

SOME INTRINSIC INVARIANTS OF A PARAMETRIC CURVE IN AFFINE HYPERSPACE

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§ 1 Introduction

In a previous paper^[1] the author has determined certain invariants of a parametric curve in affine plane. The purpose of the present paper is to generalize the method to affine hyperspace \mathcal{A}^m of m (>2) dimensions.

Let the parametric equations of a curve of degree n in \mathcal{A}^m be

$$(E) \quad x = \sum_{i=0}^n \frac{1}{i!} a_i t^i,$$

where

$$x = (x_p), \quad p=1, 2, \dots, m,$$

$$a_i = (a_{pi}), \quad i=0, 1, \dots, n$$

and

$$2 < m < n.$$

In what follows, we denote the determinant of order n by

$$\det |a_{i_1}, a_{i_2}, \dots, a_{i_m}| = p_{i_1, i_2, \dots, i_m}$$

and assume that

$$p_{n-m+1, n-m+2, \dots, n-1, n} \neq 0,$$

and, furthermore, that in the last determinant all the diagonal cofactors from below of the orders $1, 2, \dots, n-1$ are different from zero. Then there exists a unique regular affine transformation, called the *canonical affinity*:

$$A^*: \quad x \rightarrow x^*$$

with $J^* \equiv \det |A^*| \neq 0$, so also a canonical parameter transformation:

$$T^*: \quad t = t^* - R,$$

where we have put

$$(1.1) \quad R = p_{n-m, n-m+2, \dots, n} / p_{n-m+1, n-m+2, \dots, n},$$

such that the equations in (E) are reduced to the *canonical form*:

$$(E^*) \quad x_p^* = \sum_{i=1}^{n-m+p} \frac{1}{i!} a_{p,i}^* t^{*i},$$

where

$$(1.2) \quad \begin{aligned} a_{p, n-m+p}^* &= (n-m+p)!, \\ a_{1, n-m}^* &= 0 \quad (p=1, 2, \dots, m). \end{aligned}$$

This new system (E^*) will be called the *associate* system of (E) , and is characterized by two facts:

(1) The highest degrees in t^* of the 1st, 2nd, ..., m th coordinates of x^* are equal to $n-m+1$, $n-m+2$, ..., n respectively. (2) The coefficient of the term in x_1^* of second to the highest degree is equal to zero.

We shall demonstrate the following

Theorem *A parametric curve of degree n in m -dimensional affine space \mathcal{A}^m with $n > m > 2$ possesses, in general, $m(n-m) - 2$ intrinsic affine invariants.*

§ 2 The Pan-Inflexion Equation

As an extension of the inflexion equation of a plane curve, we now consider in \mathcal{A}^m the equation

$$(2.1) \quad D(t) \equiv \det \left| \frac{d\mathbf{x}}{dt}, \frac{d^2\mathbf{x}}{dt^2}, \dots, \frac{d^m\mathbf{x}}{dt^m} \right| = 0$$

and call it the *pan-inflexion equation* of the curve defined by the system (E) .

Obviously, the equation (2.1) is covariantly connected with respect to any non-singular affinity A :

$$(2.2) \quad \bar{x}_r = \sum \alpha_{rs} x_s + \alpha_r, \quad r=1, 2, \dots, m,$$

where

$$(2.3) \quad J \equiv \det |\alpha_{rs}| \neq 0,$$

and any linear transformation T of parameter t :

$$(2.4) \quad t = ct + f \quad (c \neq 0).$$

Accordingly, the equation (2.1) can be rewritten in the form:

$$(F^*) \quad D^*(t^*) \equiv \det \left| \frac{d\mathbf{x}^*}{dt^*}, \frac{d^2\mathbf{x}^*}{dt^{*2}}, \dots, \frac{d^m\mathbf{x}^*}{dt^{*m}} \right| = 0.$$

As the latter is of $N \equiv m(n-m)$ degrees, we obtain

$$(2.5) \quad \sum_{k=0}^N \frac{1}{k!} g_k^* t^{*k} = 0,$$

where we have in particular

$$(2.6) \quad g_0^* = \begin{vmatrix} a_{1,1}^* & a_{2,1}^* & \cdots & a_{m,1}^* \\ a_{1,2}^* & a_{2,2}^* & \cdots & a_{m,2}^* \\ \cdots & \cdots & \cdots & \cdots \\ a_{1,m}^* & a_{2,m}^* & \cdots & a_{m,m}^* \end{vmatrix}.$$

Suppose that $g_0^* \neq 0$, then the equation (2.5) takes the canonical form as follows:

$$(2.7) \quad 1 + \sum_{k=1}^N \frac{1}{k!} G_k^* t^{*k} = 0$$

with the coefficients

$$(2.8) \quad G_k = g_k^* / g_0^*, \quad k=1, 2, \dots, N.$$

In the 4th section we shall demonstrate that

$$(2.9) \quad g_{m(n-m)}^* = \frac{n! [m(n-m)]!}{(n-m)!} \prod_{p=1}^m (m-p)!,$$

$$g_{m(n-m)-1}^* \equiv 0,$$

so that $G_{N-1} \equiv 0$, and therefore we have $N-1$ G_k 's only. It is evident from (2.1) that these G_k 's are affine invariants with respect to A . In the next section we are going to show that they are relative invariants with respect to T .

§ 3 Proof of the Theorem

In order to show this, we have to calculate certain coefficients in the transformed equations

$$(3.1) \quad \bar{x}_r \equiv \sum_{j=0}^n \frac{1}{j!} \bar{a}_{r,j} \bar{t}^j,$$

when the original ones (E) are subjected to A and T simultaneously.

A simple calculation gives

$$(3.2) \quad \bar{a}_{r,j} = c^j \sum_{s=1}^m \alpha_{rs} \sum_{i=j}^n \frac{1}{(i-j)!} a_{s,i} f^{i-j} + \delta_{0j} \alpha_r,$$

$$j=0, 1, \dots, n,$$

$$r=1, 2, \dots, m,$$

where $\delta_{0j} = 1$ or 0 according as $j=0$ or $\neq 0$.

In the following we need merely to evaluate $\bar{a}_{r,j}$ for $j=1, 2, \dots, n$, and therefore assume that

$$i, j, l=1, 2, \dots, n,$$

$$p, q, r=1, 2, \dots, m.$$

Putting

$$(3.3) \quad A_{s,j} = \sum_{i=j}^n \frac{1}{(i-j)!} a_{s,i} f^{i-j},$$

we are led to the relations

$$(3.4) \quad \bar{a}_{r,j} = c^j \sum_{s=1}^m \alpha_{rs} A_{s,j},$$

or in matrix form

$$(3.5) \quad (\bar{a}_{r,j}) = c^j (\alpha_{rs}) (A_{s,j}),$$

the left side being an $m \times n$ matrix.

From (3.4) and the definition of $\bar{p}_{j_1, j_2, \dots, j_m}$ we easily conclude that

$$(3.6) \quad \bar{p}_{j_1, j_2, \dots, j_m} = c^j \cdot J \cdot P_{j_1, j_2, \dots, j_m},$$

where $j = \sum_{r=1}^m j_r$, and

$$(3.7) \quad P_{j_1, j_2, \dots, j_m} \equiv \det |A_{s, j_1} A_{s, j_2} \cdots A_{s, j_m}|.$$

We have now to compute two of them, namely,

$$\bar{p}_{n-m+1, n-m+2, \dots, n} \quad \text{and} \quad \bar{p}_{n-m, n-m+2, \dots, n}.$$

To this end, (3.3) is utilized to derive the following A 's:

$$\begin{aligned} A_{s, n} &= a_{s, n}, \\ A_{s, n-1} &= a_{s, n-1} + a_{s, n} f, \\ A_{s, n-2} &= a_{s, n-2} + a_{s, n-1} f + \frac{1}{2!} a_{s, n} f^2, \\ &\dots\dots\dots \\ A_{s, n-m+1} &= a_{s, n-m+1} + a_{s, n-m+2} f + \dots + \frac{1}{(m-1)!} a_{s, n} f^{m-1}, \\ A_{s, n-m} &= a_{s, n-m} + a_{s, n-m+1} f + \dots + \frac{1}{m!} a_{s, n} f^m. \end{aligned}$$

Hence we arrive at the relations

$$\begin{aligned} \bar{p}_{n-m+1, n-m+2, \dots, n} &= c^\rho \cdot J \cdot P_{n-m+1, n-m+2, \dots, n}, \\ \bar{p}_{n-m, n-m+2, \dots, n} &= c^{\rho-1} \cdot J \cdot \{P_{n-m, n-m+2, \dots, n} + f P_{n-m+1, n-m+2, \dots, n}\} \end{aligned}$$

with

$$\rho = \frac{1}{2} m(2n-m+1).$$

Let \bar{R} be the corresponding expression of R as defined by (1.1). The above two equations give immediately the important equality

$$(3.8) \quad \bar{R} = \frac{1}{c} (R + f).$$

Just as we have used t^* to denote the canonical parameter of t , \bar{t}^* is utilized to denote the corresponding one to \bar{t} , that is,

$$(3.9) \quad t = t^* - R, \quad \bar{t} = \bar{t}^* - \bar{R}.$$

Substituting these expressions into (2.4) and reducing by means of (3.8), we obtain finally

$$(3.10) \quad \bar{t}^* = \frac{1}{c} t^*.$$

There is no difficulty in proving the relative invariant property of each G in (2.7). In fact, let

$$(3.11) \quad 1 + \sum_{r=1}^N \bar{G}_r \bar{t}^{*r} = 0$$

be the canonical equation corresponding to (2.7). If (3.10) is substituted into (3.11), then we get

$$(3.12) \quad \bar{G}_r = c^r G_r.$$

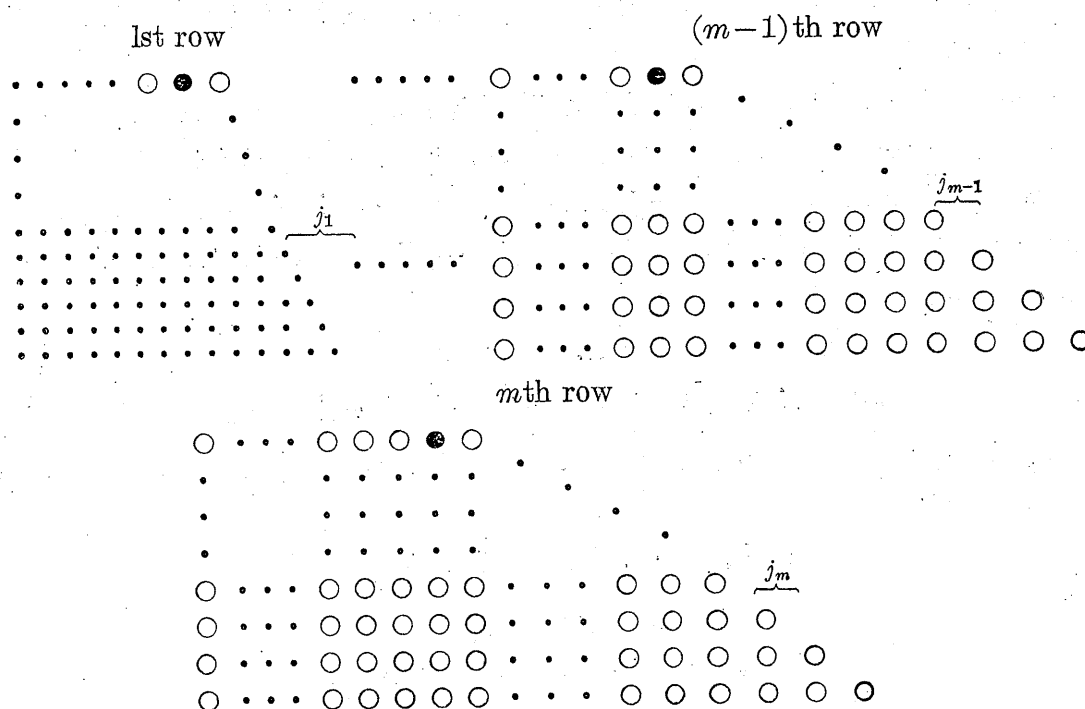
In general case $G_1 \neq 0$. We have then $N-2$ intrinsic affine invariants as given by

$$(3.13) \quad \begin{aligned} I_r &= G_r / (G_1)^r, \\ r &= 2, \dots, N-2, N. \end{aligned}$$

Thus we have completed the proof of our theorem stated in the introduction.

§ 4 Evaluation of g_N^* and g_{N-1}^*

It remains for us to demonstrate the validity of (2.9). For this purpose we express the m rows of the determinant D^* in the left side of (F^*) symbolically as follows (see figure):



In each row a series of small circles on one and the same column is used to denote a polynomial in t^* such that the degree of each term reaches the highest at the right end, and becomes 0 at the left. In every top series we have described a black circle to denote a lacunary term, since $a_{1,n-m}^* = 0$. Take, for example, the m th row. The m th column of this row is composed of all the terms of $d^m x_m^* / (dt^*)^m$, and the degrees in t^* from the right to the left are $n-m$, $n-m-1$, \dots , 0, respectively. Moreover, each term on the same verticle line of this row is of the same degree in t^* . We take one verticle, the j_m th line from the right, say; then each term on it is of degree $n-m-j_m+1$. Here j_m runs over the range 1, 2, \dots , m . In this verticle only the j_m terms counted from the bottom are different from zero, the others ($m-j_m$ in total) being lacunary. The top term is found to be

$$(4.1) \quad T_{m,j_m} = \frac{(n-j_m+1)!}{(n-m-j_m+1)!} t^{*n-m-j_m+1}.$$

When j_m runs over the range 1, 2, \dots , m , corresponding non-zero terms form an equilateral triangle of the hypotenuse composed of m small circles, as shown in the above figure.

This illustration is applicable to any row of D^* , so that we obtain the non-zero top

term on the j_μ th verticle, counted from the right, as

$$(4.2) \quad T_{\mu, j_\mu} = \frac{(n - j_\mu + 1)!}{(n - \mu - j_\mu + 1)!} t^{*n - \mu - j_\mu + 1} \\ (\mu = 1, 2, \dots, m).$$

It should be noted that under the assumption $j_\mu = j_\nu$, but $\mu \neq \nu$, the corresponding terms of the j_μ th and the j_ν verticles on one and the same column of D^* must be proportional, and therefore any determinant of order m containing these two verticles vanishes identically.

Now we notice that the terms in D^* of the highest degree appear when and only when we select those verticles from each corresponding equilateral triangle of the rows above stated, and have to render $j_\mu \neq j_\nu$ for $\mu \neq \nu$. Hence (j_1, j_2, \dots, j_m) must be one permutation of $(1, 2, \dots, m)$. If we use $\sigma(j_1, j_2, \dots, j_m)$ to denote $+1$ or -1 according as the substitution

$$\begin{pmatrix} j_1 & j_2 & \dots & j_{m-1} & j_m \\ m+1-j_1 & m+1-j_2 & \dots & m+1-j_{m-1} & m+1-j_m \end{pmatrix}$$

is even or odd, then the determinant of order m thus formed by selecting the above m verticles is equal to

$$(4.3) \quad \sigma(j_1, j_2, \dots, j_m) T_{1, j_1} T_{2, j_2} \dots T_{m, j_m}.$$

Since

$$\sum_{\mu=1}^m (n - \mu - j_\mu + 1) = m(n - m) = N,$$

the term of the highest degree in t^* , denoted by At^{*N} , is found to be

$$\sum \sigma(j_1, j_2, \dots, j_m) T_{1, j_1} T_{2, j_2} \dots T_{m, j_m}, \\ (j_1, j_2, \dots, j_m) = (1, 2, \dots, m).$$

Hence we arrive at

$$A = \sum \sigma(j_1, j_2, \dots, j_m) \frac{(n - j_1 + 1)! (n - j_2 + 1)! \dots (n - j_m + 1)!}{(n - j_1)! (n - j_2 - 1)! \dots (n - j_m - m + 1)!}, \\ (j_1, j_2, \dots, j_m) = (1, 2, \dots, m).$$

Whence follows immediately the determinant form of A , namely,

$$D_m^N = \begin{vmatrix} \frac{(n-m+1)!}{(n-m)!} & \frac{(n-m+1)!}{(n-m-1)!} & \dots & \frac{(n-m+1)!}{(n-2m+1)!} \\ \frac{(n-m+2)!}{(n-m+1)!} & \frac{(n-m+2)!}{(n-m)!} & \dots & \frac{(n-m+2)!}{(n-2m+2)!} \\ \dots & \dots & \dots & \dots \\ \frac{n!}{(n-1)!} & \frac{n!}{(n-2)!} & \dots & \frac{n!}{(n-m)!} \end{vmatrix}.$$

By means of direct calculation or mathematical induction we obtain finally

$$D_m^N = \frac{n!}{(n-m)!} \prod_{\nu=1}^m (m - \nu)!,$$

or

$$(4.4) \quad g_N^* = \frac{N! n!}{(n-m)!} \prod_{\nu=1}^m (m-\nu)!.$$

Thus the first of (2.9) is proved.

As to the term Bt^{*N-1} in D^* , we have merely to discuss how the coefficient B is formed. During the procedure of finding out A it was revealed that in the present case two of j_1, j_2, \dots, j_m must be equal. If both of them are less than m , the determinant thus formed would vanish identically. On the other hand, if $j_\mu = m$, then we should select the left neighbour of the m th verticle in the μ th column instead of the m th verticle itself. But the top term of the left neighbour verticle is lacunary. Therefore the corresponding determinant thus constructed is also equal to zero. Thus we have proved $B=0$, that is, $g_{N-1}^* = 0$.

Xin Yuanlong also evaluated these coefficients g_N^* and g_{N-1}^* by an alternative method (cf. [2]).

§ 5 Applications

In the case $m=2$ we have obtained certain invariants of parameteric cubics ($n=3$) and of parametric quintics ($n=5$) with two additional conditions (cf. [3] [4]). We shall apply the above theorem to these special cases, and obtain simply the affine invariants.

For the parametric plane cubic ($m=2, n=3$) we consider the vectors

$$\mathbf{a} = (a_1, a_2, a_3), \quad \mathbf{b} = (b_1, b_2, b_3),$$

as well as their vector product

$$\mathbf{a} \times \mathbf{b} = (p, q, r).$$

The inflexion equation (2.1) takes the form

$$D(t) \equiv pt^2 - 2qt + 2r = 0.$$

In general, $p \neq 0$.

Our theorem gives that

$$(5.1) \quad D^*(t^*) \equiv D(t^* - R).$$

In other words:

$$(5.2) \quad 1 + \sum_{k=1}^N \frac{1}{k!} G_k t^{*k} \equiv \frac{1}{D(-R)} D(t^* - R).$$

In the present case we are led to the affine invariant

$$(5.3) \quad I = \left(\frac{q}{p}\right)^2 - 2 \frac{r}{p},$$

which is a relative invariant of weight -2 with respect to T .

A second application is found in the case of parametric plane quintics with additional conditions

$$(5.4) \quad p_{35}=0, p_{45}=0, p_{25} \neq 0.$$

In this case we can put

$$(5.5) \quad \begin{cases} a_3 = \lambda a_5, & b_3 = \lambda b_5, \\ a_4 = \mu a_5, & b_4 = \mu b_5. \end{cases}$$

Using (5.2), we reach three affine invariants, namely,

$$\begin{aligned} a &= 5 \left(\mu - \frac{p_{15}}{p_{25}} \right), \\ b &= 20 \left\{ \frac{p_{23}}{p_{25}} - \mu \frac{p_{15}}{p_{25}} + \frac{1}{2} \left(\frac{p_{15}}{p_{25}} \right)^2 \right\}, \\ g &= -120 \left\{ \frac{p_{12}}{p_{25}} - \frac{1}{2} \lambda \left(\frac{p_{15}}{p_{25}} \right)^2 + \frac{1}{6} \mu \left(\frac{p_{15}}{p_{25}} \right)^3 - \frac{1}{24} \left(\frac{p_{15}}{p_{25}} \right)^2 \right\}, \end{aligned}$$

which are of weights $-1, -2, -4$ with respect to T , respectively.

References

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- [3] Su Buchin, Notes on parametric cubic splines. *Acta Math. Appl. Sinica* (1976), 49—58 (Chinese).
- [4] Su Buchin, Note on parametric quintic splines, *Acta Math. Appl. Sinica* (1977), 22—29 (Chinese).

高维仿射空间参数曲线的几个内在不变量

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摘 要

作者证明下列定理:

m 维仿射空间 $n (> m > 2)$ 次参数曲线一般具有 $m(n-m)-2$ 个内在仿射不变量.

这定理在一些特殊情形下有着应用, 它起到迅速找出仿射不变量的作用. 详情参见苏步青、忻元龙合著论文, 应用数学学报, **3**(1980).