

ON BOUNDEDNESS OF HARDY-LITTLEWOOD MAXIMAL FUNCTION OPERATOR ON RIEMANNIAN MANIFOLDS

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Abstract

The authors construct a complete Riemannian manifold such that its Hardy-Littlewood maximal function operator is unbounded in L^p for some $p > 1$.

§1. Introduction

For a complete Riemannian manifold N , its Hardy-Littlewood maximal function operator is defined by

$$M(f)(x) = \sup_{r>0} |B(x, r)|^{-1} \int_{B(x, r)} |f(y)| dy,$$

where $B(x, r)$ is the geodesic ball with center x and radius r . As known, Hardy-Littlewood maximal operator is very important in Harmonic Analysis. For $N = \mathbb{R}^n$, a classical result shows its L^p and weak type $(1, 1)$ boundedness, $1 < p \leq \infty$ (see [6]). For positively curved manifolds, Varapoulos proved its L^p and weak type $(1, 1)$ boundedness^[9,1], $1 < p \leq \infty$; and the first named author^[1] proved its BMO-boundedness. For non-compact symmetric spaces, Clerc and Stein^[4] proved its L^p -boundedness for $1 < p \leq \infty$; and Strömberg proved its weak type $(1, 1)$ boundedness. For general negatively curved manifolds, Lohoué proved its L^p -boundedness for $p > p_0$ where $p_0(> 1)$ depends on the bounds of the sectional curvature of N . A basic problem naturally arise: Is M L^p -bounded for all $p > 1$? In this paper, we shall construct a simply connected complete Riemannian manifold (based on [2]) with sectional curvature $K_N \leq 0$, for which M is not L^p -bounded for all $1 < p < 2$. At the same time, the example also shows that the main results of "On the sectional curvature of a Riemannian manifold" (Chinese Annals of Mathematics (Ser. B), Vol. 11, No. 1, 1990) are wrong. For simplicity, we only consider 2-dimensional case, i.e., $\dim(N) = 2$.

In the whole paper, C denotes an absolute positive number and $C_{a,b,\dots}$ a positive number depending only on a, b, \dots , $f(r) = \overline{O}(g(r))$ means that $C^{-1} \leq |f(r)/g(r)| \leq C$.

§2. Some Notes on Poincare Plane

Let $\mathbb{M}_{-1} = (D, (1-r^2)^{-2}(dr^2 + r^2 d\theta^2))$ denote the Poincare plane, where $D = \{z : |z| < 1\} \subset \mathbb{R}^2$, $B_{-1}(z, r)$ denote the geodesic ball in \mathbb{M}_{-1} with center z and radius r , $B_0(z, r)$ denote the Euclidean ball in \mathbb{R}^2 with center z and radius r , $\rho(\cdot, \cdot)$ denote the geodesic distance function on \mathbb{M}_{-1} , $R_0 = \text{th } 1$, $0 < R < 1$. We have (see the figure)

Manuscript received August 1, 1990. Revised October 7, 1991.

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Lemma 2.1. $B_{-1}(R, \rho(O, R)) = B_0(O_R, O_R)$ where $O_R = R/(1 + R^2)$,

$$B_{-1}(R, \rho(O, R) + 1) = B_0(O'_R, O'_R + R_0)$$

where $O'_R = 4e^2(e^2 + 1)^{-2}R/(1 + 2R \operatorname{th} 1 + R^2)$.

Proof. It is easy to see that the Riemannian structure of \mathbb{M}_{-1} is preserved by the maps

$$z \rightarrow (az + b)/(\bar{b}z + \bar{a}) \quad (\forall z \in D, |a|^2 - |b|^2 = 1) \quad (2.1)$$

and all straight lines through the origin are geodesics. So, all geodesic balls with center O are Euclidean balls and the maps (2.1) preserve both the Euclidean and the \mathbb{M}_{-1} -geodesic balls. It is also easy to see that O_R , the center of $B_{-1}(R, \rho(O, R))$ as a Euclidean ball, must be in x -axis because $B_{-1}(R, \rho(O, R))$ is tangent to y -axis at O and the angle between two vectors in the Riemannian structure coincides with the Euclidean angle. Similarly, O'_R , the center of $B_{-1}(R, \rho(O, R) + 1)$ as a Euclidean ball, must be in x -axis. Now, let R_* and R'_* be shown in the figure. We shall compute R'_* and O'_R only, here. We have

$$\rho(O, R_0) + \rho(O, R) = \rho(R, R'_*).$$

An easy computation by maps (1) shows

$$\rho(z', z'') = \frac{1}{2} \ln \frac{|1 - \bar{z}' z''| + |z' - z''|}{|1 - \bar{z}' z''| - |z' - z''|}$$

and thus $\rho(O, R_0) = 1$. Therefore

$$(1 - R)(1 - RR'_* + R'_* - R) = (1 + R)e^2(1 - RR'_* - R'_* + R),$$

$$R'_* = (\operatorname{th} 1 + 2R + R^2 \operatorname{th} 1)/(1 + 2R \operatorname{th} 1 + R^2),$$

and

$$O'_R = \frac{1}{2}(R_0 + R'_*) = 4e^2(e^2 + 1)^{-2}R/(1 + 2R \operatorname{th} 1 + R^2).$$

Similarly, we have

$$R_* = 2R/(1 + R^2) \quad \text{and} \quad O_R = R/(1 + R^2).$$

Let α_R and α'_R be shown in the figure. Then

Lemma 2.2. $\alpha_R = \arccos \frac{1}{2}(1 + R^2) = \overline{O}((1 - R)^{\frac{1}{2}}) \quad (R \rightarrow 1^-),$

$$\alpha'_R = \arccos(2O'_R \operatorname{th} 1 + \operatorname{th}^2 1 - R^2)/(-2RO'_R) = \overline{O}((1 - R)^{\frac{1}{2}}) \quad (R \rightarrow 1^-).$$

Proof. Here, we only compute α'_R . We have

$$|R \exp(i\alpha'_R) - O'_R| = O'_R + R_0,$$

so

$$\alpha'_R = \arccos(2O'_R \operatorname{th} 1 + \operatorname{th}^2 1 - R^2)/(-2RO'_R).$$

Now

$$\begin{aligned} \arccos x &= \int_x^1 \frac{dx}{\sqrt{1-x^2}} = \overline{O}(1) \int_x^1 \frac{dx}{\sqrt{1-x}} \\ &= \overline{O}(1)(1-x)^{\frac{1}{2}}. \end{aligned}$$

Thus

$$\begin{aligned}
 \alpha'_R &= \overline{O}(1)(2RO'_R + 2O'_R \operatorname{th} 1 + \operatorname{th}^2 1 - R^2)^{\frac{1}{2}} \\
 &= \overline{O}(1)((8e^2 R^2 + 8e^2 R^2 \operatorname{th} 1)/(1 + 2R \operatorname{th} 1 + R^2) + (e^2 - 1)^2 - R^2(e^2 + 1)^2)^{\frac{1}{2}} \\
 &= \overline{O}(1)(8e^4 R(1 + R) - 8e^2 R(1 - R) + ((e^4 + 1)(1 - R^2) - 2e^2(1 + R^2)) \\
 &\quad \cdot (e^2(1 + 2R + R^2) + (1 - 2R + R^2)))^{\frac{1}{2}} \\
 &= \overline{O}(1)(2e^4(4R(1 + R) - (1 + R^2)(1 + 2R + R^2)) - \\
 &\quad - 2e^2(1 + R^2)(1 - R)^2 + \overline{O}_+(1 - R))^{\frac{1}{2}} \\
 &= \overline{O}(1)(O((1 - R)^2) + 2e^4(R^2 + 2R + 1)(1 - R)^2 + \overline{O}_+(1 - R))^{\frac{1}{2}} \\
 &= \overline{O}((1 - R)^{\frac{1}{2}}) \quad (R \rightarrow 1^-),
 \end{aligned}$$

where $h(R) = \overline{O}_+(1 - R)$ ($R \rightarrow 1^-$) means that when $R \rightarrow 1^-$,

$$h(R) > 0 \text{ and } C^{-1} \leq |h(R)/(1 - R)| \leq C.$$

Lemma 2.2 is proved.

Let r_θ and r'_θ be shown in the figure. We have

Lemma 2.3. $r_\theta = (2r/(1 + r^2)) \cos \theta$,

$$r'_\theta = O'_R \cos \theta + ((O'_R \cos \theta)^2 + (2O'_R \operatorname{th} 1 + \operatorname{th}^2 1))^{\frac{1}{2}}.$$

Proof. We only compute r'_θ . We have

$$|r'_\theta e^{i\theta} - O'_R| = O'_R + R_0,$$

$$r'^2_\theta - 2O'_R \cos \theta \cdot r'_\theta - (2O'_R \operatorname{th} 1 + \operatorname{th}^2 1) = 0.$$

Its positive solution is

$$r'_\theta = O'_R \cos \theta + ((O'_R \cos \theta)^2 + (2O'_R \operatorname{th} 1 + \operatorname{th}^2 1))^{\frac{1}{2}}.$$

Now, we have

Lemma 2.4. $|B_{-1}(O, \rho(O, R))| = \pi(1/(1 - R^2) - 1) = \overline{O}(1/(1 - R))$,

$$|B_{-1}(O, \rho(O, R)) \cap B_{-1}(R, \rho(O, R) + 1)| = \overline{O}(1/(1 - R)^{\frac{1}{2}})$$

when $R \rightarrow 1^-$.

Proof. We have

$$\begin{aligned}
 |B_{-1}(O, \rho(O, R))| &= |B_0(O, R)| = \int_{|z| < R} \frac{rdrd\theta}{(1 - r^2)^2} \\
 &= 2\pi \int_0^{R^2} \frac{\frac{1}{2}dt}{(1 - t)^2} = \pi((1 - R^2)^{-1} - 1).
 \end{aligned}$$

And, by Lemma 2.1, we have

$$\begin{aligned}
 &|B_{-1}(O, \rho(O, R)) \cap B_{-1}(R, \rho(O, R) + 1)| \\
 &= |B_0(O, R) \cap B_0(O'_R, O'_R + R_0)| \\
 &= \overline{O}(1) \left(\int_0^{\alpha'_R} \int_0^{R_\epsilon} + \int_{\alpha'_R}^{\frac{\pi}{2}} \int_0^{r'_\theta} + \int_{\frac{\pi}{2}}^\pi \int_0^{r_\theta} \right) \frac{rdrd\theta}{(1 - r^2)^2} \\
 &= \overline{O}(1)(\text{I} + \text{II} + \text{III}).
 \end{aligned}$$

It is easy to see that

$$\begin{aligned} \text{III} &= \overline{O}(1) = o(1/(1-R)^{\frac{1}{2}}) \quad (R \rightarrow 1^-), \\ \text{I} &= \overline{O}(1)\alpha'_R/(1-R^2) = \overline{O}(1/(1-R)^{\frac{1}{2}}) \quad (R \rightarrow 1^-) \end{aligned}$$

by Lemma 2.2. To estimate II, we consider $1-r'_\theta$ first. We have

$$\begin{aligned} 1-r'_\theta &= 1 - O'_R \cos \theta - ((O'_R \cos \theta)^2 + (2O'_R \text{th } 1 + \text{th}^2 1))^{\frac{1}{2}} \\ &= \frac{(1 - O'_R \cos \theta)^2 - (O'_R \cos \theta)^2 - (2O'_R \text{th } 1 + \text{th}^2 1)}{1 - O'_R \cos \theta + ((O'_R \cos \theta)^2 + (2O'_R \text{th } 1 + \text{th}^2 1))^{\frac{1}{2}}} \\ &= \overline{O}(1)(1 - 2O'_R \cos \theta - (2O'_R \text{th } 1 + \text{th}^2 1)) \\ &= \overline{O}(1)((1 - \text{th}^2 1)/2O'_R - \text{th } 1 - \cos \theta) \\ &= \overline{O}(1)((1 - \text{th}^2 1)(1 + 2R \text{th } 1 + R^2)(e^2 + 1)^2/4e^2 R - \text{th } 1 - \cos \theta) \\ &= \overline{O}(1)((1 + R^2)/2R - \cos \theta) \\ &= \overline{O}(1)(1 - (2R \cos \theta/(1 + R^2))^2). \end{aligned}$$

So

$$\begin{aligned} \text{II} &= \int_{\alpha'_R}^{\frac{\pi}{2}} \int_0^{r'_\theta} \frac{r dr d\theta}{(1-r^2)^2} = \frac{1}{2} \int_{\alpha'_R}^{\frac{\pi}{2}} \frac{d\theta}{1-r'^2_\theta} \\ &= \overline{O}(1) \int_{\alpha'_R}^{\frac{\pi}{2}} \frac{d\theta}{1-r'_\theta} = \overline{O}(1) \int_{\alpha'_R}^{\frac{\pi}{2}} \frac{d\theta}{1 - (2O'_R \cos \theta)^2} \\ &= \overline{O}(1)(1 - 4O_R^2)^{-\frac{1}{2}} \left(\frac{\pi}{2} - \arctg((\text{tg } \alpha'_R)/(1 - 4O_R^2)^{\frac{1}{2}}) \right). \end{aligned}$$

Now

$$(1 - 4O_R^2)^{\frac{1}{2}} = (1 - 4(R/(1 + R^2))^2)^{\frac{1}{2}} = \overline{O}(1 - R),$$

$$\begin{aligned} \text{tg } \alpha'_R &= (\cos^{-2} \alpha'_R - 1)^{\frac{1}{2}} = \overline{O}(1)(1 - \cos \alpha'_R)^{\frac{1}{2}} \\ &= \overline{O}(1)\alpha'_R = \overline{O}((1 - R)^{\frac{1}{2}}), \end{aligned}$$

$$\begin{aligned} &\frac{1}{2} \pi - \arctg((\text{tg } \alpha'_R)/(1 - 4O_R^2)^{\frac{1}{2}}) \\ &= \int_0^{\text{tg } \alpha'_R/\sqrt{1-4O_R^2}} \frac{dx}{1+x^2} = \overline{O}\left(\left(\frac{\text{tg } \alpha'_R}{\sqrt{1-4O_R^2}}\right)^{-1}\right) \\ &= \overline{O}(1)((1 - R)^{\frac{1}{2}}). \end{aligned}$$

Therefore

$$\text{II} = \overline{O}(1)((1 - R)^{-\frac{1}{2}}) \quad (R \rightarrow 1^-).$$

§3. Construction of the Counterexample

Let

$$\begin{aligned} D_n &= \{z : |z - z_n| < 1\}, \quad z_n = (n+2)^2, \\ R_n &= \text{th } n, \\ ds_n^2(z) &= f_{R_n}^2(r)(dr^2 + r^2 d\theta) \quad \text{where } z = z_n + re^{i\theta}, \\ f_R(r) &= (1 - (r\chi_R(r))^2)^{-1}, \\ \chi_R(t) &= \tilde{\chi}_R * \varphi_{\epsilon/3}(t) = \int_{-\infty}^{+\infty} \tilde{\chi}_R(u) \varphi_{\epsilon/3}(t-u) du \quad (\epsilon = (1-R)^2), \\ \varphi_r(t) &= r^{-1} \varphi(t/r), \\ \varphi(t) &= \begin{cases} Ce^{-(1-t^2)^{-1}}, & |t| < 1, \\ 0, & |t| \geq 1, \end{cases} \quad C^{-1} = \int_{R^1} e^{-(1-t^2)^{-1}} dt, \\ \tilde{\chi}_R(t) &= \begin{cases} 1, & t \leq R + \frac{1}{3}\epsilon, \\ 0, & t \geq R + \frac{2}{3}\epsilon, \\ \text{linear}, & R + \frac{1}{3}\epsilon \leq t \leq R + \frac{2}{3}\epsilon. \end{cases} \end{aligned}$$

Then, take (compare with [2])

$$\begin{aligned} N &= (R^2, ds^2), \\ ds^2(z) &= \begin{cases} ds_n^2(z), & z \in D_n, \quad n = 1, 2, \dots, \\ dzd\bar{z}, & \text{otherwise.} \end{cases} \end{aligned}$$

We have

Lemma 3.1. *N is a smooth complete Riemannian manifold.*

$$f_{R(r)} \begin{cases} = (1-r^2)^{-1} & \text{for } r \leq R, \\ = 1 & \text{for } r \geq R + \epsilon, \\ \leq (1-r^2)^{-1} & \text{for } R \leq r \leq R + \epsilon. \end{cases}$$

Proof. Obviously, $f_{R_n} \in C^\infty(D_n)$ and $f_{R_n} = 1$ for

$$z \in D_n - \{z : 1 > |z - z_n| \geq 1 - R_n - \epsilon_n\}.$$

So, ds^2 is a smooth Riemannian metric. Thus, it is easy to see that N is a smooth complete Riemannian manifold. Now, noticing that

$$\begin{aligned} 0 &\leq \chi_R(t) \leq 1, \quad \chi_R \in C^\infty, \\ \chi_R(t) &= \begin{cases} 1 & \text{for } t \leq R, \\ 0 & \text{for } t \geq R + \epsilon, \end{cases} \end{aligned}$$

we can easily get the estimates of f_R .

Let $d(.,.)$ denote the geodesic distance function on N , $B(z, r)$ the geodesic ball with center z and radius r . Then, we have

Lemma 3.2. *When $n \rightarrow \infty$, we have*

$$\begin{aligned} |B(z_n, d(z_n, z_n + R_n))| &= \overline{O}(1/(1 - R_n)), \\ |B(z_n + R_n, d(z_n, z_n + R_n) + 1)| &= \overline{O}(1/(1 - R_n)^{\frac{1}{2}}). \end{aligned}$$

Proof. The first estimate is the same as the first estimate in Lemma 2.4. The second

estimate can be obtained by the second estimate in Lemma 2.4. Since

$$B(z_n + R_n, d(z_n, z_n + R_n) + 1)$$

is convex in N , we have

$$\begin{aligned} & B(z_n + R_n, d(z_n, R_n + z_n) + 1) \cap B_0(z_n, R_n + \epsilon_n) \\ & \subset B_0(z_n, R_n + \epsilon_n) \cap \{z : |\arg(z - z_n)| < \alpha'_{R_n}\} \\ & \cup (B(z_n + R_n, d(z_n, R_n + z_n) + 1) \cap \{z : |\arg(z - z_n)| > \alpha'_{R_n}\}). \end{aligned}$$

So, by Lemma 2.4 and Lemma 3.1

$$\begin{aligned} & |B(z_n + R_n, d(z_n, R_n + z_n) + 1) \cap B_0(z_n, R_n + \epsilon_n)| \\ & = \overline{O}(1/(1 - R_n)^{\frac{1}{2}}) \quad (n \rightarrow \infty). \end{aligned}$$

Finally, the Riemannian metric on

$$B(z_n + R_n, 1 + d(z_n, R_n + z_n)) \cap (B_0(z_n, R_n + \epsilon_n))^c$$

is Euclidean and the geodesic distance

$$d(z_n, R_n + z_n) = \frac{1}{2} \ln((1 + R_n)/(1 - R_n)) = n,$$

so we have

$$\begin{aligned} & |B(z_n + R_n, d(z_n, R_n + z_n) + 1) \cap (B_0(z_n, R_n + \epsilon_n))^c| \\ & = \overline{O}(1)(d(z_n, R_n + z_n))^2 = \overline{O}(1)(\ln((1 + R_n)/(1 - R_n)))^2. \end{aligned}$$

Therefore

$$B(z_n + R_n, d(z_n, z_n + R_n) + 1) = \overline{O}((1 - R_n)^{-\frac{1}{2}}) \quad (n \rightarrow \infty).$$

Now, take

$$h_n(z) = |B(z_n, 1)|^{-1} \chi_{B(z_n, 1)}(z).$$

Then, for $z \in B_0(z_n, R_n)$

$$\begin{aligned} M(h_n)(z) & \geq |B(z, d(z_n, z) + 1)|^{-1} \\ & \geq |B(z_n + R_n, d(z_n, z_n + R_n) + 1)|^{-1} \\ & \geq C(1 - R_n)^{\frac{1}{2}} \end{aligned}$$

by Lemma 3.2. So

$$\begin{aligned} & |\{z : M(h_n)(z) > C(1 - R_n)^{\frac{1}{2}}\}| \geq |B_0(z_n, R_n)| \\ & = |B(z_n, d(z_n, z_n + R_n))| \\ & = \overline{O}(1/(1 - R_n)). \end{aligned}$$

But

$$((1 - R_n)^{\frac{1}{2}})^{-p} \int_N h_n^p(z) d\sigma(z) = \overline{O}((1 - R_n)^{-p/2}).$$

Thus, M is not weak type (p, p) bounded for $1 \leq p < 2$. Of course, it is not L^p -bounded for $1 \leq p < 2$.

Acknowledgement. The first named author would like to express his many thanks to Prof. Chen Min-de for his continuous, enthusiastic support, and to Prof. Bai Zhenguo for his inspiration.

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