4 p_3 p_2 p_1} A J_{21})^3 = T_1 T_2$, from which we know that $y = -1$, i. e.

$$A_{p_5} A J_{21} = J_{21}, \quad p_6 = p_5 p_4 p_3 p_2 p_1.$$

Applying

$$F_{12} = J_{12} T_1 J_{21} T_1 J_{12} T_1, \quad T_{2, \nu+2}(1) = F_{12} T_{1, \nu+1}(1) F_{12}^{-1},$$

$$T_{\nu+2, 2}(1) = F_{12}^{-1} T_{\nu+1, 1}(1) F_{12},$$

we have

$$A_{p_6} A T_{2, \nu+2}(1) = T_{2, \nu+2}(1), \quad A_{p_6} A T_{\nu+2, 2}(1) = T_{\nu+2, 2}(1).$$

For any integers $k (\geq 3)$, we assume that there is

$$Q \in S_{p_n}(R_1), \quad \lambda_{S_t} Q = I, \quad \forall t \in T$$

such that $A_Q A Y = Y$, where Y may be any one of T_i , J_{1i} , J_{j1} , $T_{1, \nu+1}(1)$, $T_{\nu+1, 1}(1)$, $T_{j, \nu+j}(1)$, $T_{\nu+j, j}(1)$, $j=2, \dots, k-1$.

Using the argument as above, we can see that $A_Q A$ preserves J_{1k} .

Choose another matrix $Q_1 \in GS_{p_n}(R_1)$, $\lambda_{S_t} Q_1 = I$ for all $t \in T$. Then $A_{Q_1} A$ pre-

serves $J_{k1} T_{k, \nu+k} (1)$ and $T_{\nu+k, k} (1)$ besides the above matrices.

Our lemma therefore follows from the above discussion.

§ 2. The proof of our main theorem

Recall that the isomorphism A of $S_{p_n}(R)$ onto $S_{p_n}(R_1)$ induces a set of isomorphisms

$$\Lambda_{S_t}: S_{p_n}(R/M_t) \rightarrow S_{p_n}(R_1/N_{S_t}), \quad \forall t \in T$$

with $\Lambda_{S_t}(\lambda_t X) = \lambda_{S_t}(\Lambda X)$ for all X in $S_{p_n}(R)$, therefore, according to the result on symplectic groups over fields, $n = n_1$ and for each $t \in T$ there is $P_{S_t} \in GS_{p_n}(R_1)$ such that

$$\Lambda_{S_t}(\lambda_t X) = P_{S_t}(\lambda_t X)^{\sigma_{S_t}} P_{S_t}^{-1},$$

that is,

$$\lambda_{S_t}(\Lambda X) = P_{S_t}(\lambda_t X)^{\sigma_{S_t}} P_{S_t}^{-1}, \quad \forall t \in T, X \in S_{p_n}(R),$$

where σ_{S_t} is the isomorphism of R/M_t onto R_1/N_{S_t} .

Since R_1 is a Φ -surjective ring, there exists $P_1 \in S_{p_n}(R_1)$ such that $\lambda_{S_t} P_1 = P_{S_t}$ for all $t \in T$. Hence

$$\lambda_{S_t}(\Lambda_{p_1^{-1}} \Lambda X) = (\lambda_t X)^{\sigma_{S_t}}, \quad \forall t \in T.$$

If $X \in S_{0,1}$, it is clear that $(\lambda_t X)^{\sigma_{S_t}} = \lambda_{S_t} X$. So we have

$$\lambda_{S_t}(\Lambda_{p_1^{-1}} \Lambda X) = \lambda_{S_t} X, \quad \forall t \in T \text{ and } X \in S_{0,1}.$$

Now $\Lambda_{p_1^{-1}} \Lambda$ is also an isomorphism of $S_{p_n}(R)$ onto $S_{p_n}(R_1)$. By lemma 9 and lemma 10, there is $P_2 \in GS_{p_n}(R)$ such that $\Lambda_{p_1^{-1}} \Lambda Y = Y$, $P = P_1 P_2$, where Y may be any one of the following matrices.

$$T_i, T_{i, \nu+i}(1), T_{\nu+i, i}(1), J_{1j}, J_{j1}, i=1, \dots, \nu, j=2, \dots, \nu.$$

By Lemma 8, we have $\Lambda_{p_1^{-1}} \Lambda a_i = b_i$. But $a_i \simeq SL_2(R)$, $b_i \simeq SL_2(R_1)$. So, there is an isomorphism σ of R onto R_1 such that $\Lambda_{p_1^{-1}} \Lambda X = X^\sigma$, $\forall X \in a_i$.

Using lemma, and the fact that $\begin{pmatrix} -I & \\ & I \end{pmatrix}$ can be expressed by

$$T_{i, \nu+i}(1), T_{\nu+i, i}(1), i=1, \dots, \nu,$$

we can show

$$\Lambda_{p_1^{-1}} \Lambda X = X^\sigma, \quad \forall X \in S_{p_n}(R),$$

i. e.

$$\Lambda X = P X^\sigma P^{-1}, \quad \forall X \in S_{p_n}(R),$$

where $P \in GS_{p_n}(R_1)$.

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