

ON THE MINIMAL PERIOD FOR PERIODIC SOLUTION PROBLEM OF NONLINEAR HAMILTONIAN SYSTEMS**

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Abstract

The author proves a sharper estimate on the minimal period for periodic solutions of autonomous second order Hamiltonian systems under precisely Rabinowitz' superquadratic condition.

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§1. The Main Results

In this short note, we consider the existence of non-constant periodic solutions with prescribed minimal period for the following autonomous second order Hamiltonian systems

$$\ddot{x} + V'(x) = 0, \quad \forall x \in \mathbf{R}^n, \quad (1.1)$$

where n is a positive integer. $V : \mathbf{R}^n \rightarrow \mathbf{R}$ is a function, and V' denotes its gradient. In his pioneer work [6] in 1978, P. Rabinowitz posed a conjecture of whether (1.1) possesses a non-constant solution with any prescribed minimal period under superquadratic conditions. Since then, a large amount of contributions on this minimal period problem have been made by many mathematicians. We refer to [1] for discussions and references before 1990 on this problem. In a recent paper^[4] under precisely Rabinowitz' superquadratic condition, the author proved that for every $T > 0$ there exists a T -periodic even non-constant solution x of (1.1) with minimal period T/k for some integer k satisfying $1 \leq k \leq n + 2$ (cf. also [2, 3, 5]). In this paper we further improve this estimate for the integer k to $1 \leq k \leq n + 1$. Our main results are the following theorems.

Theorem 1.1. *Suppose V satisfies the following conditions.*

(V1) $V \in C^2(\mathbf{R}^n, \mathbf{R})$.

(V2) *There exist constants $\mu > 2$ and $r_0 > 0$ such that*

$$0 < \mu V(x) \leq V'(x) \cdot x, \quad \forall |x| \geq r_0.$$

(V3) $V(x) \geq V(0) = 0, \quad \forall x \in \mathbf{R}^n$.

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(V4) $V(x) = o(|x|^2)$, at $x = 0$.

Then for every $T > 0$, the system (1.1) possesses a non-constant T -periodic even solution with minimal period T/k for some integer k satisfying $1 \leq k \leq n + 1$.

Theorem 1.2. Suppose V satisfies conditions (V1)–(V3) and the following condition.

(V5) There exist constants $\omega > 0$ and $r_1 > 0$ such that

$$V(x) \leq \frac{\omega}{2}|x|^2, \quad \forall |x| \leq r_1.$$

Then for every positive $T < \frac{2\pi}{\sqrt{\omega}}$, the conclusion of Theorem 1.1 holds.

Our proof depends on a new inequality (Theorem 2.1) of iterated Morse indices for the functional corresponding to (1.1) defined on even function spaces, and the approach used in [4].

§2. The Proofs

As in [4] let $E_T = W^{1,2}(S_T, \mathbf{R}^n)$, where $S_T = \mathbf{R}/(T\mathbf{Z})$, with the norm

$$\|x\|_T = \left(\int_0^T |\dot{x}|^2 dt + T|x(0)|^2 \right)^{1/2}, \quad \forall x \in E_T.$$

The functional corresponding to the system (1.1) is defined by

$$\psi_T(x) = \int_0^T \left(\frac{1}{2}|\dot{x}|^2 - V(x) \right) dt, \quad \forall x \in E_T. \quad (2.1)$$

Define

$$SE_T = \{x \in E_T \mid x(-t) = x(t), \forall t \in \mathbf{R}\}.$$

In [4] it is proved that the critical points of ψ_T restricted to SE_T are one-to-one correspondent to T -periodic even solutions of the system (1.1).

For any critical point x of $\psi_T|_{SE_T}$ the following bilinear form is defined by $\psi_T''(x)$ on SE_T :

$$\phi_T(y, z) = \int_0^T \{\dot{y} \cdot \dot{z} - A(t)y \cdot z\} dt, \quad \forall y, z \in SE_T. \quad (2.2)$$

Denote by $\mathcal{L}_s(\mathbf{R}^n)$ the space of symmetric $n \times n$ real matrices. $A(t) = V''(x(t))$ satisfies the following condition.

(AS) $A \in C(S_T, \mathcal{L}_s(\mathbf{R}^n))$ and $A(t)$ is even about $t = 0$.

Note that ϕ_T corresponds to the following linear second order Hamiltonian system

$$\ddot{y} + A(t)y = 0, \quad \forall y \in \mathbf{R}^n. \quad (2.3)$$

It is proved in [4] that under (AS), SE_T possesses a ϕ_T -orthogonal decomposition $SE_T = SE_T^+ \oplus SE_T^0 \oplus SE_T^-$ according to ϕ_T being positive, null, and negative definite respectively.

If x is a non-constant critical point of ψ_T in SE_T , then $\dot{x}$ is a nontrivial solution of (2.3) with $A(t) = V''(x(t))$, and $\dot{x} \in E_T$ is odd about $t = 0$. Thus we define the space of such odd solutions of (2.3) by $OE_T^0 = \{y \in E_T \mid y \text{ is an odd solution of (2.3)}\}$.

Definition 2.1. Define $si_T = \dim SE_T^-$ and $ov_T = \dim OE_T^0$.

The following estimate on the iterated Morse indices is the main result in this paper.

Theorem 2.1. Suppose the condition (AS) holds. Then

$$si_{kT} \geq k \min\{ov_T, 1\}, \quad \forall k \in \mathbf{N}. \quad (2.4)$$

Proof. Suppose $ov_T \geq 1$ and fix an integer $k \in \mathbf{N}$. Fix $u \in OE_T^0 \setminus \{0\}$. We define new functions u_+ and $u_- \in C(S_{kT}, \mathbf{R}^n)$ by

$$u_+(t) = \begin{cases} u(t), & \text{if } 0 \leq t \leq T/2, \\ 0, & \text{if } T/2 \leq t \leq kT, \end{cases} \quad u_-(t) = \begin{cases} u(t + T/2), & \text{if } 0 \leq t \leq T/2, \\ 0, & \text{if } T/2 \leq t \leq kT. \end{cases} \quad (2.5)$$

Define a $T/2$ -translation operator $\eta : C(S_{kT}, \mathbf{R}^n) \rightarrow C(S_{kT}, \mathbf{R}^n)$ by

$$\eta v(t) = v(t - T/2), \quad \forall v \in C(S_{kT}, \mathbf{R}^n). \quad (2.6)$$

Now we define a sequence of functions $\{u_i\}$ for $1 \leq i \leq k$ based on u by

$$u_i = \eta^{i-1} u_+ - \eta^{2k-i} u_-, \quad \text{if } i \in 2\mathbf{N} - 1, \quad (2.7)$$

$$u_i = -\eta^{i-1} u_- + \eta^{2k-i} u_+, \quad \text{if } i \in 2\mathbf{N}, \quad (2.8)$$

(cf. Figure 1.) and define $N = \text{span}\{u_i \mid 1 \leq i \leq k\}$.

Since all the u_i 's have mutually nonintersect supports, they are linearly independent. Note that each $u_i \in E_{kT}$ is even, there hold

$$\dim N = k, \quad N \subset SE_{kT}, \quad (2.9)$$

$$\phi_{kT}(u_i, u_j) = 0, \quad \text{if } i \neq j. \quad (2.10)$$

Since $u \in OE_T^0 \setminus \{0\}$, we obtain $\dot{u}(0) = \dot{u}(T) \neq 0$ and $\dot{u}(T/2) \neq 0$. Therefore each u_i is not C^1 , and therefore does not belong to $\ker \phi_T$ in E_T . Since u_k is not C^1 at $t = kT/2$, any function in $N \setminus \{0\}$ is not C^1 . Therefore we obtain

$$N \cap \ker \phi_{kT} = \{0\}. \quad (2.11)$$

If i is odd, from the definition of u_i , we obtain

$$\begin{aligned} \phi_{kT}(u_i, u_i) &= \int_{(i-1)T/2}^{iT/2} (|\dot{u}_i|^2 - A(t)u_i \cdot u_i) dt + \int_{(2k-i)T/2}^{(2k-i+1)T/2} (|\dot{u}_i|^2 - A(t)u_i \cdot u_i) dt \\ &= \int_0^{T/2} (|\dot{u}_+|^2 - A(t)u_+ \cdot u_+) dt + \int_0^{T/2} (|\dot{u}_-|^2 - A(t+T/2)u_- \cdot u_-) dt \\ &= \int_0^T (|\dot{u}|^2 - A(t)u \cdot u) dt \\ &= 0. \end{aligned} \quad (2.12)$$

If i is even, from the definition of u_i , we obtain similarly

$$\begin{aligned} \phi_{kT}(u_i, u_i) &= \int_0^{T/2} (|\dot{u}_-|^2 - A(t+T/2)u_- \cdot u_-) dt + \int_0^{T/2} (|\dot{u}_+|^2 - A(t)u_+ \cdot u_+) dt \\ &= 0. \end{aligned} \quad (2.13)$$

Note that (2.10), (2.12), and (2.13) imply

$$\phi_{kT}(v_1, v_2) = 0 \quad \forall v_1, v_2 \in N. \quad (2.14)$$

Based upon (2.9), (2.11), and (2.14), we can apply the step 4 in the proof of Theorem 3.10 of [4], and obtain (2.4). The proof is complete.

Note that different from the constructions in Theorem 3.10 of [4], the u_i 's may not be ϕ_{kT} -orthogonal to constant solutions. Theorem 2.1 should be compared with the following iteration inequality of Morse indices, Theorem 3.10 of [4], where $\sigma_{kT}^+ \in [0, n]$ is an integer determined by $A(t)$,

$$si_{kT} \geq (k-1) \min\{ov_T, 1\} + \sigma_{kT}^+, \quad \forall k \in \mathbf{N}.$$

Since the non-constant solution x obtained via the saddle point theorem in the proofs of Theorems 1.1 and 1.2 always possesses Morse indices $si_T \leq n + 1$ and $ov_{T/k} \geq 1$, where the minimal period of x is denoted by $\tau \equiv T/k$ for some $k \in \mathbf{N}$, we then obtain from Theorem 2.1,

$$n + 1 \geq si_T = si_{k\tau} \geq k \min\{ov_\tau, 1\} \geq k.$$

This proves Theorems 1.1 and 1.2. For details of the proof we refer to that in the section 4 of [4], where we replace the Theorem 3.10 of [4] by the above Theorem 2.1. Note that in the proof of Theorem 1.2, we use Grownwall's inequality to get the constant $2\pi/\sqrt{\omega}$.

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Figure 1. Functions in N defined by (2.7) and (2.8) for the case of $k = 4$.