

Some Remarks Concerning Hyperholomorphic B-Manifolds****

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(Dedicated to the memory of Vladimir Vishnevskii)

Abstract The authors consider a differentiable manifold with Π -structure which is an isomorphic representation of an associative, commutative and unital algebra. For Riemannian metric tensor fields, the Φ -operators associated with r -regular Π -structure are introduced. With the help of Φ -operators, the hyperholomorphy condition of B-manifolds is established.

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1 Introduction

Let \mathfrak{A}_m be an associative commutative unital algebra (hypercomplex algebra) of order m over the field of real numbers \mathbb{R} . We consider the exact (monomorphic) representation $\Phi: \mathfrak{A}_m \rightarrow \text{End } L_n$ of algebra \mathfrak{A}_m in a linear space L_n over \mathbb{R} . Note that the algebra \mathfrak{A}_m admits in its vector space, the so-called regular representation, given by linear operators $S_\alpha(x) = ax$, where a is a fixed element of \mathfrak{A}_m . It is not difficult to see that the regular representation is exact. For the regular representation, we have

$$(S_\alpha)_\alpha^\beta = C_{\sigma\alpha}^\beta a^\sigma, \quad \alpha, \beta, \sigma = 1, \dots, m,$$

where $C_{\sigma\alpha}^\beta$ are structure constants of the algebra \mathfrak{A}_m . In particular, to the base units $e_\sigma \in \mathfrak{A}_m$, there correspond the matrices $S_\sigma = (C_{\sigma\alpha}^\beta)$. It is known that for the linear operator (affinor) to belong to regular representation $\{S_\alpha\}$, the necessary and sufficient condition is that it commutes with all S_α (see [3]). With the aid of regular representation, we build the so-called r -regular representation of algebra \mathfrak{A}_m in the linear space L_n ($n = mr$), which is also exact, and the matrix of r -regular representation has the form

$$(\varphi)_j^\alpha = \delta_v^u (S_\alpha)_\beta^\alpha,$$

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where δ_v^u is the Kronecker symbol and $u, v = 1, \dots, r$, $i, j = 1, \dots, n$.

In this work, we consider only r -regular representations of algebra \mathfrak{A}_m .

Let $L_r(\mathfrak{A}_m)$ be an \mathfrak{A} -module or a module over algebra \mathfrak{A}_m of order r (see [9, p. 65]), which is defined with the aid of the operators $\{\varphi\}$ or r -regular representation

$$\Phi : \mathfrak{A}_m \rightarrow \text{End } L_n,$$

where $\{\varphi\} = \Phi(\mathfrak{A}_m) \subset \text{End } L_n$, $n = mr$. Note that the \mathfrak{A} -module $L_r(\mathfrak{A}_m)$ arises after comparison

$$\xi^i = \xi^{(u-1)m+\alpha} = \xi^{u\alpha} \rightarrow \xi^u = \xi^{u\alpha} e_\alpha.$$

In fact, if $\eta^i = \varphi_j^i \xi^j$, where $\varphi_j^i \in \Phi(\mathfrak{A}_m)$, then $\eta^{u\alpha} = \delta_v^u C_{\sigma\beta}^\alpha \xi^{v\beta}$, or

$$\eta^u = \eta^{u\alpha} e_\alpha = C_{\sigma\beta}^\alpha \xi^{u\beta} e_\alpha = e_\sigma e_\beta \xi^{u\beta} = e_\sigma \xi^u.$$

The vector transformation law for quantities ξ^u is verified after the definition of a fundamental group of module $L_r(\mathfrak{A}_m)$. The fundamental group of the module $L_r(\mathfrak{A}_m)$ is realized in L_n as the subgroup $G_\varphi \subset \text{GL}(n, \mathbb{R})$, which preserves affinors of representation, i.e., $\forall p \in G_\varphi$ and $\forall \varphi \in \Phi(\mathfrak{A}_m)$,

$$\varphi p = p \varphi, \quad \det(p_{j'}^i) \neq 0.$$

Thus, any block of matrix P of order m commutes with all S_α . That is why

$$p_{j'}^i = \Delta_{u'}^{\sigma u} C_{\sigma\alpha'}^\alpha,$$

where $\Delta_{u'}^{\sigma u}$ are arbitrary coefficients subject only to the regularity condition $\det(p_{j'}^i) \neq 0$. It is easily seen that $\xi^u = S_{u'}^u \xi^{u'}$, where $S_{u'}^u = \Delta_{u'}^{\sigma u} e_\sigma$, i.e., the comparison $\xi^{u\alpha} \rightarrow \xi^u$ is defined correctly on the vector module $L_r(\mathfrak{A}_m)$ over algebra \mathfrak{A}_m .

Let $z = x^\alpha e_\alpha$ be a variable in algebra \mathfrak{A}_m and $f^1(x), f^2(x), \dots, f^m(x)$ be the set of functions of all x^α . Then $\omega = f^\alpha(x) e_\alpha$ is a function of z . We define the differentials

$$d\omega = df^\alpha e_\alpha, \quad dz = dx^\alpha e_\alpha.$$

The function $\omega = \omega(z)$ is called hyperholomorphic, if there exists a function $\omega'(z)$ such that

$$d\omega = \omega'(z) dz.$$

The necessary and sufficient condition for hyperholomorphy of function $\omega = \omega(z)$ is the condition (see [3])

$$S_\alpha D = D S_{\alpha'}, \quad (1.1)$$

where

$$S_\sigma = (C_{\alpha\beta}^\gamma), \quad D = \left(\frac{\partial f^\alpha}{\partial x^\beta} \right).$$

Condition (1.1) will be called the Scheffers condition (see [8]). In particular, in the case of the algebra of complex numbers $\mathfrak{A}_2 = \mathbb{R}(i)$, where $i^2 = -1$, the Scheffers condition coincides with Cauchy-Riemann conditions. If we consider the algebra of dual numbers $\mathfrak{A}_2 = \mathbb{R}(\varepsilon)$, where $\varepsilon^2 = 0$, then from (1.1) it follows that the condition of existence of derivative

$$\omega'(z) = \frac{d\omega}{dz}, \quad \omega = f^1(x^1, x^2) + \varepsilon f^2(x^1, x^2), \quad z = x^1 + \varepsilon x^2$$

has the form

$$\frac{\partial f^1}{\partial x^2} = 0, \quad \frac{\partial f^2}{\partial x^2} = \frac{\partial f^1}{\partial x^1}.$$

Hence, we obtain that the dualholomorphic function $\omega = \omega(z)$ has the structure

$$\omega = F(x^1) + \varepsilon(x^2 F'(x^1) + G(x^1)). \quad (1.2)$$

The dualholomorphic function in form (1.2) is called synectic. In particular, if $G(x^1) = 0$ in (1.2), then the dualholomorphic function in form (1.2) is called the natural extension of real differentiable function $F(x^1)$ to the algebra $\mathbb{R}(\varepsilon)$.

The notion of hyperholomorphic function of several variables from algebra is introduced in a natural way (see [9]): the function $\omega = f^\alpha(x^1, \dots, x^{rm})e_\alpha$ is hyperholomorphic with respect to $z^u = x^{(u-1)m+\alpha}e_\alpha$, $u, v = 1, \dots, r$, if and only if the Scheffers condition is valid for Jacobian matrix

$$\frac{D(f^1, \dots, f^m)}{D(x^{(u-1)m+1}, \dots, x^{um})}, \quad u = 1, \dots, r.$$

Let M_n be a connected manifold of class C^∞ . The field of endomorphisms $\Pi = \{\varphi\}$ is called an algebraic hypercomplex Π -structure over M_n . By the structure, we mean affinors $\varphi, \alpha = 1, \dots, m$, which correspond to the base units $e_\alpha \in \mathfrak{A}_m$ under the isomorphism Φ . Then

$$\varphi_{\alpha\beta}^i \varphi_j^m = C_{\alpha\beta}^\gamma \varphi_j^i. \quad (1.3)$$

If Φ is the r -regular representation of algebra \mathfrak{A}_m , then the hypercomplex Π -structure is called an r -regular Π -structure over M_n ($n = mr$). Note that if \mathfrak{A}_2 is a complex algebra, then the r -regularity of its representation over M_n at once follows from (1.3). Therefore, an almost complex structure over M_{2r} is an example of r -regular Π -structure. A. P. Shirokov proved in [2] that in the tangent bundle, the r -regular Π -structure arises in a natural way and is defined by algebra of dual numbers.

If the coordinate neighbourhood $U \subset M_n$ is endowed with an affine connection in which $\nabla\varphi = 0$, $\forall \varphi \in \Pi$, then such a connection is called a Π -connection. A Π -structure is called integrable, if M_n admits a smooth atlas of local charts such that any affiner $\varphi \in \Pi$ in any of the charts of this atlas has constant components. A Π -structure is called almost integrable, if in a neighbourhood of any point of M_n , there exists at least one Π -connection without torsion. It is known that any integrable r -regular Π -structure is almost integrable and vice versa.

From the facts mentioned above, it follows that if on M_{rm} the r -regular Π -structure is given, then the tangent space $T_x(M_{rm})$ at any point $x \in M_n$ is transformed to the module $L_r(\mathfrak{A}_m)$ over algebra \mathfrak{A}_m . Moreover, if the r -regular Π -structure on M_n is integrable, then as proved in [3], the adapted charts on M_{rm} consist of charts that are connected by hyperholomorphic transition functions, i.e., M_n carries the structure of hyperholomorphic manifold of order r over algebra $\mathfrak{A}_m : \mathfrak{X}_r(\mathfrak{A})$.

2 Φ_φ -Operator

Let \mathfrak{A}_m be a Frobenius hypercomplex algebra and $K^* = (K_{v_1 \dots v_q}^{u_1 \dots u_p})$ be a hypercomplex tensor field on $\mathfrak{X}_r(\mathfrak{A}_m)$. Then the real model of such a tensor field is a tensor field $K = (K_{j_1 \dots j_q}^{i_1 \dots i_p})$ on M_{mr} of the same order that is independent of whether its vector or covector arguments

are subject to the action of affinors φ , $\alpha = 1, \dots, m$. Such tensor fields are said to be pure with respect to $\Pi = \{\varphi\}$, $\alpha = 1, \dots, m$. They were studied by many authors (see [3, 5–7, 9]). Applied to $K \in \mathfrak{S}_q^p(M_n)$, $p + q > 1$, the purity means that for any $X_1, X_2, \dots, X_q \in \mathfrak{S}_0^1(M_n)$ and $\xi_1, \xi_2, \dots, \xi_p \in \mathfrak{S}_1^0(M_n)$ the following conditions should hold:

$$\begin{aligned} & K(\varphi X_1, X_2, \dots, X_q, \xi_1, \xi_2, \dots, \xi_p) \\ &= K(X_1, \varphi X_2, \dots, X_q, \xi_1, \xi_2, \dots, \xi_p) = \dots = K(X_1, X_2, \dots, \varphi X_q, \xi_1, \xi_2, \dots, \xi_p) \\ &= K(X_1, X_2, \dots, X_q, \varphi' \xi_1, \xi_2, \dots, \xi_p) = K(X_1, X_2, \dots, X_q, \xi_1, \varphi' \xi_2, \dots, \xi_p) \\ &= \dots = K(X_1, X_2, \dots, X_q, \xi_1, \xi_2, \dots, \varphi' \xi_p), \end{aligned}$$

where φ' is the adjoint operator of φ . The vector (covector) field and scalar is considered to be pure by convention.

We denote by $\mathfrak{S}_q^p(M_n)$ the module of all pure tensor fields of type (p, q) on M_n with respect to the affinor field $\varphi \in \mathfrak{S}_1^1(M_n)$. We now fix a positive integer λ . If K and L are pure tensor fields of types (p_1, q_1) and (p_2, q_2) respectively, then the tensor product of K and L with contraction $K \overset{C}{\otimes} L = K_{j_1 \dots j_{q_1}}^{i_1 \dots i_{p_1} m_\lambda \dots i_{p_1}} L_{s_1 \dots s_{q_2}}^{r_1 \dots r_{p_2} m_\lambda \dots s_{q_2}}$ is also a pure tensor field. We shall prove only the case when $K \in \mathfrak{S}_1^1(M_n)$ and $L \in \mathfrak{S}_2^0(M_n)$. In fact, we have

$$(K \overset{C}{\otimes} L)(\varphi X, Y) = K(L(\varphi X, Y)) = K(L(X, \varphi Y)) = (K \overset{C}{\otimes} L)(X, \varphi Y).$$

We shall now make the direct sum $\mathfrak{S}^*(M_n) = \sum_{p,q=0}^{\infty} \mathfrak{S}_q^p(M_n)$ into an algebra over the real number \mathbb{R} by defining the pure product (denoted by $\overset{C}{\otimes}$) of $K \in \mathfrak{S}_{q_1}^{p_1}(M_n)$ and $L \in \mathfrak{S}_{q_2}^{p_2}(M_n)$ as follows:

$$\overset{C}{\otimes}: (K, L) \rightarrow K \overset{C}{\otimes} L = \begin{cases} K_{j_1 \dots j_{q_1}}^{i_1 \dots i_{p_1} m_\lambda \dots i_{p_1}} L_{s_1 \dots s_{q_2}}^{r_1 \dots r_{p_2} m_\lambda \dots s_{q_2}} & \text{for } \lambda \leq p_1, q_2 \text{ (}\lambda \text{ is a fixed positive integer),} \\ K_{j_1 \dots j_{q_1}}^{i_1 \dots i_{p_1} m_\mu \dots i_{p_1}} L_{s_1 \dots s_{q_2}}^{r_1 \dots r_{p_2} m_\mu \dots s_{q_2}} & \text{for } \mu \leq p_2, q_1 \text{ (}\mu \text{ is a fixed positive integer),} \\ 0 & \text{for } p_1 = 0, p_2 = 0, \\ 0 & \text{for } q_1 = 0, q_2 = 0. \end{cases}$$

Let $K \in \mathfrak{S}_0^1(M_n)$ and $L \in \Lambda_{q_2}(M_n)$ be a q_2 -form. Then the pure product coincides with the interior product $i_X L$.

Definition 2.1 A map $\Phi_\varphi: \mathfrak{S}^*(M_n) \rightarrow \mathfrak{S}^*(M_n)$ $\left(\mathfrak{S}^*(M_n) = \sum_{p,q=0}^{\infty} \mathfrak{S}_q^p(M_n)\right)$ is a Φ_φ -operator on M_n , if

- (a) Φ_φ is linear with respect to constant coefficients,
- (b) for all p, q , $\Phi_\varphi: \mathfrak{S}_q^p(M_n) \rightarrow \mathfrak{S}_{q+1}^p(M_n)$,
- (c) for all $K, L \in \mathfrak{S}^*(M_r)$,

$$\Phi_\varphi(K \overset{C}{\otimes} L) = (\Phi_\varphi K) \overset{C}{\otimes} L + K \overset{C}{\otimes} \Phi_\varphi L,$$

(d) for all $X, Y \in \mathfrak{S}_0^1(M_n)$, $\Phi_{\varphi X} Y = -(L_Y \varphi) X$, where L_Y is the Lie derivation with respect to Y .

- (e) for all $\omega \in \mathfrak{S}_1^0(M_n)$ and $X, Y \in \mathfrak{S}_0^1(M_n)$, $\Phi_{\varphi X}(i_Y \omega) = (\varphi X)(i_Y \omega) - X(i_Y \omega)$.

Remark 2.1 It follows that Φ_φ possesses also the following property:

$$\Phi_{\varphi X}(\omega(Y_1, \dots, Y_q)) = (\varphi X)(\omega(Y_1, \dots, Y_q)) - X(\omega(\varphi Y_1, \dots, Y_q)).$$

Proof We shall prove the formula for the case $q = 2$. By Definition 2.1(d) and the purity of ω , we have

$$\begin{aligned} \Phi_{\varphi X}(\omega(Y, Z)) &= \Phi_{\varphi X}((i_Y \omega)Z) = \Phi_{\varphi X}(i_Z(i_Y \omega)) = (\varphi X)(i_Z(i_Y \omega)) - X(i_{\varphi Z}(i_Y \omega)) \\ &= (\varphi X)(i_Y \omega)(Z) - X(i_Y \omega)(\varphi Z) = (\varphi X)(\omega(Y, Z)) - X(\omega(\varphi Y, Z)). \end{aligned}$$

Let $K \in \mathfrak{S}_q^1(M_n)$. Using the condition (c) of Definition 2.1, we have, for any operator Φ_φ ,

$$\Phi_{\varphi X}(K(Y_1, \dots, Y_q)) = (\Phi_{\varphi X} K)(Y_1, \dots, Y_q) + \sum_{\lambda=1}^q K(Y_1, \dots, \Phi_{\varphi X} Y_\lambda, \dots, Y_q).$$

Then Definition 2.1(d) implies

$$\begin{aligned} (\Phi_\varphi K)(X; Y_1, \dots, Y_q) &= (\Phi_{\varphi X} K)(Y_1, \dots, Y_q) \\ &= -(L_{K(Y_1, \dots, Y_q)} \varphi)X + \sum_{\lambda=1}^q K(Y_1, \dots, (L_{Y_\lambda} \varphi)X, \dots, Y_q). \end{aligned}$$

Using (e) by similar devices for $\omega \in \mathfrak{S}_q^0(M_n)$, we have

$$\begin{aligned} (\Phi_\varphi \omega)(X; Y_1, \dots, Y_q) &= (L_{\varphi X} \omega - L_X(\omega \circ \varphi))(Y_1, Y_2, \dots, Y_q) \\ &\quad + \sum_{\lambda=2}^q \omega(Y_1, Y_2, \dots, \varphi(L_X Y_\lambda), \dots, Y_q) \\ &\quad - \sum_{\lambda=2}^q \omega(\varphi Y_1, Y_2, \dots, L_X Y_\lambda, \dots, Y_q). \end{aligned} \quad (2.1)$$

The following theorem is true.

Theorem 2.1 *Let on M_{rm} be given the integrable r -regular hypercomplex Π -structure. For hypercomplex tensor field t of type $(1, q)$ (or of type $(0, q)$) on $\mathfrak{X}_r(\mathfrak{A})$ to be \mathfrak{A} -holomorphic tensor field, it is necessary and sufficient that*

$$\Phi_{\varphi_\alpha} t = 0, \quad \alpha = 1, \dots, m, \quad t \in \mathfrak{S}^*(M_{rm}).$$

Proof For simplicity, let $t \in \mathfrak{S}_q^0(\mathfrak{X}_r(\mathfrak{A}))$. By setting $X = \partial_k$, $Y_\lambda = \partial_{j_\lambda}$, $\lambda = 1, \dots, q$ in the equation of (2.1), we see that the components $(\Phi_{\varphi_\alpha} t)_{kj_1 \dots j_q}$ of $\Phi_{\varphi_\alpha} t$ with respect to local coordinate system x^1, \dots, x^{rm} may be expressed as follows:

$$(\Phi_{\varphi_\alpha} t)_{kj_1 \dots j_q} = \varphi_\alpha^m \partial_m t_{j_1 \dots j_q} - \partial_k(t(\varphi)_\alpha)_{j_1 \dots j_q} + \sum_{\lambda=1}^q (\partial_{j_\lambda} \varphi_\alpha^m) t_{j_1 \dots m \dots j_q}.$$

By virtue of [3],

$$t_{j_1 \dots j_q} = \mathfrak{S}_{v_1 \dots v_q \sigma} C_{\beta_1 \lambda_1}^\sigma C_{\beta_2 \lambda_2}^{\lambda_1} \dots C_{\beta_{q-1} \lambda_{q-1}}^{\lambda_{q-2}}.$$

In the adapted charts, we have ($j_\lambda = v_\lambda \beta_\lambda$, $k = \omega \gamma$, $\lambda = 1, \dots, q$)

$$\begin{aligned} (\Phi_{\varphi} t)_{k j_1 \dots j_q} &= \varphi_k^m \partial_m t_{j_1 \dots j_q} - \partial_k (t(\varphi))_{j_1 \dots j_q} \\ &= (C_{\alpha \gamma}^\mu \partial_{\omega \mu} \mathfrak{S}_{v_1 \dots v_q \sigma} - C_{\alpha \sigma}^\lambda \partial_{\omega \gamma} \mathfrak{S}_{v_1 \dots v_s \lambda}) C_{\beta_1 \lambda_1}^\sigma C_{\beta_2 \lambda_2}^{\lambda_1} \dots C_{\beta_{q-1} \lambda_{q-1}}^{\lambda_{q-2}} = 0 \end{aligned}$$

or

$$C_{\alpha \gamma}^\mu \partial_{\omega \mu} \mathfrak{S}_{v_1 \dots v_q \sigma} = C_{\alpha \sigma}^\mu \partial_{\omega \gamma} \mathfrak{S}_{v_1 \dots v_q \mu},$$

which is the Scheffers condition of \mathfrak{A} -holomorphy of $t_{v_1 \dots v_q}^* = \mathfrak{S}_{v_1 \dots v_q \sigma} e^\sigma$ ($e^\sigma = q^{\sigma \alpha} e_\alpha$, $q^{\sigma \alpha}$ is a Frobenius metric) with respect to local coordinates $z^u = x^{u \alpha} e_\alpha$ from $\mathfrak{X}_r(\mathfrak{A})$. This completes the proof.

3 Hyperholomorphic B-Manifold

Let M_{rm} be a Riemannian manifold with metric g , which is not necessarily positive definite. A pure metric with respect to the hypercomplex structure is a Riemannian metric g such that

$$g(\varphi_\alpha X, Y) = g(X, \varphi_\alpha Y), \quad \alpha = 1, \dots, m \quad (3.1)$$

for any $X, Y \in \mathfrak{S}_0^1(M_{rm})$. Such Riemannian metrics were studied in [9], where they were said to be B-metrics, since the metric tensor g with respect to the Π -structure is B-tensor according to the terminology accepted in [4]. If (M_{rm}, Π) is an almost hypercomplex manifold with B-metric, we say that (M_{rm}, Π, g) is an almost hypercomplex B-manifold. If $\Pi = \{\varphi_\alpha\}$ is integrable, we say that (M_{rm}, Π, g) is a hypercomplex B-manifold.

In a B-manifold, a B-metric is called hyperholomorphic, if

$$(\Phi_{\varphi} g)(X, Y, Z) = 0, \quad \alpha = 1, \dots, m.$$

If (M_{rm}, Π, g) is a B-manifold with hyperholomorphic B-metric g , we say that (M_{rm}, Π, g) is a hyperholomorphic B-manifold. Since in dimension m , such a manifold is flat (see [9, p. 113]), we assume in the sequel that $\dim M \geq 2m$, i.e., $r \geq 2$.

Theorem 3.1 *An almost B-manifold is a hyperholomorphic B-manifold, if and only if the almost hypercomplex structure is parallel with respect to the Levi-Civita connection ∇ .*

Proof By virtue of (3.1) and $\nabla g = 0$, we have

$$g(Z, (\nabla_Y \varphi_\alpha) X) = g((\nabla_Y \varphi_\alpha) Z, X). \quad (3.2)$$

Using (3.1) and $[X, Y] = \nabla_X Y - \nabla_Y X$, we have transform $\Phi_{\varphi} g$ as follows:

$$(\Phi_{\varphi} g)(X; Z_1, Z_2) = -g((\nabla_X \varphi_\alpha) Z_1, Z_2) + g((\nabla_{Z_1} \varphi_\alpha) X, Z_2) + g(Z_1, (\nabla_{Z_2} \varphi_\alpha) X). \quad (3.3)$$

From this, we have

$$(\Phi_{\varphi} g)(Z_2; Z_1, X) = g((\nabla_{Z_2} \varphi_\alpha) Z_1, X) + g((\nabla_{Z_1} \varphi_\alpha) Z_2, X) + g(Z_1, (\nabla_X \varphi_\alpha) Z_2). \quad (3.4)$$

If we add (3.3) to (3.4), we find

$$(\Phi_{\varphi}g)(X; Z_1, Z_2) + (\Phi_{\varphi}g)(Z_2; Z_1, X) = 2g(X, (\nabla_{Z_1}\varphi)Z_2). \quad (3.5)$$

Putting $\Phi_{\varphi}g = 0$ in (3.5), we find $\nabla_{\alpha}\varphi = 0$. Conversely, if $\nabla_{\alpha}\varphi = 0$, then the condition $\Phi_{\varphi}g = 0$ follows from (3.3) or (3.4).

4 Examples of Hyperholomorphic B-Manifolds

A Kahler-Norden manifold (see [1]) can be defined as a triple (M_{2n}, φ, g) , $n \geq 2$, which consists of a manifold M_{2n} , endowed with an almost complex structure φ and a pseudo-Riemannian metric g such that $\nabla\varphi = 0$, where ∇ is the Levi-Civita connection of g and the metric g is assumed to be Nordenian: $g(\varphi X, Y) = g(X, \varphi Y)$. Thus, the Kahler-Norden manifold is a complex holomorphic B-manifold.

Let $T(M_n)$ be a tangent bundle of a Riemannian manifold (M_n, g) . It is well-known that there exists a tensor field of type $(1, 1)$ which has components of the form

$$\gamma = \begin{pmatrix} 0 & 0 \\ E & 0 \end{pmatrix}$$

with respect to the induced coordinates (x^i, x^{n+i}) in $T(M_n)$, E being unit matrix in M_n and γ satisfying $\gamma^2 = 0$. Thus $T(M_n)$ has a natural integrable n -regular dual Π -structure $\Pi = \{I, \gamma\}$, where I denotes the identity transformation. The complete lift Cg of g is a B-metric with respect to γ . Thus $(T(M_n), \gamma, {}^Cg)$ is a B-manifold. Moreover, we easily see that ${}^C\nabla\gamma = 0$, where ${}^C\nabla$ is the complete lift of the Levi-Civita connection ∇ in M_n . Thus $(T(M_n), \Pi, {}^Cg)$ is a dualholomorphic B-manifold.

By similar devices, we can prove that $(T(M_n), \gamma, {}^Cg)$ is also a dualholomorphic B-manifold, where ${}^Cg = {}^Sg + {}^Va$ (Va is a vertical lift of a symmetric tensor field $a \in T_2^0(M_n)$) is a synectic lift of g (see [2]).

Let, now, $T^2(M_n)$ be a tangent bundle of order 2 over M_n . It is also well-known that there exists an affinor field $\gamma \in \mathfrak{S}_1^1(T^2(M_n))$ which has components of the form

$$\hat{\gamma} = \begin{pmatrix} 0 & 0 & 0 \\ E & 0 & 0 \\ 0 & E & 0 \end{pmatrix}, \quad \hat{\gamma}^3 = 0$$

with respect to the induced coordinates (x^i, x^{n+i}, x^{2n+i}) in $T^2(M_n)$, i.e., $T^2(M_n)$ has a natural integrable n -regular plural Π -structure $\Pi = \{I, \hat{\gamma}, \hat{\gamma}^2\}$. The second lift of g , i.e., ${}^{CC}g = {}^IIg$ (see [10, p. 332]), is a B-metric with respect to $\hat{\gamma}$ and ${}^{CC}\nabla {}^Cg = 0$ where ${}^{CC}\nabla$ denotes the second lift of the Levi-Civita connection ∇ , which is necessarily the Levi-Civita connection determined by ${}^{CC}g$. Thus, $(T^2(M_n), \hat{\Pi}, {}^{CC}g)$ is a pluralholomorphic B-manifold.

A locally decomposable Riemannian manifold M_{2k} is a paraholomorphic B-manifold (see [7]).

5 Curvature Tensors in a Hyperholomorphic B-Manifold

Let R be the Riemannian curvature tensor formed by g . If a torsion free connection ∇ preserving the structure ($\nabla\varphi = 0$) satisfies the condition $\nabla_{\varphi X}Y = \varphi(\nabla_X Y)$, then ∇ is called

a hyperholomorphic connection (see [9, p. 185]). The purity of the curvature tensor field of a connection ∇ is a necessary and sufficient condition for its holomorphy (see [3, 9]). Since the Levi-Civita connection of hyperholomorphic B-manifold is hyperholomorphic (see [3, 9]), we see that in a hyperholomorphic B-manifold, the Riemannian curvature tensor R of B-metric g is pure.

Since the Riemannian curvature tensor R is pure, we can apply the Φ -operator to R . By similar devices (see the proof of Theorem 3.1), we can prove that

$$(\Phi_{\varphi} R)(X, Y_1, Y_2, Y_3, Y_4) = (\nabla_{\varphi X} R)(Y_1, Y_2, Y_3, Y_4) - (\nabla_X R)(\varphi Y_1, Y_2, Y_3, Y_4). \quad (5.1)$$

Applying the Ricci's identity to φ_{α} , we get

$$\varphi_{\alpha}(R(X, Y)Z) = R(X, Y)\varphi_{\alpha}Z \quad (5.2)$$

by virtue of $\nabla_{\alpha}\varphi = 0$. Using (5.2) and applying the second Bianchi identity to (5.1), we get

$$\begin{aligned} (\Phi_{\varphi} R)(X, Y_1, Y_2, Y_3, Y_4) &= g((\nabla_{\varphi X} R)(Y_1, Y_2, Y_3) - (\nabla_X R)(\varphi Y_1, Y_2, Y_3), Y_4) \\ &= g((\nabla_{\varphi X} R)(Y_1, Y_2, Y_3) - \varphi_{\alpha}((\nabla_X R)(Y_1, Y_2, Y_3)), Y_4) \\ &= g(-(\nabla_{Y_1} R)(Y_2, \varphi X, Y_3) - (\nabla_{Y_2} R)(\varphi X, Y_1, Y_3) \\ &\quad - \varphi_{\alpha}((\nabla_X R)(Y_1, Y_2, Y_3)), Y_4). \end{aligned} \quad (5.3)$$

On the other hand, using $\nabla_{\alpha}\varphi = 0$, we find

$$\begin{aligned} (\nabla_{Y_2} R)(\varphi X, Y_1, Y_3) &= \nabla_{Y_2}(R(\varphi X, Y_1, Y_3)) - R(\nabla_{Y_2}(\varphi X), Y_1, Y_3) \\ &\quad - R(\varphi X, \nabla_{Y_2} Y_1, Y_3) - R(\varphi X, Y_1, \nabla_{Y_2} Y_3) \\ &= (\nabla_{Y_2} \varphi)(R(X, Y_1, Y_3)) + \varphi_{\alpha}(\nabla_{Y_2} R(X, Y_1, Y_3)) \\ &\quad - R((\nabla_{Y_2} \varphi)X + \varphi_{\alpha}(\nabla_{Y_2} X), Y_1, Y_3) \\ &\quad - R(\varphi X, \nabla_{Y_2} Y_1, Y_3) - R(\varphi X, Y_1, \nabla_{Y_2} Y_3) \\ &= \varphi_{\alpha}(\nabla_{Y_2} R(X, Y_1, Y_3)) - \varphi_{\alpha}(R(\nabla_{Y_2} X, Y_1, Y_3)) \\ &\quad - \varphi_{\alpha}(R(X, \nabla_{Y_2} Y_1, Y_3)) - \varphi_{\alpha}(R(X, Y_1, \nabla_{Y_2} Y_3)) \\ &= \varphi_{\alpha}((\nabla_{Y_2} R)(X, Y_1, Y_3)). \end{aligned} \quad (5.4)$$

Similarly,

$$(\nabla_{Y_1} R)(Y_2, \varphi X, Y_3) = \varphi_{\alpha}((\nabla_{Y_1} R)(Y_2, X, Y_3)). \quad (5.5)$$

Substituting (5.4) and (5.5) in (5.3) and using again the second Bianchi identity, we obtain

$$\begin{aligned} (\Phi_{\varphi} R)(X, Y_1, Y_2, Y_3, Y_4) &= g(-\varphi_{\alpha}((\nabla_{Y_1} R)(Y_2, X, Y_3)) - \varphi_{\alpha}((\nabla_{Y_2} R)(X, Y_1, Y_3)) \\ &\quad - \varphi_{\alpha}((\nabla_X R)(Y_1, Y_2, Y_3)), Y_4) \\ &= -g(\varphi_{\alpha}(\sigma\{(\nabla_X R)(Y_1, Y_2, Y_3)\}), Y_4) = 0, \end{aligned}$$

where σ denotes the cyclic sum with respect to X, Y_1 and Y_2 . Therefore, we have

Theorem 5.1 *In a hyperholomorphic B-manifold, the Riemannian curvature tensor field is a pluralholomorphic tensor field.*

Theorem 5.2 *A necessary and sufficient condition for an exact 1-form df , $f \in \mathfrak{S}_0^0(M_{2m})$ to be hyperholomorphic, i.e., $\Phi_\alpha(df) = 0$, is that an associated 1-form $df \circ \varphi_\alpha$ be closed, i.e., $d(df \circ \varphi_\alpha) = 0$.*

Proof Using

$$(d\omega)(X, Y) = \frac{1}{2}\{X(\omega(Y)) - Y(\omega(X)) - \omega([X, Y])\}, \quad X, Y \in \mathfrak{S}_0^1(M_{2n}), \quad \omega \in \mathfrak{S}_1^0(M_{2n})$$

for $(\omega \circ \varphi_\alpha)(X) = \omega(\varphi_\alpha(X))$, we have

$$\begin{aligned} (d\omega)(Y, \varphi_\alpha X) &= \frac{1}{2}\{Y(\omega(\varphi_\alpha X)) - (\varphi_\alpha X)(\omega(Y)) - \omega([Y, \varphi_\alpha X])\} \\ &= \frac{1}{2}\{Y(\omega(\varphi_\alpha X)) - (\varphi_\alpha X)(\omega(Y)) + \omega([\varphi_\alpha X, Y])\} \\ &= \frac{1}{2}\{Y(\omega(\varphi_\alpha X)) - (\varphi_\alpha X)(\omega(Y)) + \omega([\varphi_\alpha X, Y]) - \varphi_\alpha[X, Y] + \varphi_\alpha[X, Y]\}. \end{aligned} \quad (5.6)$$

From (2.1), we have

$$\begin{aligned} (\Phi_\alpha \omega)(X, Y) &= (\varphi_\alpha X)(\omega(Y)) - X(\omega(\varphi_\alpha Y)) + \omega((L_Y \varphi_\alpha)(X)) \\ &= (\varphi_\alpha X)(\omega(Y)) - X(\omega(\varphi_\alpha Y)) - \omega([\varphi_\alpha X, Y] - \varphi_\alpha[X, Y]). \end{aligned} \quad (5.7)$$

Substituting (5.7) into (5.6), we obtain

$$\begin{aligned} (d\omega)(Y, \varphi_\alpha X) &= \frac{1}{2}\{-(\Phi_\alpha \omega)(X, Y) + Y(\omega(\varphi_\alpha X)) - X(\omega(\varphi_\alpha Y)) + \omega(\varphi_\alpha[X, Y])\} \\ &= -\frac{1}{2}\{(\Phi_\alpha \omega)(X, Y) + Y((\omega \circ \varphi_\alpha)(X)) - X((\omega \circ \varphi_\alpha)(Y)) - (\omega \circ \varphi_\alpha)([Y, X])\} \\ &= -\frac{1}{2}(\Phi_\alpha \omega)(X, Y) + (d(\omega \circ \varphi_\alpha))(Y, X). \end{aligned}$$

From this we see that the equation $\Phi_\alpha \omega = 0$ is equivalent to

$$(d(\omega \circ \varphi_\alpha))(Y, X) = (d\omega)(Y, \varphi_\alpha X). \quad (5.8)$$

For $\omega = df$, equation (5.8) turns into the following simple form

$$(d(df \circ \varphi_\alpha))(Y, X) = (d^2 f)(Y, \varphi_\alpha X) = 0, \quad \text{i.e.,} \quad d(df \circ \varphi_\alpha) = 0. \quad (5.9)$$

Thus Theorem 5.2 is proved.

If there exists a function g in a hyperholomorphic B-manifold such that $df \circ \varphi_\alpha = dg$ for a function f , then we call f a hyperholomorphic function and g an associated function. If such a function f is defined locally, then we call it a locally hyperholomorphic function.

We notice that equation (5.9) is equivalent to $df \circ \varphi = dg$ only locally. Hence, the condition for f to be locally hyperholomorphic $(\varphi_i^m \partial_m f = \partial_i g)$ is also given by

$$(\Phi_\alpha df)_{ij} = \varphi_i^m \partial_m \partial_j f - \partial_i (\varphi_j^m \partial_m f) + (\partial_j \varphi_i^m) \partial_m f = 0.$$

Let $(M_{2m}, \varphi_\alpha, g)$ be a hyperholomorphic B-manifold with B-metric g . Then from Theorem 5.1 and (5.1), we find that in plurallholomorphic B-manifolds the covariant derivative of the curvature tensor field ∇R is also pure. Now, the covariant derivative of the Ricci tensor $R_{ji} = R_{sji}^s = g^{ts} R_{tjis}$ is pure in all its indices and hence

$$\varphi_t^s \nabla_s R_{ji} = \varphi_j^s \nabla_t R_{si}.$$

Contracting this equation with contravariant B-metric g^{ji} , we find

$$\varphi_t^s \nabla_s R = g^{ji} \varphi_j^s \nabla_t R_{si} = \nabla_t (G_\alpha^{si} R_{si}) = \nabla_t R_\alpha^*, \quad (5.10)$$

where $R = g^{ij} R_{ij}$ is the scalar curvature of B-metric g and $R_\alpha^* = g^{ji} \varphi_j^s R_{si}$.

From (5.10), we have

Theorem 5.3 *In a hyperholomorphic B-manifold, the scalar curvature R is a locally hyperholomorphic function.*

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