

# Long-Time Dynamics for a Nonlinear Viscoelastic Kirchhoff Plate Equation\*

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**Abstract** This paper is devoted to study the long-time dynamics for a nonlinear viscoelastic Kirchhoff plate equation. Under some growth conditions of  $g$  and  $f$ , the existence of a global attractor is granted. Furthermore, in the subcritical case, this global attractor has finite Hausdorff and fractal dimensions.

**Keywords** Global attractor, Kirchhoff plate, Memory kernel, Finite Hausdorff dimensions

**2000 MR Subject Classification** 35B41, 37L30, 35L75

## 1 Introduction

In the past ten years many attentions were attracted by the following models of Kirchhoff plates subject to a viscoelastic damping

$$u_{tt} - \sigma \Delta u_{tt} + \alpha \Delta^2 u - \int_{-\infty}^t \mu(t-s) \Delta^2 u(s) ds = \mathcal{F}, \quad (1.1)$$

where  $\sigma > 0$  is the uniform plate thickness, the kernel  $\mu > 0$  corresponds to the viscoelastic flexural rigidity, and  $\mathcal{F} = \mathcal{F}(x, t, u, u_t, \dots)$  represents additional damping and forcing terms. The unknown function  $u = u(x, t)$  represents the transverse displacement of a plate filament with prescribed history  $u_0(x, t), t \leq 0$ . The derivation of the linear mathematical model (1.1) with  $\mathcal{F} = 0$  is given in [1–2], by assuming viscoelastic stress-strain laws on an isotropic material occupying a region of  $\mathbb{R}^3$  and constant Poissons ratio.

When  $\sigma = \mu = 0$ , i.e., neglecting the influence of viscoelastic term and rotational inertia term, the model (1.1) was extensively studied by Yang [3–6] and Yang and Jin [7]. More precisely they proved the global solvability and existence of finite-dimensional global attractors to a strongly damped system of the form

$$u_{tt} + \Delta^2 u - \operatorname{div}(|\nabla u|^{p-2} \nabla u) - \Delta u_t = h(x, u, u_t), \quad (1.2)$$

in bounded domains of  $\mathbb{R}^N$  with critical and subcritical exponents  $p$ . In particular, in a two-dimensional setting with  $p = 4$  and weak damping, (1.2) corresponds to the so called Kirchhoff-

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Boussinesq model for nonlinear plates

$$u_{tt} + \Delta^2 u - \operatorname{div}(|\nabla u|^{p-2} \nabla u) + ku_t = \alpha \Delta(u^2) - f(u). \quad (1.3)$$

Chueshov and Lasiecka [8–9] established the existence of finite-dimensional global attractors to (1.3) under a weak damping  $ku_t$  instead of  $-\Delta u_t$ .

If  $\sigma = 0$  and  $\mathcal{F} = \operatorname{div}(|\nabla u|^{p-2} \nabla u) - g(u) + \Delta u_t + h(x)$ ,  $p \geq 2$ , the model (1.1) becomes

$$u_{tt} + \alpha \Delta^2 u - \operatorname{div}(|\nabla u|^{p-2} \nabla u) - \int_0^\infty \mu(s) \Delta^2 u(t-s) ds - \Delta u_t + g(u) = h(x). \quad (1.4)$$

In [10–11], Jorge Silva and Ma established the well-posedness, exponential stability and long-time dynamics of (1.4) Narciso [12] discussed the long-time behavior of the following evolution equation:

$$u_{tt} + \alpha \Delta^2 u - \int_{-\infty}^t \mu(t-s) \Delta^2 u(s) ds + f(u) + g(u_t) = h(x).$$

By considering the nonlinear damping and source terms

$$g(u_t) \approx |u_t|^{p-1} u_t \quad \text{and} \quad f(u) \approx |u|^\alpha u - |u|^\beta u$$

with  $1 < p \leq 3$  and  $0 \leq \beta < \alpha \leq 2$ , the author showed the existence of the global attractor. This work was extended by Conti and Geredeli [13] to a situation where  $g$  has any arbitrary polynomial growth instead of cubic at most and  $f$  has no growth restriction.

In the presence of the rotational inertia term ( $\sigma > 0$ ), the model (1.1) with  $\alpha = 1$  and  $u(x, t) = 0, t \leq 0$  was considered by several authors. In [14], Barreto et al. studied the following viscoelastic equation:

$$u_{tt} - \sigma \Delta u_{tt} + \Delta^2 u - \int_0^t \mu(t-s) \Delta^2 u(s) ds = 0. \quad (1.5)$$

They established that the energy decays to zero with the same rate of the kernel  $\mu$  such as exponential and polynomial decay.

More recently, Jorge Silva et al. [15] investigated the well-posedness and the asymptotic behavior of energy to the following nonlinear viscoelastic Kirchhoff plate equation:

$$u_{tt} - \sigma \Delta u_{tt} + \Delta^2 u - \operatorname{div} f(\nabla u) - \int_0^t \mu(t-s) \Delta^2 u(s) ds = 0. \quad (1.6)$$

Motivated by the works above, our goal of this paper is to discuss the long-time behavior of the following nonlinear viscoelastic Kirchhoff plate equation:

$$u_{tt} - \sigma \Delta u_{tt} + \alpha \Delta^2 u - \operatorname{div} f(\nabla u) - \int_0^\infty \mu(s) \Delta^2 u(t-s) ds - \Delta u_t + g(u) = h(x), \quad (1.7)$$

with simply supported boundary condition

$$u = \Delta u = 0 \quad \text{on} \quad \partial\Omega \times \mathbb{R} \quad (1.8)$$

and initial conditions

$$u(x, \tau) = u_0(x, \tau) \quad \text{and} \quad u_t(x, \tau) = \partial_t u_0(x, \tau), \quad (x, \tau) \in \Omega \times (-\infty, 0], \quad (1.9)$$

where  $\Omega$  is a bounded domain of  $\mathbb{R}^N$  with smooth boundary  $\partial\Omega$ ,  $u_0 : \Omega \times (-\infty, 0] \rightarrow \mathbb{R}$  is the prescribed past history of  $u$ . Here,  $\alpha > 0$  is a constant,  $\mu$  is the memory kernel,  $f : \mathbb{R}^N \rightarrow \mathbb{R}^N$  is a vector field, and  $g, h$  are forcing terms. Without loss of generality we can take  $\sigma = 1$ .

Following the framework proposed in [16–17], which uses an argument of [18], we shall add a new variable  $\eta^t$  to the system which corresponds to the relative displacement history. Let us define

$$\eta^t(x, s) = u(x, t) - u(x, t - s), \quad (x, s) \in \Omega \times \mathbb{R}^+, \quad t \geq 0. \quad (1.10)$$

Differentiating (1.10) with respect to  $t$  we have

$$\eta_t^t(x, s) = -\eta_s^t(x, s) + u_t(x, t), \quad (x, s) \in \Omega \times \mathbb{R}^+, \quad t \geq 0$$

and we can take as initial condition ( $t = 0$ )

$$\eta^0(x, s) = u_0(x, 0) - u_0(x, -s), \quad (x, s) \in \Omega \times \mathbb{R}^+.$$

Thus, the original memory term can be rewritten as

$$\int_0^\infty \mu(s) \Delta^2 u(t - s) ds = \left( \int_0^\infty \mu(s) ds \right) \Delta^2 u(t) - \int_0^\infty \mu(s) \Delta^2 \eta^t(s) ds.$$

Then assuming for simplicity that  $\alpha = 1 + \int_0^\infty \mu(s) ds$ , (1.7) becomes

$$u_{tt} - \Delta u_{tt} - \operatorname{div} f(\nabla u) + \Delta^2 u + \int_0^\infty \mu(s) \Delta^2 \eta^t(s) ds - \Delta u_t + g(u) = h(x), \quad (1.11)$$

$$\eta_t^t(x, s) = -\eta_s^t(x, s) + u_t(x, s), \quad (1.12)$$

with boundary condition

$$u = \Delta u = 0 \quad \text{on} \quad \partial\Omega \times \mathbb{R}^+, \quad \eta^t = \Delta \eta^t = 0 \quad \text{on} \quad \partial\Omega \times \mathbb{R}^+ \quad (1.13)$$

and initial conditions

$$u(x, 0) = u_0(x), \quad u_t(x, 0) = u_1(x), \quad \eta^t(x, 0) = 0, \quad \eta^0(x, s) = \eta_0(x, s), \quad (1.14)$$

where

$$\begin{cases} u_0(x) = u_0(x, 0), & x \in \Omega, \\ u_1(x) = \partial_t u_0(x, t)|_{t=0}, & x \in \Omega, \\ \eta_0(x, s) = u_0(x, 0) - u_0(x, -s), & (x, s) \in \Omega \times \mathbb{R}^+. \end{cases}$$

## 2 Preliminaries

In this section we recall some fundamentals of the theory of infinite-dimensional dynamical systems which can be founded in classic references such as [19–22]. Below we follow more closely the book by Chueshov and Lasiecka [23–24].

**Theorem 2.1** *A dissipative dynamical system  $(\mathcal{H}, S(t))$  has a compact global attractor if and only if it is asymptotically smooth.*

The proof of asymptotic smoothness property can be very delicate. Here we use the following “compensated compactness” result in [23–24] and [25–26] for other applications.

**Theorem 2.2** Suppose that for any bounded positively invariant set  $B \subset \mathcal{H}$  and for any  $\varepsilon > 0$ , there exists  $T = T(\varepsilon, B)$  such that

$$\|S(T)x - S(T)y\|_{\mathcal{H}} \leq \varepsilon + \phi_T(x, y), \quad \forall x, y \in B,$$

where  $\phi_T : B \times B \rightarrow \mathbb{R}$  satisfies

$$\liminf_{n \rightarrow \infty} \liminf_{m \rightarrow \infty} \phi_T(z_n, z_m) = 0, \quad (2.1)$$

for any sequence  $\{z_n\}_{n \in \mathbb{N}}$  in  $B$ . Then  $S(t)$  is asymptotic smooth in  $\mathcal{H}$ .

Let  $X, Y, Z$  be three reflexive Banach spaces with  $X$  compactly embedded in  $Y$  and put  $\mathcal{H} = X \times Y \times Z$ . Consider the dynamical system  $(\mathcal{H}, S(t))$  given by an evolution operator

$$S(t)w = (u(t), u_t(t), \eta^t), \quad w = (u_0, u_1, \eta_0) \in \mathcal{H}, \quad (2.2)$$

where the functions  $u$  and  $\eta^t$  have regularity

$$u \in C(\mathbb{R}^+; X) \cap C^1(\mathbb{R}^+; Y), \quad \eta^t \in C(\mathbb{R}^+; Z). \quad (2.3)$$

Then one says that  $(\mathcal{H}, S(t))$  is quasi-stable on a set  $B \subset \mathcal{H}$  if there exists a compact seminorm  $n_X$  on  $X$  and nonnegative scalar functions  $a(t)$  and  $c(t)$ , locally bounded in  $[0, \infty)$ , and  $b(t) \in L^1(\mathbb{R}^+)$  with  $\lim_{t \rightarrow +\infty} b(t) = 0$ , such that,

$$\|S(t)w_1 - S(t)w_2\|_{\mathcal{H}}^2 \leq a(t)\|w_1(t) - w_2(t)\|_{\mathcal{H}}^2 \quad (2.4)$$

and

$$\|S(t)w_1 - S(t)w_2\|_{\mathcal{H}}^2 \leq b(t)\|w_1(t) - w_2(t)\|_{\mathcal{H}}^2 + c(t) \sup_{0 < s < t} [n_X(u(s) - v(s))]^2, \quad (2.5)$$

for any  $w_1 = (u, u_t, \eta^t), w_2 = (v, v_t, \xi^t) \in B$ . The inequality (2.5) is often called stabilizability inequality.

**Theorem 2.3** Let  $(\mathcal{H}, S(t))$  be given by (2.2) and satisfying (2.3). If  $(\mathcal{H}, S(t))$  possesses a compact global attractor  $\mathcal{A}$  and is quasi-stable on  $\mathcal{A}$ , then the attractor  $\mathcal{A}$  has finite fractal dimension.

### 3 Assumptions and the Main Result

We start this section introducing the following Hilbert spaces

$$V_0 = L^2(\Omega), \quad V_1 = H_0^1(\Omega), \quad V_2 = H^2(\Omega) \cap H_0^1(\Omega)$$

and

$$V_3 = \{u \in H^3(\Omega) | u = \Delta u = 0 \text{ on } \partial\Omega\},$$

equipped with respective inner products and norms,

$$\begin{aligned} (u, v)_{V_1} &= (\nabla u, \nabla v) \quad \text{and} \quad \|u\|_{V_1} = \|\nabla u\|_2, \\ (u, v)_{V_2} &= (\Delta u, \Delta v) \quad \text{and} \quad \|u\|_{V_2} = \|\Delta u\|_2, \\ (u, v)_{V_3} &= (\nabla \Delta u, \nabla \Delta v) \quad \text{and} \quad \|u\|_{V_3} = \|\nabla \Delta u\|_2. \end{aligned}$$

As usual,  $\|\cdot\|_p$  denotes the  $L^p$ -norms as well as  $(\cdot, \cdot)$  denotes either the  $L^2$ -inner product or else a duality pairing between a Banach space  $V$  and its dual  $V'$ . The constants  $\lambda_0, \lambda_1, \lambda_2 > 0$  represent the embedding constants

$$\lambda_0 \|u\|_2^2 \leq \|\nabla u\|_2^2, \quad \lambda_1 \|u\|_2^2 \leq \|\Delta u\|_2^2, \quad \lambda_2 \|\nabla u\|_2^2 \leq \|\Delta u\|_2^2 \quad \text{for } u \in V_2. \quad (3.1)$$

In order to consider the relative displacement  $\eta^t$  as a new variable, one introduces the weighted  $L^2$ -spaces

$$\mathcal{M}_i := L_\mu^2(\mathbb{R}^+; V_i) = \left\{ \xi : \mathbb{R}^+ \rightarrow V_i \mid \int_0^\infty \mu(s) \|\xi(s)\|_{V_i}^2 ds < \infty \right\}, \quad i = 0, 1, 2, 3,$$

which are Hilbert spaces endowed with inner products and norms

$$(\xi_1, \xi_2)_{\mu, i} = \int_0^\infty \mu(s) (\xi_1(s), \xi_2(s))_{V_i} ds$$

and

$$\|\xi\|_{\mu, i}^2 = \int_0^\infty \mu(s) \|\xi(s)\|_{V_i}^2 ds, \quad i = 0, 1, 2, 3$$

respectively.

Now let us introduce the phase spaces

$$\mathcal{H} = V_2 \times V_1 \times \mathcal{M}_2 \quad \text{and} \quad \mathcal{H}_1 = V_3 \times V_2 \times \mathcal{M}_3, \quad (3.2)$$

equipped with norms

$$\|(u, v, \xi)\|_{\mathcal{H}} = \|\Delta u\|_2^2 + \|\nabla v\|_2^2 + \|\xi\|_{\mu, 2}^2$$

and

$$\|(u, v, \xi)\|_{\mathcal{H}_1} = \|\nabla \Delta u\|_2^2 + \|\Delta v\|_2^2 + \|\xi\|_{\mu, 3}^2$$

respectively.

Next we impose some hypotheses on  $f, g$  and  $\mu$ .

**Assumption A.1** Concerning the forcing term  $f : \mathbb{R}^N \rightarrow \mathbb{R}^N$  is a  $C^1$ -vector field given by  $f = (f_1, \dots, f_N)$  such that

$$|\nabla f_j(z)| \leq k_j (1 + |z|^{\frac{p_j-1}{2}}), \quad \forall z \in \mathbb{R}^N, \quad (3.3)$$

where, for every  $j = 1, \dots, N$ , we consider  $k_j > 0$  and  $p_j$  satisfying

$$p_j \geq 1 \quad \text{if } N = 1, 2 \quad \text{and} \quad 1 \leq p_j \leq \frac{N+2}{N-2} \quad \text{if } N \geq 3. \quad (3.4)$$

Moreover,  $f$  is a conservative vector field with  $f = \nabla F$ , where  $F : \mathbb{R}^N \rightarrow \mathbb{R}$  is a real valued function satisfying

$$-\beta_0 - \frac{\beta}{2}|z|^2 \leq F(z) \leq f(z) \cdot z + \frac{\beta}{2}|z|^2, \quad \forall z \in \mathbb{R}^N, \quad (3.5)$$

where  $\beta_0 \geq 0$  and  $\beta \in [0, \frac{\lambda_2}{2})$ .

**Remark 3.1** Observe that the vector field satisfying conditions (3.3) and (3.5) includes not only usual  $p$ -Laplacian operator but also other forms. Then we give examples of vector fields.

Let us consider

$$F(z) = \frac{1}{p}|z|^p, \quad z = (z_1, \dots, z_N) \in \mathbb{R}^N, \quad p \geq 2.$$

We note that  $f = \nabla F$ . Then we have

$$f(z) = |z|^{p-2}z.$$

It is also easy to verify that (3.3) and (3.5) hold true. Therefore, this vector field generates the following  $p$ -Laplacian operator

$$\operatorname{div} f(\nabla u) = \operatorname{div}(|\nabla u|^{p-2}\nabla u).$$

Another case of  $p$ -Laplacian operator arises when we consider the vector field  $f = (f_1, \dots, f_N)$  whose components  $f_j, j = 1, \dots, N$  are given by

$$f_j(z) = |z_j|^{p-2}z_j, \quad \forall z = (z_1, \dots, z_N) \in \mathbb{R}^N,$$

where  $p \geq 2$ . In this case

$$\operatorname{div} f(\nabla u) = \sum_{j=1}^N \frac{\partial}{\partial x_j} \left( \left| \frac{\partial u}{\partial x_j} \right|^{p-2} \frac{\partial u}{\partial x_j} \right).$$

To illustrate another vector field, different one of  $p$ -Laplacian type, we consider  $f = \nabla F$ , where the potential function is given by

$$F(z) = \ln(\sqrt{|z|^2 + 1}), \quad z = (z_1, \dots, z_N) \in \mathbb{R}^N.$$

In such case we have

$$f(z) = \frac{z}{|z|^2 + 1}, \quad \forall z \in \mathbb{R}^N,$$

which vanishes when  $z \rightarrow \infty$ . It is easy to check that  $F$  and  $f$  satisfy (3.3) and (3.5). Thus

$$\operatorname{div}(f(\nabla u)) = \operatorname{div}\left(\frac{\nabla u}{|\nabla u|^2 + 1}\right).$$

**Assumption A.2** With respect to  $g : \mathbb{R} \rightarrow \mathbb{R}$  we assume that

$$g(0) = 0, \quad |g(u) - g(v)| \leq \sigma_0(1 + |u|^q + |v|^q)|u - v|, \quad \forall u, v \in \mathbb{R}, \quad (3.6)$$

where  $\sigma_0 > 0$  and

$$0 < q \leq \frac{4}{N-4} \quad \text{if } N \geq 5 \quad \text{and} \quad q > 0 \quad \text{if } 1 \leq N \leq 4. \quad (3.7)$$

In addition, we assume that for some  $\sigma_1 \geq 0$ ,

$$-\sigma_1 \leq G(u) \leq g(u)u, \quad \forall u \in \mathbb{R}, \quad (3.8)$$

where  $G(z) = \int_0^z g(s)ds$ .

**Assumption A.3** The memory kernel is required to satisfy the following hypotheses

$$\mu \in C^1(\mathbb{R}^+) \cap L^1(\mathbb{R}^+), \quad \mu'(s) \leq 0, \quad \mu(s) \geq 0, \quad (3.9)$$

and there exist  $\mu_0, \delta > 0$  such that

$$\int_0^\infty \mu(s) ds = \mu_0 \quad (3.10)$$

and

$$\mu'(s) + \delta\mu(s) \leq 0, \quad \forall s \in \mathbb{R}^+. \quad (3.11)$$

**Remark 3.2** Applying (3.4) it follows from Sobolev embedding that

$$V_2 \hookrightarrow W_0^{1,p_j+1}(\Omega), \quad \forall j = 1, \dots, N.$$

Thereby, the constants  $\mu_{p_1}, \dots, \mu_{p_N} > 0$  represent the embedding constants for

$$\|\nabla u\|_{p_j+1} \leq \mu_{p_j} \|\Delta u\|_2^2, \quad j = 1, \dots, N. \quad (3.12)$$

Also, condition (3.7) implies that

$$V_2 \hookrightarrow L^{2(q+1)}.$$

In addition, assumptions (3.6) and (3.8) include nonlinear terms of the form

$$g(u) \approx |u|^q u \pm |u|^\theta u, \quad 0 < \theta < q.$$

Given initial data  $(u_0, u_1, \eta_0) \in \mathcal{H}$  and  $h \in V_0$ , a function  $z = (u, u_t, \eta^t) \in C([0, T], \mathcal{H})$  is called a weak solution of the problem (1.11)–(1.14) if it satisfies the initial condition  $z(0) = (u_0, u_1, \eta_0)$  and

$$\begin{aligned} & (u_{tt}, \omega) + (\nabla u_{tt}, \nabla \omega) + (\Delta u, \Delta \omega) + (\nabla u_t, \nabla \omega) + (f(\nabla u), \nabla \omega) \\ & + \int_0^\infty (\Delta \eta^t, \Delta \omega) + (g(u) - h, \omega) = 0, \\ & (\eta_t^t + \eta_s^t, \xi)_{\mu,2} = (u_t(t), \xi)_{\mu,2}, \end{aligned}$$

for all  $\omega \in V_1, \xi \in \mathcal{M}_2$  and a.e.  $t \in [0, T]$ .

The energy corresponding to the system (1.11)–(1.14) is defined as

$$\begin{aligned} E(t) &= \frac{1}{2} \|u_t\|_2^2 + \frac{1}{2} \|\nabla u_t\|_2^2 + \frac{1}{2} \|\Delta u\|_2^2 + \frac{1}{2} \|\eta^t\|_{\mu,2}^2 \\ &+ \int_\Omega F(\nabla u) dx + \int_\Omega (G(u) - hu) dx. \end{aligned} \quad (3.13)$$

Applying Faedo-Galerkin method and combining the arguments of Jorge Silva [15] with those of Jorge Silva and Ma [10], we can obtain the following result.

**Theorem 3.1** Assume that assumptions A.1–A.3 hold and consider  $h \in V_0$ . Then we have

(i) If initial data  $(u_0, u_1, \eta_0) \in \mathcal{H}$ , then problem (1.11)–(1.14) has a weak solution

$$(u, u_t, \eta^t) \in C([0, T], \mathcal{H}), \quad \forall T > 0,$$

satisfying

$$\begin{aligned} u &\in L^\infty(0, T; V_2), \quad u_t \in L^\infty(0, T; V_1), \\ (\mathbf{I} - \Delta)u_{tt} &\in L_{loc}^\infty(\mathbb{R}^+, V_2'), \quad \eta^t \in L^\infty(0, T; \mathcal{M}_2). \end{aligned}$$

(ii) If initial data  $(u_0, u_1, \eta_0) \in \mathcal{H}_1$ , then problem (1.11)–(1.14) has a stronger solution satisfying

$$\begin{aligned} u &\in L^\infty(0, T; V_3), \quad u_t \in L^\infty(0, T; V_2), \\ (\mathbf{I} - \Delta)u_{tt} &\in L_{loc}^\infty(\mathbb{R}^+, V_1'), \quad \eta^t \in L^\infty(0, T; \mathcal{M}_3). \end{aligned}$$

(iii) Let  $z_1(t) = (u, u_t, \eta^t)$ ,  $z_2(t) = (v, v_t, \xi^t)$  be weak solutions of problem (1.11)–(1.14) corresponding to initial data  $z_1(0) = (u_0, u_1, \eta_0)$ ,  $z_2(0) = (v_0, v_1, \xi_0)$ . Then one has

$$\|z_1(t) - z_2(t)\|_{\mathcal{H}}^2 \leq C_T \|z_1(0) - z_2(0)\|_{\mathcal{H}}^2, \quad t \geq 0,$$

for some constant  $C_T = C(\|z_1(0)\|_{\mathcal{H}}, \|z_2(0)\|_{\mathcal{H}}, T) > 0$ . In particular, problem (1.11)–(1.14) has a unique weak solution.

**Remark 3.3** The well-posedness of problem (1.11)–(1.14) given by Theorem 3.1 implies that the one-parameter family of operators  $S(t) : \mathcal{H} \rightarrow \mathcal{H}$  defined by

$$S(t)(u_0, u_1, \eta_0) = (u(t), u_t(t), \eta^t(t)), \quad t \geq 0, \quad (3.14)$$

where  $(u(t), u_t(t), \eta^t(t))$  is the unique weak solution of the system (1.11)–(1.14), satisfies the semigroup properties

$$S(0) = \mathbf{I} \quad \text{and} \quad S(t+s) = S(t) \circ S(s), \quad t, s \geq 0,$$

and defines a nonlinear  $C_0$ -semigroup. Then problem (1.11)–(1.14) can be viewed as a nonlinear infinite dynamical system  $(\mathcal{H}, S(t))$ .

Our main result in this present paper is the following.

**Theorem 3.2** Assume that assumptions A.1–A.3 hold and consider  $h \in V_0$ . Then we have

(i) The dynamical system  $(\mathcal{H}, S(t))$  corresponding to the system (1.11)–(1.14) has a compact global attractor  $\mathcal{A} \subset \mathcal{H}$ .

(ii) If in (3.4) and (3.7) we assume subcritical conditions

$$1 \leq p_j < \frac{N+2}{N-2} \quad \text{if } N \geq 3 \quad \text{and} \quad 0 < q < \frac{4}{N-4} \quad \text{if } N \geq 5, \quad (3.15)$$

then the corresponding global attractor  $\mathcal{A}$  has finite fractal dimension.

## 4 Proof of the Main Result

In this section we will apply the abstract results presented in Section 2 to prove Theorem 3.2. The proof is divided three steps. The first step is to show that the dynamical system  $(\mathcal{H}, S(t))$  is dissipative. The second step is to verify the asymptotic smoothness. Then the existence of a compact global attractor is guaranteed by Theorem 2.1. The final step is to prove the quasi-stability property which implies that the fractal dimension of the attractor is finite, as stated in Theorem 2.3.



#### 4.1 Existence of an absorbing set

**Lemma 4.1** (Absorbing Set) *Under assumptions of Theorem 3.2, the semigroup  $S(t)$  defined by (3.14) has a bounded absorbing set  $\mathcal{B} \in \mathcal{H}$ .*

**Proof** Multiplying (1.11) by  $u_t$  and (1.12) by  $\eta^t$  and integrating over  $\Omega$ , we obtain

$$\frac{d}{dt}E(t) = -\|\nabla u_t\|_2^2 - (\eta^t, \eta_s^t)_{\mu,2}. \quad (4.1)$$

From (3.9), we see that

$$\begin{aligned} (\eta^t, \eta_s^t)_{\mu,2} &= \frac{1}{2} \int_0^\infty \mu(s) \frac{d}{ds} \|\Delta \eta^t(s)\|_2^2 ds \\ &= \left[ \frac{1}{2} \mu(s) \|\Delta \eta^t(s)\|_2^2 \right]_0^\infty - \frac{1}{2} \int_0^\infty \mu'(s) \|\Delta \eta^t(s)\|_2^2 ds. \end{aligned}$$

Using (3.11) we arrive at

$$\mu(s) \leq \mu(0)e^{-\delta s}, \quad \forall s \in \mathbb{R}^+.$$

And this implies

$$\lim_{s \rightarrow \infty} \mu(s) = 0.$$

According to (1.10), namely, the definition of  $\eta^t(x, s)$ , one can easily see that

$$\eta^t(x, 0) = u(x, t) - u(x, t - 0) = 0,$$

which implies that

$$\|\Delta \eta^t(0)\|_2^2 = 0.$$

Thus

$$(\eta^t, \eta_s^t)_{\mu,2} = -\frac{1}{2} \int_0^\infty \mu'(s) \|\Delta \eta^t(s)\|_2^2 ds,$$

which together with (3.11) gives

$$(\eta^t, \eta_s^t)_{\mu,2} \geq \frac{\delta}{2} \|\eta^t\|_{\mu,2}^2. \quad (4.2)$$

This proves that (4.1) can be written as

$$\frac{d}{dt}E(t) \leq -\|\nabla u_t\|_2^2 - \frac{\delta}{2} \|\eta^t\|_{\mu,2}^2. \quad (4.3)$$

Next let us consider the perturbed energy

$$E_\varepsilon(t) = E(t) + \varepsilon \Psi(t), \quad \varepsilon > 0,$$

with

$$\Psi(t) = \int_\Omega u_t(t)u(t)dx - \int_\Omega \Delta u_t(t)u(t)dx. \quad (4.4)$$

Let us show that there exists a constant  $C_1 > 0$  such that

$$|E_\varepsilon(t) - E(t)| \leq \varepsilon C_1 (E(t) + \|h\|_2^2 + |\Omega|), \quad \forall t \geq 0, \quad \forall \varepsilon > 0. \quad (4.5)$$

Indeed, from (3.8), (3.1) and Young inequality, we get

$$\int_{\Omega} (G(u) - hu) dx \geq -\frac{1}{4} \|\Delta u\|_2^2 - \sigma_1 |\Omega| - \frac{1}{\lambda_1} \|h\|_2^2. \quad (4.6)$$

Combining (3.5) with (3.1), we can see that

$$\int_{\Omega} F(\nabla u) dx \geq -\beta_0 |\Omega| - \frac{\beta}{2} \|\nabla u\|_2^2 \geq -\beta_0 |\Omega| - \frac{\beta}{2\lambda_2} \|\Delta u\|_2^2. \quad (4.7)$$

Then using (3.13)–(4.7) we obtain

$$\begin{aligned} E(t) + \frac{1}{\lambda_1} \|h\|_2^2 + (\beta_0 + \sigma_1) |\Omega| &\geq \frac{1}{2} \|\nabla u_t\|_2^2 + \frac{1}{2} \|\eta^t\|_2^2 + \left(\frac{1}{4} - \frac{\beta}{2\lambda_2}\right) \|\Delta u\|_2^2 \\ &\geq \frac{1}{2} C_2 \|(u(t), u_t(t), \eta^t)\|_{\mathcal{H}}^2, \end{aligned} \quad (4.8)$$

where  $C_2 = \min\{1, \frac{1}{2} - \frac{\beta}{\lambda_1}\}$ .

Using Young inequality, (3.1) and (4.8), we have

$$\begin{aligned} |\Psi(t)| &\leq \frac{1}{2} \|u_t\|_2^2 + \frac{1}{2} \|u\|_2^2 + \frac{1}{2} \|\nabla u_t\|_2^2 + \frac{1}{2} \|\nabla u\|_2^2 \\ &\leq \frac{1}{2} \left(\frac{1}{\lambda_0} + 1\right) \|\nabla u_t\|_2^2 + \frac{1}{2} \left(\frac{1}{\lambda_1} + \frac{1}{\lambda_2}\right) \|\Delta u\|_2^2 \\ &\leq \frac{C_3 C_4}{C_2} (E(t) + \|h\|_2^2 + |\Omega|), \end{aligned} \quad (4.9)$$

where

$$C_3 = \max\left\{\lambda_0 + 1, \frac{1}{\lambda_1} + \frac{1}{\lambda_2}\right\}, \quad C_4 = \max\left\{1, \frac{1}{\lambda_1}, \beta_0 + \sigma_1\right\}.$$

Then taking  $C_1 = \frac{C_3 C_4}{C_2}$  the inequality (4.5) follows.

Next let us prove that there exist constants  $C_5, C_6 > 0$  such that

$$\Psi'(t) \leq -E(t) + C_5 \|\nabla u_t(t)\|_2^2 + C_6 \|\eta^t\|_{\mu,2}^2. \quad (4.10)$$

From definition of  $\Psi(t)$ , we see that

$$\Psi'(t) = \int_{\Omega} (u_{tt} - \Delta u_{tt}) u dx + \|u_t\|_2^2 + \|\nabla u_t\|_2^2. \quad (4.11)$$

Using (1.11) we obtain

$$\begin{aligned} \int_{\Omega} (u_{tt} - \Delta u_{tt}) u dx &= -\|\Delta u\|_2^2 - \int_{\Omega} f(\nabla u) \cdot \nabla u dx - \int_0^\infty \mu(s) (\Delta \eta^t(s), \Delta u(t)) ds \\ &\quad - \int_{\Omega} \nabla u_t \cdot \nabla u dx - \int_{\Omega} (g(u)u - hu) dx. \end{aligned} \quad (4.12)$$

Combining (4.11)–(4.12) with (3.13), we get

$$\Psi'(t) = -E(t) + \frac{3}{2} \|u_t\|_2^2 + \frac{3}{2} \|\nabla u_t\|_2^2 - \frac{1}{2} \|\Delta u\|_2^2 + \frac{1}{2} \|\eta^t\|_{\mu,2}^2$$

$$+ I_1 + I_2 + I_3 + I_4, \quad (4.13)$$

where

$$\begin{aligned} I_1 &= \int_{\Omega} [G(u) - g(u)u] dx, \\ I_2 &= \int_{\Omega} [F(\nabla u) - f(\nabla u) \cdot \nabla u] dx, \\ I_3 &= - \int_0^{\infty} \mu(s) (\Delta \eta^t(s), \Delta u(t)) ds, \\ I_4 &= - \int_{\Omega} \nabla u_t \cdot \nabla u dx. \end{aligned}$$

Now let us estimate  $I_i$  ( $i = 1, 2, 3, 4$ ). From (3.8), we have  $I_1 \leq 0$  promptly.

Combining (3.5) with (3.1), we see that

$$I_2 \leq \int_{\Omega} \frac{\beta}{2} |\nabla u|^2 dx \leq \frac{\beta}{2\lambda_2} \|\Delta u\|_2^2. \quad (4.14)$$

By Young inequality, given  $\nu > 0$ , we get

$$\begin{aligned} |I_3| &\leq \int_0^{\infty} \mu(s) \left( \frac{1}{4\nu} \|\Delta \eta^t\|_2^2 + \nu \|\Delta u\|_2^2 \right) ds \\ &= \nu \left( \int_0^{\infty} \mu(s) ds \right) \|\Delta u\|_2^2 + \frac{1}{4\nu} \int_0^{\infty} \mu(s) \|\Delta \eta^t\|_2^2 ds \\ &= \nu \mu_0 \|\Delta u\|_2^2 + \frac{1}{4\nu} \|\eta^t\|_{\mu,2}^2. \end{aligned} \quad (4.15)$$

Using Young inequality and (3.1), we obtain

$$|I_4| \leq \nu \|\nabla u\|_2^2 + \frac{1}{4\nu} \|\nabla u_t\|_2^2 \leq \frac{\nu}{\lambda_2} \|\Delta u\|_2^2 + \frac{1}{4\nu} \|\nabla u_t\|_2^2. \quad (4.16)$$

Then from (4.13)–(4.16) we obtain

$$\begin{aligned} \Psi'(t) &\leq -E(t) + \left( \frac{3}{2\lambda_0} + \frac{3}{2} + \frac{1}{4\nu} \right) \|\nabla u_t\|_2^2 + \left( \frac{1}{2} + \frac{1}{4\nu} \right) \|\eta^t\|_{\mu,2}^2 \\ &\quad - \left[ \frac{1}{2} \left( 1 - \frac{\beta}{\lambda_2} \right) - \nu \left( \frac{1}{\lambda_2} + \mu_0 \right) \right] \|\Delta u\|_2^2. \end{aligned} \quad (4.17)$$

Choose  $\nu$  small enough such that

$$\frac{1}{2} \left( 1 - \frac{\beta}{\lambda_2} \right) - \nu \left( \frac{1}{\lambda_2} + \mu_0 \right) > 0.$$

Therefore, we get (4.10) with  $C_5 = \frac{3}{2\lambda_0} + \frac{3}{2} + \frac{1}{4\nu}$  and  $C_6 = \frac{1}{2} + \frac{1}{4\nu}$ .

Let us choose  $\varepsilon_1 = \min\{\frac{1}{C_5}, \frac{\delta}{2C_6}\}$ , which is positive since we have assumed  $\delta > 0$ . Then combining (4.3) with (4.17), we infer that

$$\begin{aligned} E'_\varepsilon(t) &= E'(t) + \varepsilon \Psi'(t) \\ &\leq -\varepsilon E(t) - (1 - \varepsilon C_5) \|\nabla u_t\|_2^2 - \left( \frac{\delta}{2} - \varepsilon C_6 \right) \|\eta^t\|_{\mu,2}^2 \\ &\leq -\varepsilon E(t), \quad \varepsilon \in (0, \varepsilon_1]. \end{aligned} \quad (4.18)$$

Let us take  $\varepsilon_2 = \min\{\frac{1}{2C_1}, \varepsilon_1\}$ . Then for all  $\varepsilon \leq \varepsilon_2$ , it follows from (4.5) that

$$\frac{1}{2}E(t) - \frac{1}{2}(\|h\|_2^2 + |\Omega|) \leq E_\varepsilon(t) \leq \frac{3}{2}E(t) + \frac{1}{2}(\|h\|_2^2 + |\Omega|). \quad (4.19)$$

Using (4.19) we see that

$$E'_\varepsilon(t) \leq -\frac{2\varepsilon}{3}E_\varepsilon(t) + \frac{\varepsilon}{3}(\|h\|_2^2 + |\Omega|),$$

which implies that

$$\begin{aligned} E_\varepsilon(t) &\leq E_\varepsilon(0)e^{-\frac{2\varepsilon}{3}t} + \frac{1}{2}(1 - e^{-\frac{2\varepsilon}{3}t})(\|h\|_2^2 + |\Omega|) \\ &= \left[ E_\varepsilon(0) - \frac{1}{2}(\|h\|_2^2 + |\Omega|) \right] e^{-\frac{2\varepsilon}{3}t} + \frac{1}{2}(\|h\|_2^2 + |\Omega|). \end{aligned}$$

Using again (4.19) we obtain

$$E(t) \leq 3E(0)e^{-\frac{2\varepsilon}{3}t} + 2(\|h\|_2^2 + |\Omega|).$$

Therefore from (4.8) we conclude that

$$\|(u(t), u_t(t), \eta^t)\|_{\mathcal{H}}^2 \leq CE(0)e^{-\frac{2\varepsilon}{3}t} + C(\|h\|_2^2 + |\Omega|), \quad (4.20)$$

where  $C = \frac{2}{C_2} \max\{3, (2 + C_4)\}$ .

Hence, taking the closed ball  $\mathcal{B} = \overline{\mathcal{B}_{\mathcal{H}}}(0, R)$  with  $R = \sqrt{2C(\|h\|_2^2 + |\Omega|)}$  we infer from (4.20) that  $\mathcal{B}$  is a bounded absorbing set for  $S(t)$ . The proof is complete.

As a straight consequence of Lemma 4.1, we have that the solutions of problem (1.11)–(1.14) are globally bounded provided initial data lying in bounded sets  $B \subset \mathcal{H}$ . Namely, let  $(u, u_t, \eta^t)$  be a solution of (1.11)–(1.14) with initial data  $(u_0, u_1, \eta_0)$  in a bounded set  $B$ . Then one has

$$\|(u(t), u_t(t), \eta^t)\|_{\mathcal{H}} \leq C_B, \quad \forall t \geq 0, \quad (4.21)$$

where  $C_B$  is a constant depending on  $B$ . Lemma 4.1 also ensures the existence of bounded positively invariant sets.

## 4.2 Stability inequality

**Lemma 4.2** (see [15]) *Let  $f : \mathbb{R}^N \rightarrow \mathbb{R}^N$  be a  $C^1$ -vector field given by  $f = (f_1, \dots, f_N)$  and satisfy (3.3). Then, there exists a constant  $K = K(k_j, p_j, N) > 0, j = 1, \dots, N$ , such that*

$$|f(x) - f(y)| \leq K \sum_{j=1}^N (1 + |x|^{\frac{p_j-1}{2}} + |y|^{\frac{p_j-1}{2}}) |x - y|, \quad \forall x, y \in \mathbb{R}^N. \quad (4.22)$$

**Lemma 4.3** *Under the hypotheses of Theorem 3.2, given a bounded set  $B \subset \mathcal{B}$ , let  $z_1 = (u, u_t, \eta^t)$  and  $z_2 = (v, v_t, \xi)$  be two weak solutions of problem (1.11)–(1.14) such that  $z_0^1 = (u_0, u_1, \eta_0)$  and  $z_0^2 = (v_0, v_1, \xi_0)$  are in  $B$ . Then*

$$\begin{aligned} &\|z_1(t) - z_2(t)\|_{\mathcal{H}}^2 \\ &\leq \kappa e^{-\gamma t} \|z_0^1 - z_0^2\|_{\mathcal{H}}^2 \\ &\quad + K_B \int_0^t e^{-\gamma(t-s)} \left( \sum_{j=1}^N \|\nabla(u(s) - v(s))\|_{p_j+1}^2 + \|u(s) - v(s)\|_{2(q+1)}^2 \right) ds, \quad t \geq 0, \end{aligned} \quad (4.23)$$

where  $\kappa, \gamma > 0$  and  $K_B > 0$  are constants.

**Proof** Let us fix a bounded set  $B \subset \mathcal{H}$ . Put  $w = u - v$  and  $\zeta = \eta^t - \xi^t$ . Then  $(w, \zeta^t)$  satisfies

$$\begin{aligned} w_{tt} - \Delta w_{tt} + \Delta^2 w - \operatorname{div}(f(\nabla u) - f(\nabla v)) + \int_0^\infty \mu(s) \Delta^2 \zeta^t(s) ds \\ - \Delta w_t + g(u) - g(v) = 0, \end{aligned} \quad (4.24)$$

$$\zeta^t = -\zeta_s^t + w_t, \quad (4.25)$$

with initial condition

$$w(0) = u_0 - v_0, \quad w_t(0) = u_1 - v_1, \quad \zeta^0 = \eta_0 - \xi_0.$$

Now we consider the functional

$$H(t) = \|\Delta w(t)\|_2^2 + \|\nabla w_t(t)\|_2^2 + \|w_t(t)\|_2^2 + \|\zeta^t\|_{\mu,2}^2 \quad (4.26)$$

and its perturbation

$$H_\varepsilon(t) = H(t) + \varepsilon \Phi(t),$$

where

$$\Phi(t) = \int_\Omega w_t(t) w(t) dx - \int_\Omega \Delta w_t(t) w(t) dx. \quad (4.27)$$

Owing to (3.1), we get

$$\|z_1(t) - z_2(t)\|_{\mathcal{H}}^2 \leq H(t) \leq \left(1 + \frac{1}{\lambda_0}\right) \|z_1(t) - z_2(t)\|_{\mathcal{H}}^2. \quad (4.28)$$

Multiplying (4.24) by  $w_t$  in  $V_0$  and (4.25) by  $\zeta^t$  in  $\mathcal{M}_2$ , and integrating over  $\Omega$ , we deduce that

$$\begin{aligned} & \frac{1}{2} \frac{d}{dt} H(t) + \|\nabla w_t(t)\|_2^2 \\ &= (\operatorname{div}(f(\nabla u) - f(\nabla v)), w_t(t)) - (g(u) - g(v), w_t(t)) - (\zeta^t, \zeta_s^t)_{\mu,2}. \end{aligned} \quad (4.29)$$

Let us estimate the right side of the above identity. Hereafter,  $C_B$  will denote several positive constants.

Using generalized Höld inequality with  $\frac{p_j-1}{2(p_j+1)} + \frac{1}{p_j+1} + \frac{1}{2} = 1$  and (4.22), we have

$$\begin{aligned} & |(\operatorname{div}(f(\nabla u) - f(\nabla v)), w_t)| \\ &= |(f(\nabla u) - f(\nabla v), \nabla w_t)| \\ &\leq \int_\Omega |f(\nabla u) - f(\nabla v)| |\nabla w_t(t)| dx \\ &\leq K \sum_{j=1}^N \int_\Omega (1 + |\nabla u|^{\frac{p_j-1}{2}} + |\nabla v|^{\frac{p_j-1}{2}}) |\nabla w| |\nabla w_t| dx \\ &\leq K \sum_{j=1}^N (|\Omega|^{\frac{p_j-1}{2(p_j+1)}} + \|\nabla u\|_{p_j+1}^{\frac{p_j-1}{2}} + \|\nabla v\|_{p_j+1}^{\frac{p_j-1}{2}}) \|\nabla w\|_{p_j+1} \|\nabla w_t\|_2. \end{aligned}$$

From (3.12) and (4.21) we obtain

$$K(|\Omega|^{\frac{p_j-1}{2(p_j+1)}} + \|\nabla u\|_{p_j+1}^{\frac{p_j-1}{2}} + \|\nabla v\|_{p_j+1}^{\frac{p_j-1}{2}}) \leq C_B < \infty, \quad j = 1, \dots, N.$$

Making use of Young inequality, there exists a constant  $C_B > 0$  such that

$$\begin{aligned} |(\operatorname{div}(f(\nabla u) - f(\nabla v)), w_t)| &\leq C_B \sum_{j=1}^N \|\nabla w\|_{p_j+1} \|\nabla w_t\|_2 \\ &\leq \frac{C_B}{2} \sum_{j=1}^N \|\nabla w\|_{p_j+1}^2 + \frac{1}{4} \|\nabla w_t\|_2^2. \end{aligned} \quad (4.30)$$

Further, since  $\frac{q}{2(q+1)} + \frac{1}{2(q+1)} + \frac{1}{2} = 1$ , again by generalized Höld inequality, (3.6)–(3.7), (4.21), and (3.1), it follows that

$$\begin{aligned} &|(g(u) - g(v), w_t)| \\ &\leq \sigma_0 \int_{\Omega} (1 + |u|^q + |v|^q) |w| |w_t| dx \\ &\leq \sigma_0 (|\Omega|^{\frac{q}{2(q+1)}} + \|u\|_{2(q+1)}^q + \|v\|_{2(q+1)}^q) \|w\|_{2(q+1)} \|w_t\|_2 \\ &\leq C_B \|w\|_{2(q+1)} \|\nabla w_t\|_2. \end{aligned}$$

Using again Young inequality, there exists a constant  $C_B > 0$  such that

$$|(g(u) - g(v), w_t)| \leq \frac{C_B}{2} \|w\|_{2(q+1)}^2 + \frac{1}{4} \|\nabla w_t\|_2^2. \quad (4.31)$$

As in (4.2), we conclude that

$$-(\zeta^t, \zeta_s^t)_{\mu,2} \leq -\frac{\delta}{2} \|\zeta^t\|_{\mu,2}^2. \quad (4.32)$$

Thus combining (4.29) with (4.30)–(4.32) it follows that

$$\frac{d}{dt} H(t) \leq -\|\nabla w_t(t)\|_2^2 - \delta \|\zeta^t\|_{\mu,2}^2 + C_B \left( \sum_{j=1}^N \|\nabla w\|_{p_j+1}^2 + \|w\|_{2(q+1)}^2 \right). \quad (4.33)$$

It follows promptly from the definition of  $H(t)$  and  $\Phi(t)$  that there exists a constant  $C_7 > 0$  such that

$$|H_{\varepsilon}(t) - H(t)| \leq \varepsilon C_7 H(t), \quad \forall t \geq 0, \quad \forall \varepsilon > 0. \quad (4.34)$$

As in the proof of Lemma 4.1, we claim that there exist constants  $\varepsilon_3 > 0$ , and  $C_B > 0$  such that

$$H'_{\varepsilon}(t) \leq -\frac{\varepsilon}{2} H(t) + C_B \left( \sum_{j=1}^N \|\nabla w\|_{p_j+1}^2 + \|w\|_{2(q+1)}^2 \right), \quad \forall t \geq 0, \quad \forall \varepsilon \in (0, \varepsilon_3]. \quad (4.35)$$

To prove this it suffices to prove that there exist constants  $C_8, C_9 > 0$  and  $C_B > 0$  such that

$$\Phi'(t) \leq -\frac{1}{2} H(t) + C_8 \|\nabla w_t(t)\|_2^2 + C_9 \|\zeta^t\|_{\mu,2}^2$$

$$+ C_B \left( \sum_{j=1}^N \|\nabla w\|_{p_j+1}^2 + \|w\|_{2(q+1)}^2 \right). \quad (4.36)$$

In fact, combining (4.33) with (4.36) and choosing  $\varepsilon_3 = \min\{\frac{1}{C_8}, \frac{\delta}{C_9}, 1\}$ , the inequality (4.35) holds for every  $\varepsilon \in (0, \varepsilon_1]$ .

In what follows, we prove that (4.36) holds. By differentiating (4.27), using (4.24) and (4.26), we get

$$\Phi'(t) = -\frac{1}{2}H(t) - \frac{1}{2}\|\Delta w(t)\|_2^2 + \frac{3}{2}\|w_t(t)\|_2^2 + \frac{3}{2}\|\nabla w_t(t)\|_2^2 + \frac{1}{2}\|\zeta^t\|_{\mu,2}^2 + \sum_{i=1}^4 L_i, \quad (4.37)$$

where

$$\begin{aligned} L_1 &= - \int_0^\infty \mu(s)(\Delta \zeta^t(s), \Delta w(t)) ds, \\ L_2 &= - \int_\Omega \nabla w_t(t) \cdot \nabla w(t) dx, \\ L_3 &= (\operatorname{div}(f(\nabla u(t)) - f(\nabla v(t))), w(t)), \\ L_4 &= -(g(u(t)) - g(v(t)), w(t)). \end{aligned}$$

Now we estimate the terms  $L_1, L_2, L_3$ , and  $L_4$ .

$$|L_1| \leq \nu \mu_0 \|\Delta w(t)\|_2^2 + \frac{1}{4\nu} \|\zeta^t\|_{\mu,2}^2$$

and

$$|L_2| \leq \frac{\nu}{\lambda_2} \|\Delta w(t)\|_2^2 + \frac{1}{4\nu} \|\nabla w_t(t)\|_2^2,$$

where  $\nu > 0$  is a small constant which will be chosen later.

$$|L_3| \leq C_B \sum_{j=1}^N \|\nabla w(t)\|_{p_j+1}^2$$

and

$$|L_4| \leq C_B \|w(t)\|_{2(q+1)}^2.$$

Going back to (4.37) and inserting these four last estimates we arrive at

$$\begin{aligned} \Phi'(t) &\leq -\frac{1}{2}H(t) + \left(\frac{3}{2\lambda_0} + \frac{3}{2} + \frac{1}{4\nu}\right) \|\nabla w_t(t)\|_2^2 + \left(\frac{1}{2} + \frac{1}{4\nu}\right) \|\zeta^t\|_{\mu,2}^2 \\ &\quad + C_B \left( \sum_{j=1}^N \|\nabla w(t)\|_{p_j+1}^2 + \|w(t)\|_{2(q+1)}^2 \right) - \left( \frac{1}{2} - \nu \left( \mu_0 + \frac{1}{\lambda_2} \right) \right) \|\Delta w(t)\|_2^2. \end{aligned}$$

Therefore, taking  $\nu > 0$  small enough the inequality (4.36) follows and consequently (4.35) holds.

Now we take  $\varepsilon_4 = \min\{\frac{1}{2C_7}, \varepsilon_3\}$  and choose  $\varepsilon \leq \varepsilon_4$ . Then (4.34) implies that

$$\frac{1}{2}H(t) \leq H_\varepsilon(t) \leq \frac{3}{2}H(t), \quad t \geq 0. \quad (4.38)$$

It follows from (4.35) and (4.38) that

$$H(t) \leq 3e^{-\gamma t}H(0) + K_B \int_0^t e^{-\gamma(t-s)} \left( \sum_{j=1}^N \|\nabla w(s)\|_{p_j+1}^2 + \|w(s)\|_{2(q+1)}^2 \right) ds, \quad t \geq 0,$$

where  $\gamma = \frac{\varepsilon}{3} > 0$  is a small positive constant and  $K_B$  is a constant depending on bounded set  $B$ . From the above inequality and (4.28), we conclude that (4.23) holds. The proof is complete.

**Lemma 4.4** (Asymptotic Smoothness) *Under the hypotheses of Theorem 3.2, the dynamical system  $(\mathcal{H}, S(t))$  is asymptotic smooth.*

**Proof** We apply Lemma 4.3. Let  $B$  be a bounded subset of  $\mathcal{H}$  positively invariant with respect to  $S(t)$ . Let  $S(t)z_0^1 = (u, u_t, \eta^t)$  and  $S(t)z_0^2 = (v, v_t, \xi^t)$  be two solutions for problem (1.11)–(1.14) corresponding to initial data  $z_0^1, z_0^2 \in B$ . Given  $\varepsilon > 0$ , from inequality (4.23), we can choose  $T > 0$  such that

$$\begin{aligned} & \|S(T)z_0^1 - S(T)z_0^2\|_{\mathcal{H}} \\ & \leq \varepsilon + C_B \left\{ \int_0^T \left( \sum_{j=1}^N \|\nabla(u(s) - v(s))\|_{p_j+1}^2 + \|u(s) - v(s)\|_{2(q+1)}^2 \right) ds \right\}^{\frac{1}{2}}, \end{aligned} \quad (4.39)$$

where  $C_B > 0$  is a constant which depends only on the size of  $B$ .

Let us estimate the right side of (4.39). Taking  $\theta_j = \frac{1}{2} + \frac{N}{4}(1 - \frac{2}{p_j+1})$ ,  $j = 1, \dots, N$ , for  $N \geq 1$ , then (3.4) implies that  $\frac{1}{2} \leq \theta_j \leq 1$  and  $\frac{N}{p_j+1} - 1 = \theta_j(\frac{N}{2} - 2) + \frac{N}{2}(1 - \theta_j)$ ,  $j = 1, \dots, N$ . Using Gagliardo-Nirenberg interpolation theorem we get

$$\begin{aligned} \|\nabla(u(t) - v(t))\|_{p_j+1} & \leq C_{\theta_j} \|\Delta(u(t) - v(t))\|_2^{\theta_j} \|u(t) - v(t)\|_2^{1-\theta_j} \\ & \leq C_B \|u(t) - v(t)\|_2^{1-\theta_j}. \end{aligned}$$

We observe that (3.7) implies that  $2 < 2(q+1) < \infty$  if  $1 \leq N \leq 4$  and  $2 < 2(q+1) \leq \frac{2N}{N-4}$  if  $N \geq 5$ . Taking  $\lambda = \frac{N}{4}(1 - \frac{1}{q+1})$  it follows from Gagliardo-Nirenberg interpolation theorem that

$$\begin{aligned} \|u(t) - v(t)\|_{p_j+1} & \leq C_{\lambda} \|\Delta(u(t) - v(t))\|_2^{\lambda} \|u(t) - v(t)\|_2^{1-\lambda} \\ & \leq C_B \|u(t) - v(t)\|_2^{1-\lambda}. \end{aligned}$$

Combining these two last estimates with (4.39), we conclude that there exists  $C_B > 0$  such that

$$\|S(T)z_0^1 - S(T)z_0^2\|_{\mathcal{H}} \leq \varepsilon + \phi_T(z_0^1, z_0^2),$$

where

$$\phi_T(z_0^1, z_0^2) = C_B \left\{ \int_0^T \left( \sum_{j=1}^N \|u(s) - v(s)\|_2^{2(1-\theta_j)} + \|u(s) - v(s)\|_2^{2(1-\lambda)} \right) ds \right\}^{\frac{1}{2}}.$$

To conclude the proof of asymptotic smoothness, it remains to prove that the functional  $\phi_T$  satisfies (2.1). Indeed, given a sequence of initial data  $z_0^n = (u_0^n, u_1^n, \eta_0^n) \in B$ , let us write  $S(t)z_0^n = (u^n(t), u_t^n(t), \eta^{n,t})$ . Since  $B$  is positively invariant with respect to  $S(t)$ , it follows that  $(u^n(t), u_t^n(t), \eta^{n,t})$  is uniformly bounded in  $\mathcal{H}$ . In particular

$$(u^n(t), u_t^n(t)) \text{ is bounded in } C([0, T], V_2 \times V_1), \quad T > 0.$$



Then by compact embedding  $V_2 \hookrightarrow V_0$ , passing to a subsequence if necessary, we have

$$(u^n) \text{ converges strongly in } C([0, T], V_0).$$

Therefore one obtains

$$\lim_{n \rightarrow \infty} \lim_{m \rightarrow \infty} \int_0^T \left( \sum_{j=1}^N \|u^n(s) - u^m(s)\|_2^{2(1-\theta_j)} + \|u^n(s) - u^m(s)\|_2^{2(1-\lambda)} \right) ds = 0,$$

which implies (2.1) holds. Then asymptotic smoothness follows from Theorem 2.2.

**Proof of Theorem 3.2 part (i)** We first note that Lemmas 4.1 and 4.4 imply that  $(\mathcal{H}, S(t))$  is a dissipative dynamical system which is asymptotic smooth. Then the existence of a compact global attractor  $\mathcal{A}$  to problem (1.11)–(1.14) in the phase space  $\mathcal{H}$  follows from Theorem 2.1.

### 4.3 Finite-Dimensional attractor

**Lemma 4.5** (Quasi-stability) *Suppose the assumptions of Theorem 3.2 (ii) hold. Then  $(\mathcal{H}, S(t))$  is quasi-stable on any bounded positively invariant set  $B \subset \mathcal{H}$ .*

**Proof** Since  $(\mathcal{H}, S(t))$  is defined as the solution operator of (1.11)–(1.14), it follows from Theorem 3.1 (i) that (2.2) and (2.3) hold with  $X = V_2$ ,  $Y = V_1$  and  $Z = \mathcal{M}_2$ . Also from Theorem 3.1 (iii) we see that condition (2.4) holds true. Then we only need to verify stability inequality (2.5).

Let  $B \subset \mathcal{H}$  be a bounded set positively invariant with respect to  $S(t)$ . For  $z_0^1, z_0^2 \in B$  we write  $S(t)z_0^i = (u^i(t), u_t^i(t), \eta^{i,t})$ ,  $i = 1, 2$ . Let us define the seminorm

$$n_X(u) = \sum_{j=1}^N \|\nabla u\|_{p_j+1} + \|u\|_{2(q+1)}.$$

From assumption (3.15), we know that embeddings

$$V_2 \hookrightarrow W_0^{1,p_j+1}(\Omega) \quad \text{and} \quad V_2 \hookrightarrow L^{2(q+1)}(\Omega)$$

are compact. Then we conclude that  $n_X(\cdot)$  is a compact seminorm on  $X = V_2$ . Hence from (4.23) we can see that

$$\|z_1(t) - z_2(t)\|_{\mathcal{H}}^2 \leq b(t) \|z_0^1 - z_0^2\|_{\mathcal{H}}^2 + c(t) \sup_{0 < s < t} [n_X(u^1(s) - u^2(s))]^2,$$

where

$$b(t) = \kappa e^{-\gamma t} \quad \text{and} \quad c(t) = K_B \int_0^t e^{-\gamma(t-s)} ds, \quad t \geq 0.$$

Now we note that  $b \in L^1(\mathbb{R}^+)$  and  $\lim_{t \rightarrow \infty} b(t) = 0$ . Also, since  $B$  is bounded it follows that  $c(t)$  is locally bounded on  $[0, \infty)$ . Hence, the assumptions of quasi-stability on bounded positively invariant sets are fulfilled.

**Proof of Theorem 3.2 part (ii)** From the proof of Theorem 3.2 part (i) we know that  $(\mathcal{H}, S(t))$  has a compact global attractor  $\mathcal{A}$ , which is a bounded positively invariant set of  $\mathcal{H}$ . Then it follows from Lemma 4.4 that  $(\mathcal{H}, S(t))$  is quasi-stable on  $\mathcal{A}$ . Based on Theorem 2.3, we conclude that the attractor  $\mathcal{A}$  has finite fractal dimension.

**Remark 4.1** In particular, the Hausdorff dimension of  $\mathcal{A}$  is also finite since it is bounded by the fractal dimension.

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