

ON THE EXISTENCE OF SOLUTIONS TO A TYPE OF NONLINEAR DIFFERENTIAL-ITERATIVE EQUATIONS***

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Abstract

Under the assumption that $h(z)$ is strictly monotone the existence of solutions to a type of nonlinear differential-iterative equations in the form of $x'(t) = g(x(t)) - h(x(x(t)))$ is discussed according to the behavior of the quasi-isoclinic curve $C: x = h^{-1}(g(t))$

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§1. Introduction

Differential-iterative equation is a kind of special functional differential equations which were discussed recently^[1-6]. Most of the researches^[1-3] now available focused on the existence of autonomous differential-iterative equation in the form of

$$x'(t) = f(x^{(n)}(t)),$$

where $x^{(2)} = x(x(t))$ and $x^{(k)} = x(x^{(k-1)}(t))$, $k = 3, 4, \dots, n$, and some in them^[4-5] dealt with the equation $x'(t) = (a^2 - x^2(t))f(x^{(n)}(t))$. We proposed a transformation theorem in [6] and used it to discuss the existence and behavior of solutions to the equation $x'(t) = ax(t) - bx(x(t))$, where $0 < b < a$. In this paper we study a more general equation of the form

$$x'(t) = g(x(t)) - h(x(x(t))), \quad (1.1)$$

where h is strictly monotone on \mathfrak{R} and $h(\mathfrak{R}) = \mathfrak{R}$. Without loss of generality we suppose h is strictly increasing since we can change it into the case by use of the transformation $y = -x$ and $\tau = -t$ when h is decreasing. Then we have

$$\lim_{z \rightarrow \pm\infty} h(z) = \pm\infty.$$

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Definition 1.1. A function $x(t)$ defined on an interval I is said to be a solution of (1.1) on I iff $x(t)$ satisfies (1.1) on I and $x(I) \subset I$.

Definition 1.2. The sets $\Gamma = \{(t, x) \in \mathbb{R}^2 : x = h^{-1}(g(t))\}$ and $L = \{(t, x) \in \mathbb{R}^2 : x = t\}$ are said to be a quasi-isoclinic curve and a base line to Equation (1.1), respectively.

We suppose in this paper

(H) $g, h \in C^0(\mathbb{R}, \mathbb{R})$ are locally Lipschitz, h is strictly increasing and

$$\lim_{z \rightarrow \pm\infty} h(z) = \pm\infty,$$

$$\lim_{x \rightarrow +\infty} \frac{\max\{0, g(x) - h(x)\}}{x^2} = 0.$$

Let $m = \inf\{t \in \mathbb{R} : g(t) - h(t) = 0\}$, $M = \sup\{t \in \mathbb{R} : g(t) - h(t) = 0\}$, where $m = -\infty$ and $M = +\infty$ are included. And set

$$A_0 = \{t \in \mathbb{R} : g(t) - h(t) = 0\},$$

$$A_+ = \{t \in \mathbb{R} : g(t) - h(t) > 0\},$$

$$A_- = \{t \in \mathbb{R} : g(t) - h(t) < 0\}.$$

Obviously under hypothesis (H) A_0 consists of only one point when g is decreasing. It is easy to show (see [4]).

Proposition 1.1. All the solutions of (1.1) are monotone.

Proposition 1.2. For $\eta \in A_0$ and $\xi \in \mathbb{R}$, $x(t) \equiv \eta$ is a constant solution satisfying $x(\xi) = \eta$.

Proposition 1.3. Suppose $f(u, v)$ is continuous and locally Lipschitz with respect to (u, v) on \mathbb{R}^2 and $x = x(t)$ is a solution of $x'(t) = f(x(t), x(x(t)))$ on I . If there is $t_0 \in I$ such that $x'(t_0) = 0$, then $x(t) \equiv x(t_0)$ on I .

Proof. Let $F(y) = f(y, x(y))$. Then F is locally Lipschitz with respect to y for $y \in I$ since x is differentiable on the interval. The condition $x'(t_0) = 0$ implies $f(x(t_0), x(x(t_0))) = 0$. Consider

$$\begin{cases} y' = f(y, x(y)), \\ y(t_0) = x(t_0). \end{cases} \quad (1.2)$$

Obviously both $y = x(t)$ and $y \equiv x(t_0)$ are solutions of (1.2) on I . The Picard's theorem implies $x(t) \equiv x(t_0)$ on I .

Proposition 1.4. Every decreasing solution of (1.1) has one and only one common point with $L : x = t$.

§2. Existence and Behavior of Increasing Solutions

Under hypothesis (H) the assumption that g is increasing implies that $h^{-1}(g(t))$ is increasing and the sets $\{(t, x) \in \Gamma : t \in A_+\}$, $\{(t, x) \in \Gamma : t \in A_-\}$ are above and below the line $x = t$ respectively.

For $\eta \in A_+$, let $u_1 = \sup\{t \in A_0 : t \leq \eta\}$, $u_2 = \inf\{t \in A_0 : t > \eta\}$.

Theorem 2.1. Suppose (H) holds. If $\eta \in A_+$, $m < \eta < M$, then (1.1) has a strictly increasing solution $x(t)$ satisfying $x(\xi) = \eta$ for arbitray $\xi \in \mathbb{R}$. And

(i) $x = x(t)$ intersects Γ at a point $(c, h^{-1}(g(c)))$, $c \in (u_1, u_2)$ and such a solution can be extended to the left to $-\infty$ with $\lim_{t \rightarrow -\infty} x(t) = c$ and

(ii) $x(t)$ can be extended to the right in one of the three ways.

(a) $x = x(t)$ meets Γ at a point $(\sigma_1, h^{-1}(g(\sigma_1)))$, $\sigma_1 > u_2$, $\sigma_1 > \inf\{t \geq \eta : t \in A_0\}$ and then $x(t)$ can be extended to $+\infty$ with $x(t) < \sigma_1$, $\lim_{t \rightarrow +\infty} x(t) = \sigma_1$;

(b) $x = x(t)$ does not meet Γ but has a common point with L at $t_0 > \inf\{t \geq \eta : t \in A_0\}$ with $x'(t) \geq 1$;

(c) $x(t)$ has no common point with $L \cup \Gamma$ for $t > \inf\{t > \eta : t \in A_0\}$ and then $x(t)$ can be extended to $+\infty$ with $x(+\infty) = +\infty$.

Proof. Let $u_1 = \max\{t \leq \eta : t \in A_0\}$, $u_2 = \min\{t \geq \eta : t \in A_0\}$, and $I = [v_1, v_2]$, where $v_1 = \min\{u_1, \xi\}$, $v_2 = \max\{u_2, \xi\}$. Set $M = \max_{(x,y) \in [u_1, u_2]} |g(x) - h(y)| > 0$. Take in consideration a set

$$G = \{z \in C^0(I, [u_1, u_2]) : z(\xi) = \eta, 0 \leq z(t_2) - z(t_1) \leq M(t_2 - t_1) \text{ for } t_1 \leq t_2\}$$

and a map $T : G \rightarrow C^0(I, [u_1, u_2])$ defined by

$$(Tz)(t) = \left[\eta + \int_{\xi}^t \max\{0, g(z(s)) - h(z(z(s)))\} ds \right]_{u_1}^{u_2}, \quad (2.1)$$

where $[A]_{u_1}^{u_2}$ stands for $\min\{u_2, \max\{u_1, A\}\}$. Obviously

$$|[A]_{u_1}^{u_2} - [B]_{u_1}^{u_2}| \leq |A - B|.$$

It is easy to show that G is convex and compact and T continuous. Since $(Tz)(\xi) = \eta$, $u_1 \leq (Tz)(t) \leq u_2$ and for $t_1, t_2 \in I$, $t_1 \leq t_2$,

$$0 \leq (Tz)(t_2) - (Tz)(t_1) \leq \int_{t_1}^{t_2} \max\{0, g(z(s)) - h(z(z(s)))\} ds \leq M(t_2 - t_1),$$

we have $TG \subset G$. The Schauder's fixed point theorem implies the existence of $x \in G$ such that $x = Tx$. If

$$u_1 < x(t) < u_2, \quad \text{when} \quad v_1 < t < v_2, \quad (2.2)$$

then

$$x(t) = \eta + \int_{\xi}^t \max\{0, g(x(s)) - h(x(x(s)))\} ds \quad (2.3)$$

holds on I . We show at first $\{t \in I : x(t) = u_2\} = \Phi$.

Suppose the contrary that $\{t \in I : x(t) = u_2\} \neq \Phi$ and let $\inf\{t \in I : x(t) = u_2\} = t_0$. In this case $u_1 < x(\xi) = \eta < u_2$ implies $\xi < t_0 \leq v_2$. Then $v_2 = u_2$ and $t_0 \leq u_2$. Consequently $x(t)$ satisfies (2.2) on $[\xi, t_0]$. When $t \in [t_0, u_2]$, we have $g(x(s)) - h(x(x(s))) = 0$ since $x(t) = u_2$ and $x(x(t)) = u_2$. Then (2.2) holds on $[\xi, u_2]$. That is to say, $x(t)$ satisfies

$$\begin{cases} y' = \max\{0, g(y) - h(x(y))\}, \\ y(t_0) = u_2, \end{cases} \quad (2.4)$$

on $[\xi, u_2]$. At the same time, $y \equiv u_2$ is also a solution to (2.3). It is easy to see that $F(\cdot) = \max\{0, g(\cdot) - h(x(\cdot))\}$ is locally Lipschitz and then we have $x(t) \equiv u_2$ on $[\xi, u_2]$. However, $x(\xi) = \eta \neq u_2$, a contradiction. Therefore $\{t \in I : x(t) = u_2\} = \Phi$. Similarly $\{t \in I : x(t) = u_1\} = \Phi$. Hence

$$u_1 < x(t) < u_2, \quad t \in I. \quad (2.5)$$

It follows from (2.2) that

$$x'(t) = \max\{0, g(x(t)) - h(x(x(t)))\}. \quad (2.6)$$

We show $x'(t) > 0$ for $t \in I$. Otherwise there is a $t_0 \in I$ such that $x'(t_0) = 0$.

Because $f(u, v) = \max\{0, g(u) - h(v)\}$ is locally Lipschitz, Proposition 1.3 implies $x(t) \equiv x(t_0)$ and then $\eta = x(\xi) = x(t_0)$. It follows that

$$g(x(\xi)) - h(x(x(\xi))) = g(\eta) - h(\eta) \leq 0.$$

However $\eta \in A_+$ implies $g(\eta) - h(\eta) > 0$, a contradiction.

Obviously $x'(t) > 0$ means $g(x(t)) - h(x(x(t))) > 0$ and then (2.6) becomes

$$x'(t) = g(x(t)) - h(x(x(t))), \quad t \in I.$$

That is to say, $x(t)$ is a solution of (1.1) on I with $x(\xi) = \eta$.

Finally we consider the continuation of $x(t)$.

It follows from that $x(v_2) < u_2 \leq v_2$. Consider

$$\begin{cases} y' = g(y) - h(x(y)), \\ y(v_2) = x(v_2), \end{cases} \quad x(v_2) \leq y \leq v_2. \quad (2.7)$$

The solution $y(t)$ of (2.7) is uniquely determined by

$$\int_x^y \frac{ds}{g(s) - h(x(s))} = t - \xi. \quad (2.8)$$

(a) If there is a $\sigma \in [x(v_2), v_2]$ such that $g(\sigma) - h(x(\sigma)) = 0$, then we claim that

$$\lim_{y \rightarrow \sigma} \int_{x(v_2)}^y \frac{ds}{g(s) - h(x(s))} = +\infty.$$

Otherwise suppose the limit is $\tau < +\infty$. Then $y(\tau + \xi) = \sigma$,

$$y'(\tau + \xi) = g(\sigma) - h(x(\sigma)) = 0.$$

Proposition 1.3 implies $y(t) \equiv \sigma$ for $t \in [v_2, v_2 + \tau]$, a contradiction.

Therefore y is defined on $[v_2, +\infty)$ with $y(v_2) = u_2$ and $\lim_{t \rightarrow \infty} y(t) = \sigma$. If $g(y) - h(x(y)) > 0$ for $y \in (u_2, v_2]$, then

$$\lim_{y \rightarrow v_2} \int_{\xi}^y \frac{ds}{g(s) - h(x(s))} = d_1 = t - \xi,$$

and $v_2 = y(v_4)$ where $v_4 := v_2 + d_1 > v_2$. So $y(t)$ is defined on $[v_2, v_4]$ and $y(v_4) = v_2 < v_4$.

Let

$$\tilde{x} = \begin{cases} x(t), & t \in [v_1, v_2], \\ y(t), & t \in [v_2, v_4], \end{cases}$$

and $x(t)$ stands for $\tilde{x}(t)$ on $[v_1, v_4]$. Continue the above process with v_2 replaced consequently by v_4, v_6, \dots .

Suppose there is $\sigma \in (v_{2k}, v_{2k+2}]$ such that $g(\sigma) - h(x(\sigma)) = 0$. Then we can extend $x(t)$ to $+\infty$ with $\lim_{t \rightarrow +\infty} x(t) = \sigma$. Otherwise we have an infinite series $\{v_{2k}\}, k = 1, 2, \dots$, such that $g(t) - h(x(t)) \neq 0$ for $t \in \{v_{2k}, v_{2k+2}\}$.

(b) When $\{v_{2k}\}$ is bounded and $\lim_{k \rightarrow +\infty} v_{2k} = t_0$, we claim that $x(t_0) = t_0$ since otherwise $x(t)$ can be further extended to the right. It follows from $x(t) < t, t \in [\xi, t_0)$, that $x'(t_0) \geq 1$.

(c) If $\{v_{2k}\}$ is unbounded, then $x(t)$ is defined on $[u_1, +\infty)$. We show that $\lim_{t \rightarrow +\infty} x(t) = \infty$. Otherwise suppose $\lim_{t \rightarrow +\infty} x(t) = d < \infty$ and hence

$$\lim_{t \rightarrow +\infty} x'(t) = \lim_{t \rightarrow +\infty} [g(x(t)) - h(x(x(t)))] = g(d) - h(x(d)) = 0.$$

Obviously $d > \eta$. It follows that $x = x(t)$ meets Γ at a point d , a contradiction to the process.

The last part of the proof is to show $x(t)$ can be extended to the left to $-\infty$ with $\lim_{t \rightarrow -\infty} x(t) = c > u_1$.

We have shown in (2.5) that $x(u_1) > u_1 = h^{-1}(g(u_1))$ and $x(u_2) < u_2 = h^{-1}(g(u_2))$. It follows that $\{t \in (u_1, u_2) : x(t) = h^{-1}(g(t))\} \neq \Phi$. Set $c = \max\{t \in (u_1, u_2) : x(t) = h^{-1}(g(t))\}$ and $x(c) > c$. Then the unique solution of

$$\begin{cases} y' = g(y) - h(x(y)), \\ y(v_1) = x(v_1), \end{cases} \quad c < y \leq x(c) \quad (2.9)$$

is determined by

$$\int_{x(v_1)}^y \frac{ds}{g(s) - h(x(s))} = t - v_1.$$

A similar discussion as above leads to the conclusion that

$$\lim_{y \rightarrow C} \int_{x(v_1)}^y \frac{ds}{g(s) - h(x(s))} = -\infty,$$

and then $y(t)$ is defined on $(-\infty, v_1)$ and $\lim_{t \rightarrow -\infty} y(t) = C$. The proof is completed by setting

$$\tilde{x}(t) = \begin{cases} x(t), & t \in [v_1, v_2], \\ y(t), & t \leq v_1 \end{cases}$$

and replacing symbol $\tilde{x}(t)$ by $x(t)$ again.

Lemma 2.1. *Given a differential-iterative equation*

$$x'(t) = f(x(t), x(x(t))), \quad (2.10)$$

where $f \in C^0(\mathbb{R}^2, \mathbb{R})$, such that for a $\sigma \in \mathbb{R}$ and a small $\varepsilon > 0$ satisfying $f(\sigma, \sigma) = 1, f(t, t) < 0$, for $t \in (\sigma, \sigma + \varepsilon)$, (2.10) has an increasing solution $x(t)$ on $I = [\sigma, \sigma + \varepsilon]$ such that $x(\sigma) = \sigma, x(t) < t$, for $t \in (\sigma, \sigma + \varepsilon]$.

Proof. Let $I = [\sigma, \sigma + \varepsilon]$ and $M = \max_{x \in I, \sigma \leq y \leq x} \{f(x, y)\}$. Take a set

$$G = \{z \in C^0(I, I) : z(\sigma) = \sigma, 0 \leq z(t_2) - z(t_1) \leq M(t_2 - t_1) \text{ for } t_1 \leq t_2\}$$

and a map $T : G \rightarrow C^0(I, I)$ defined by

$$(Tg)(t) = \left[\sigma + \int_{\sigma}^t f(z(s), z(z(s))) ds \right]^t, \quad t \in I.$$

By a normal discussion shown in Theorem 2.1, we can show that a fixed point x of T in G is the needed solution of (2.10) on I .

Theorem 2.2. *Suppose (H) holds. If $\eta \in A_+, \eta > M$, then (1.1) has a strictly increasing solution $x(t)$ satisfying $x(\xi) = \eta$ for arbitrary $\xi \in \mathbb{R}$. Such a solution $x(t)$ can be extended to the left to $-\infty$ with $\lim_{t \rightarrow -\infty} x(t) = c > M$ and to the right in one of the two ways.*

(a) $x(t)$ meets L at a point $t_0 > M$ with $x'(t_0) \geq 1$;

(b) $x(t)$ has no common point with L and then $x(t)$ can be extended to $+\infty$ with $x(+\infty) = +\infty$.

Proof. The condition that $\eta \in A_+$ and $\eta > M$ implies Γ is above L when $t > M$.

For $M < \eta \leq \xi$, the proof is similar to that of Theorem 2.1 except that $x(t)$ can never meet Γ below line L . So we prove the theorem only for the case $\eta \geq \xi$. (When $\eta = \xi, g(t) - h(t) > 1, t \in (\eta, \eta + \delta)$ is required for a certain $\delta > 0$ small enough.)

Let $y(\tau) = \frac{1}{x(t) - (\xi - 1)}$ and $\tau = \frac{1}{t - (\xi - 1)}$. Then (1.1) is transformed into

$$\frac{dy(\tau)}{d\tau} = f(\tau, y(\tau), y(y(\tau))), \quad (2.11)$$

where $y(\tau, y(\tau), y(y(\tau))) = \frac{y^2(\tau)}{\tau^2} [g(\frac{1}{y(\tau)} + (\xi - 1)) - h(\frac{1}{y(y(\tau))} + (\xi - 1))]$.

It is easy to see that if $x(t)$ is a solution of (1.1), satisfying $x(\xi) = \eta \geq \xi$ and $x(t) \geq t$ for $t \geq \xi$, then it becomes an appropriate solution $y(\tau)$ of (2.10) satisfying

$$y(1) = \frac{1}{\eta - \xi + 1} \leq 1 \quad \text{and} \quad 0 < y(\tau) \leq \tau \quad \text{for} \quad \tau < 1.$$

Let

$$f_n(\tau, y, z) = \begin{cases} \frac{y^2}{\tau^2 + \varepsilon_n} \max\{0, g(\frac{1}{y} + (\xi - 1)) - h(\frac{1}{z} + (\xi - 1))\}, & y \geq z > 0, \\ 0, & z = 0, \end{cases}$$

where $\varepsilon_n = \frac{\varepsilon}{2^n} > 0$. Obviously f_n is continuous on the set

$$D = \{(\tau, y, z) \in \mathbb{R}^3 : 0 \leq z \leq y \leq 1, 0 \leq \tau \leq 1\}$$

and locally Lipschitz with y and z when $z \neq 0$. Condition (H) implies

$$0 \leq \lim_{y \rightarrow 0} f_n(\tau, y, z) \leq \lim_{y \rightarrow 0} \frac{y^2}{\varepsilon^n} \max\left\{0, g\left(\frac{1}{y} + (\xi - 1)\right) - h\left(\frac{1}{z} + (\xi - 1)\right)\right\} = 0,$$

and then there is $M > 0$ such that

$$f_n(\tau, y, z) \leq M, \quad 0 \leq \max\left\{0, g\left(\frac{1}{y} + (\xi - 1)\right) - h\left(\frac{1}{z} + (\xi - 1)\right)\right\} \leq M, \quad (\tau, y, z) \in D.$$

Take a close and convex subset of $C([0, 1], [0, 1])$,

$$H = \left\{z \in C([0, 1], [0, 1]) : z(1) = \frac{1}{\eta + \xi + 1}, 0 \leq z(s) \leq s, \right. \\ \left. 0 \leq z(s_2) - z(s_1) \leq \frac{M(s_2 - s_1)}{\varepsilon_n}, \quad \forall s_1 < s_2\right\},$$

and a map $P : H \rightarrow C([0, 1], [0, 1])$ defined by

$$(Pz)(\tau) = \left[\frac{1}{\eta + \xi + 1} + \int_0^\tau f_n(s, z(s), z(z(s))) ds \right]_0^\tau, \quad 0 \leq \tau \leq 1.$$

Obviously H is compact, P continuous and $Ph \subset H$. By the Schauder's theorem of fixed points, we have $y_n \in H$ such that

$$y_n(\tau) = \left[\frac{1}{\eta - \xi + 1} + \int_1^\tau f_n(s, y_n(s), y_n(y_n(s))) ds \right]_0^\tau, \quad 0 \leq \tau \leq 1.$$

A similar discussion as in Theorem 1.1 shows that

$$0 < y_n(\tau) \leq \frac{1}{\eta - \xi + 1}. \quad (2.12)$$

Then

$$y_n(\tau) = \left[\frac{1}{\eta - \xi + 1} + \int_1^\tau f_n(s, y_n(s), y_n(y_n(s))) ds \right]^\tau, \quad 0 \leq \tau \leq 1, \quad 0 \leq y_n(\tau) \leq 1,$$

and for any $\sigma \in (0, 1)$, clearly

$$0 \leq f_n(\tau, y_n(\tau), y_n(y_n(\tau))) \leq \frac{1}{\sigma^2} M, \quad \sigma \leq \tau \leq 1.$$

Then $\{y_n(\tau)\}$ is uniformly bounded and uniformly continuous. This implies $\{y_n(\tau)\}$ has a subseries which tends to a function $y(t) > 0$,

$$y(\tau) = \left[\frac{1}{\eta - \xi + 1} + \int_1^\tau f(s, y(s), y(y(s))) ds \right]^\tau, \quad \tau \in (0, 1].$$

Obviously $\eta = y(\tau)$ must meet $L : y = \tau$ at a point $\tau_0 \in [0, 1]$. Then

$$y(\tau) = \frac{1}{\eta - \xi + 1} + \int_1^\tau f(s, y(s), y(y(s))) ds.$$

It follows from $y(t) > 0$ that $\eta(s) \neq 0$ implies $y(y(s)) \neq 0$ for $t \in [\tau_0, 1]$. The function $f(\tau, y, z)$ is locally Lipschitz when $y, z \neq 0$ and Proposition 1.3 implies $y'(\tau) > 0$ for $y(\tau) \neq 0$. Therefore

$$y(\tau) = \frac{1}{\eta - \xi + 1} \int_1^\tau \frac{y^2(s)}{s^2} \left[g\left(\frac{1}{y(s)} + (\xi - 1)\right) - h\left(\frac{1}{y(y(s))} + (\xi - 1)\right) \right] ds, \quad \tau \in (\tau_0, 1)$$

with $y(\tau_0) = \tau_0$. That is to say, $y(\tau)$ is a solution to (2.10) with $y(1) = \frac{1}{\eta - \xi + 1}$.

After making the inverse transformation of (2.10), we obtain the solution to (1.1), $x(t) = \frac{1}{y(1/(t-\xi+1))} + (\xi - 1)$ defined on $[\xi, \frac{1}{\tau_0} - \xi + 1]$ satisfying $x(\xi) = \eta$ and $x(1/\tau_0 - \xi + 1) = 1/\tau_0 - \xi + 1$. Clearly when $\tau_0 = 0$, $x(t)$ is defined on $[\xi, +\infty)$ with $\lim_{t \rightarrow +\infty} x(t) = +\infty$.

The proof for the assertion that $x(t)$ can be extended to $-\infty$ is similar to that in Theorem 2.1.

Theorem 2.3. Suppose (H) holds. If $\eta \in A_+$, $\eta < m$, then (1.1) has a strictly increasing solution $x(t)$ satisfying $x(\xi) = \eta$ for any $\xi \in \mathbb{R}$. Such a solution can be extended to the whole \mathbb{R} , and if $x(t)$ meets Γ at a point $t_1 > m$, then $\lim_{t \rightarrow +\infty} x(t) = t_1$. Otherwise $\lim_{t \rightarrow +\infty} x(t) = +\infty$. On the other hand, if $x(t)$ meets Γ at a point $t_0 < m$, then $\lim_{t \rightarrow -\infty} x(t) = t_0$. Otherwise $\lim_{t \rightarrow -\infty} x(t) = -\infty$.

Proof. (i) Set $I = [\xi, m]$ when $\xi < \eta$ or $\xi = \eta$ with $g(t) - h(t) < 1, t \in [\eta - \delta, \eta]$, required for $\delta < 0$. The same proof as in Theorem 2.1 shows the existence of solution $x(t)$, which can be extended both to the right and to the left in three ways. The theorem is valid except the case that $x(t)$ meets L at a point $\tilde{t}, \tilde{t} < \xi$ or $\tilde{t} > m$.

(ii) Applying a transformation in the form $y = \frac{1}{x - (\xi + 1)}, \tau = \frac{1}{t - (\xi + 1)}$ when $\xi > \eta$ or $\xi = \eta$ with $g(t) - h(t) > 1, t \in [\eta - \delta, \eta]$, required for a certain $\delta > 0$, the same proof as in Theorem 1.2 gives the same results as in (i).

(iii) $\xi = \eta, g(\eta) - h(\eta) = 1$. Set $s = \inf\{t \leq \eta : f(s) - h(s) = 1 \text{ for all } t \leq s \leq \eta\}$. The existence and continuation to the right of $x(t)$ can be proved in the way as showed in Theorem 2.1. If $s = -\infty$, then $x(t) = t$ for $t \leq \eta$. If $s > -\infty$, then there is $\delta > 0$ such that for $t \in [s - \delta, s]$, one of the inequalities $g(t) - h(t) < 1$ and $g(t) - h(t) > 1$ is valid. Then the continuation of solutions is changed into the case (i) or (ii).

In order to prove our assertion it suffices to discuss the case that $x(t)$ meets L at a point $t_1 > m$ with $x(t_1) = t_1$. Obviously $x'(t_1) \geq 1$ implies $g(t_1) - h(t_1) \geq 1 > 0$ and then $t_1 \in A_+, t_1 > m_1$. Taking (t_1, t_1) as (ξ, η) discussed in Theorems 2.1 or 2.2, we can extend $x(t)$ to the right furthermore. Continue the process and then get a set $\{t_n\}$, $t_{n-1} < t_n, x(t_n) = t_n$. If $\{t_n\}$ is finite or infinite but bounded, the continuation to the right is proved as in using Theorems 2.1 or 2.2. If $\{t_n\}$ is infinite and unbounded, then $\lim_{t \rightarrow +\infty} x(t) = +\infty$ since $x(t)$ is increasing.

The continuation to the left can be proved in a similar way.

When the same argument is applied to the case discussed in Theorem 2.1 or 2.2 we have

Corollary 2.1. Suppose (H) holds. If $\eta \in A_+$, then (1.1) has a solution $x(t)$ defined on \mathbb{R} satisfying $x(\xi) = \eta$ for any $\xi \in \mathbb{R}$. If $x(t)$ has a common point $t_1 > \eta[t_1 < \eta]$ with the line

$L : x = t$, then $\lim_{t \rightarrow +\infty} x(t) = t_2$ [$\lim_{t \rightarrow -\infty} x(t) = t_1$]. Otherwise

$$\lim_{t \rightarrow +\infty} x(t) = +\infty \text{ } [\lim_{t \rightarrow -\infty} x(t) = -\infty].$$

Corollary 2.2. Suppose (H) holds. If $g(t)$ is bounded in the positive direction, then all increasing solutions are bounded in the same direction.

§3. Existence and Behavior of Decreasing Solutions

Theorem 3.1. Suppose (H) holds. If $\eta \in A_-$, (1.1) has a decreasing solution $x(t)$ defined on \mathbb{R} satisfying $x(\xi) = \eta$ for any $\xi \in \mathbb{R}$. Let σ be the unique common point of $x = x(t)$ and $x = t$ and $S_1 = \{t \leq \sigma : x(t) = h^{-1}(g(t))\}$, $S_2 = \{t > \sigma : x(t) = h^{-1}(g(t))\}$, $t_1 = \max S_1$, $t_2 = \min S_2$ (If $S_1 = \Phi$, [$S_2 = \Phi$], then $t_1[t_2]$ is defined to be $-\infty[+\infty]$). Then $\lim_{t \rightarrow -\infty} x(t) = t_2$ and $\lim_{t \rightarrow +\infty} x(t) = t_1$.

Proof. (i) If $m < \eta < M$, then let

$$u_1 = \max\{t \leq \eta : t \in A_0\}, \quad u_2 = \min\{t \geq \eta : t \in A_0\}$$

and $I = [v_1, v_2]$, where $v_1 = \min\{u_1, \xi\}$, $v_2 = \min\{u_2, \xi\}$. Set $M = \max_{(x,y) \in I^2} |g(x) - h(y)| > 0$.

Take in $C^0(I, [u_1, u_2])$ a subset

$$H = \{z \in C^0(I, [u_1, u_2]) : z(\xi) = \eta, \quad 0 \leq z(t_2) - z(t_1) \leq M(t_2 - t_1), \quad t_1 \leq t_2\}$$

and a map $P : H \rightarrow C^0(I, [u_1, u_2])$ defined by

$$(Tz)(t) = \left[\eta + \int_{\xi}^t \min\{0, g(z(s)) - h(z(z(s)))\} ds \right]_{u_1}^{u_2}, \quad t \in I. \quad (3.1)$$

A similar discussion as that in Theorem 2.1 leads to the conclusion.

(i) If $\eta < m$, then the proof is almost the same as the case (i) except that $I = [\min\{\xi, \eta\}, \max\{\xi, \eta\}]$ this time and u_1 and u_2 are replaced by $\min\{\xi, \eta\}$ and m respectively.

(ii) If $\eta > M$, then $\overline{\lim}_{x \rightarrow +\infty} h^{-1}(g(x)) = +\infty$. Let $\tau = \min\{t > M : h^{-1}(g(t)) = \eta\}$. Obviously $\tau > M$ since $h^{-1}(g(M)) = M < \eta$ and $\overline{\lim}_{t \rightarrow +\infty} h^{-1}(g(t)) = +\infty$. Take a set and a map similar to those in (i) except $I = [\min\{\xi, M\}, \max\{\tau, \xi\}]$, $u_1 = \min\{\xi, M\}$, $u_2 = \tau$. Then applying the same discussion as the proof of Theorem 2.1 leads to our assertion.

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