

# Constructions of Metric $(n + 1)$ -Lie Algebras\*

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**Abstract** Metric  $n$ -Lie algebras have wide applications in mathematics and mathematical physics. In this paper, the authors introduce two methods to construct metric  $(n + 1)$ -Lie algebras from metric  $n$ -Lie algebras for  $n \geq 2$ . For a given  $m$ -dimensional metric  $n$ -Lie algebra  $(\mathfrak{g}, [\cdot, \dots, \cdot], B_g)$ , via one and two dimensional extensions  $\mathfrak{L} = \mathfrak{g} \dot{+} \mathbb{F}c$  and  $\mathfrak{g}_0 = \mathfrak{g} \dot{+} \mathbb{F}x^{-1} \dot{+} \mathbb{F}x^0$  of the vector space  $\mathfrak{g}$  and a certain linear function  $f$  on  $\mathfrak{g}$ , we construct  $(m + 1)$ - and  $(m + 2)$ -dimensional  $(n + 1)$ -Lie algebras  $(\mathfrak{L}, [\cdot, \dots, \cdot]_{cf})$  and  $(\mathfrak{g}_0, [\cdot, \dots, \cdot]_1)$ , respectively. Furthermore, if the center  $Z(\mathfrak{g})$  is non-isotropic, then we obtain metric  $(n + 1)$ -Lie algebras  $(\mathfrak{L}, [\cdot, \dots, \cdot]_{cf}, B)$  and  $(\mathfrak{g}_0, [\cdot, \dots, \cdot]_1, B)$  which satisfy  $B|_{\mathfrak{g} \times \mathfrak{g}} = B_g$ . Following this approach the extensions of all  $(n + 2)$ -dimensional metric  $n$ -Lie algebras are discussed.

**Keywords**  $n$ -Lie algebra, Metric  $n$ -Lie algebra, Extension, Isotropic center

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## 1 Introduction

Lie algebras have played an extremely important role in physics for a long time. Their generalizations, known as  $n$ -Lie algebras (see [1–3]), also arise naturally in physics and have recently been studied in the context of  $M$ -branes (see [4–8]). The applications of  $n$ -Lie algebras to  $M$ -branes, quantization of Nambu mechanics, volume-preserving diffeomorphisms, integrable systems, and related generalizations of Lax equations have been considered in [9].

Due to the multiple multiplication, structures of  $n$ -Lie algebras are complex. Ling proved in [10] that there is only one finite dimensional simple  $n$ -Lie algebra over the complex numbers under the isomorphism, which is the  $(n + 1)$ -dimensional  $n$ -Lie algebra  $\mathfrak{g}$  with  $\dim \mathfrak{g}^1 = n + 1$ . Kasymov in [11] defined nilpotent  $n$ -Lie algebras and Cartan subalgebras of  $n$ -Lie algebras, and proved that Cartan subalgebras of an  $n$ -Lie algebra are conjugate, and the similar Engel's theorem is true in  $n$ -Lie algebras. More results on structures of  $n$ -Lie algebras can be seen in [12–17]. A metric  $n$ -Lie algebra  $(L, [\cdot, \dots, \cdot], B)$  over a field  $F$  is an  $n$ -Lie algebra  $(L, [\cdot, \dots, \cdot])$  endowed with a non-degenerate symmetric bilinear form  $B : L \otimes L \rightarrow F$  satisfying the ad-invariant Equation (2.2). The structure of metric 3-Lie algebras is applied to the study of the supersymmetry and gauge symmetry transformations of the world-volume theory of multiple coincident  $M2$ -branes (see [4]); the Bagger-Lambert theory has a novel local gauge symmetry which is based on a metric 3-Lie algebra (see [5, 18]). Papers [19–20] studied structures of metric  $n$ -Lie algebras over the real numbers. Paper [21] discussed the isotropic ideals of metric

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$n$ -Lie algebras over the complex numbers, and obtained the formulation on metric dimensions and numbers of minimal ideals of metric  $n$ -Lie algebras.

Realization of  $n$ -Lie algebras is very important, but it is indeed difficult. In reference [1], Fillipov constructed  $n$ -Lie algebras, called Jacobian algebras, by a commutative associative algebra  $A$  and  $n$  commutative derivations  $D_1, \dots, D_n$ , where the multiplication is defined as: For  $x_1, \dots, x_n \in A$ ,  $[x_1, \dots, x_n] = \det(D_i(x_j))$ . Authors in [17, 22–23] constructed some infinite dimensional simple Jacobian  $n$ -Lie algebras over the fields of positive characters. P. Ho, Y. Imamura and Y. Matsuo studied two derivations of the multiple  $D2$  action from the multiple  $M2$ -brane model proposed by Bagger-Lambert and Gustavsson; they constructed metric 3-Lie algebras by arbitrary metric Lie algebras through 2-dimensional extensions (see [24]). Bai and collaborators realized 3-Lie algebras by Lie algebras, pre-Lie algebras, commutative associative algebras and linear functions and derivations (see [25–26]), and constructed  $(n+1)$ -Lie algebras by arbitrary  $n$ -Lie algebras (see [27]). They also constructed two-step nilpotent 3-Lie algebras by four index matrices (see [28]). In this paper we construct metric  $(n+1)$ -Lie algebras from metric  $n$ -Lie algebras ( $n \geq 2$ ) and linear functions.

Throughout this paper, all  $n$ -Lie algebras ( $n \geq 2$ ) are of finite dimension and over an algebraically closed field  $\mathbb{F}$  of characteristic zero. Any bracket which is not listed in the multiplication of an  $n$ -Lie algebra is assumed to be zero.

## 2 Fundamental Notions

First we introduce some basic notions used in the paper (see [1, 21]). An  $n$ -Lie algebra is a vector space  $\mathfrak{g}$  over a field  $\mathbb{F}$  endowed with an  $n$ -ary multi-linear skew-symmetric operation  $[x_1, \dots, x_n]$  satisfying the  $n$ -Jacobi identity

$$[[x_1, \dots, x_n], y_2, \dots, y_n] = \sum_{i=1}^n [x_1, \dots, [x_i, y_2, \dots, y_n], \dots, x_n]. \quad (2.1)$$

The mapping  $\text{ad}(x_1, \dots, x_{n-1}): \mathfrak{g} \rightarrow \mathfrak{g}$ ,  $\text{ad}(x_1, \dots, x_{n-1})(x_n) = [x_1, \dots, x_n]$  for all  $x_n \in \mathfrak{g}$ , is called a left multiplication defined by elements  $x_1, \dots, x_{n-1} \in \mathfrak{g}$ .

A subspace  $I$  of  $\mathfrak{g}$  is called a subalgebra (an ideal) if  $[I, \dots, I] \subseteq I$  ( $[I, \mathfrak{g}, \dots, \mathfrak{g}] \subseteq I$ ). The subalgebra generated by the vectors  $[x_1, \dots, x_n]$  for all  $x_1, \dots, x_n \in \mathfrak{g}$  is called the derived algebra of  $\mathfrak{g}$ , which is denoted by  $\mathfrak{g}^1$ . If  $\mathfrak{g}^1 = 0$ , then  $\mathfrak{g}$  is called abelian. If  $\mathfrak{g}^1 \neq 0$  and  $\mathfrak{g}$  has no ideals other than 0 and itself, then  $\mathfrak{g}$  is called a simple  $n$ -Lie algebra. A minimal (maximal) ideal is a nontrivial ideal  $I$  such that if  $J \neq 0$  is an ideal of  $\mathfrak{g}$  and  $J \subseteq I$  ( $J \supseteq I$ ), then  $J = I$  ( $J = \mathfrak{g}$ ).

The subset  $Z(\mathfrak{g}) = \{x \in \mathfrak{g} \mid [x, y_1, \dots, y_{n-1}] = 0, \forall y_1, \dots, y_{n-1} \in \mathfrak{g}\}$  is called the center of  $\mathfrak{g}$ . Obviously,  $Z(\mathfrak{g})$  is an abelian ideal of  $\mathfrak{g}$ .

Let  $(\mathfrak{g}, [\dots])$  be an  $n$ -Lie algebra. If a non-degenerate symmetric bilinear form  $B_g: \mathfrak{g} \otimes \mathfrak{g} \rightarrow \mathbb{F}$  is ad-invariant, that is, for arbitrary  $x_1, \dots, x_{n-1}, y, z \in \mathfrak{g}$ ,

$$B_g([x_1, \dots, x_{n-1}, y], z) = -B_g(y, [x_1, \dots, x_{n-1}, z]), \quad (2.2)$$

then  $(\mathfrak{g}, [\dots], B_g)$  is called a metric  $n$ -Lie algebra, and  $B_g$  is called a metric on  $\mathfrak{g}$ . For a subspace  $W$  of  $\mathfrak{g}$ , the orthogonal complement of  $W$  is defined by

$$W^\perp = \{x \in \mathfrak{g} \mid B_g(w, x) = 0 \text{ for all } w \in W\}.$$

If  $W$  is an ideal, so is  $W^\perp$  and  $(W^\perp)^\perp = W$ . Notice that  $W$  is a minimal ideal if and only if  $W^\perp$  is maximal. We say that  $W$  is isotropic (coisotropic) if  $W \subseteq W^\perp$  ( $W^\perp \subseteq W$ ). It is not difficult to see that  $\mathfrak{g}^1 = [\mathfrak{g}, \dots, \mathfrak{g}] = Z(\mathfrak{g})^\perp$ .

**Lemma 2.1** (see [27]) *Let  $(\mathfrak{g}, [\dots], B_g)$  be an  $m$ -dimensional metric  $n$ -Lie algebra with a basis  $\{x_1, \dots, x_m\}$ . Suppose that  $x^{-1}$  and  $x_0$  are not contained in  $\mathfrak{g}$ . Set*

$$\mathfrak{g}_0 = \mathfrak{g} \oplus \mathbb{F}x^0 \oplus \mathbb{F}x^{-1} \quad (\text{a direct sum of vector spaces}).$$

*Then  $(\mathfrak{g}_0, [\dots]_0, B_0)$  is a metric  $(n+1)$ -Lie algebra whose bracket and metric are given below. For every  $1 \leq k \leq n+1$ ,*

$$\begin{cases} [x_{i_1}, \dots, \underbrace{x_0}_k, \dots, x_{i_n}]_0 = (-1)^{k-1} [x_{i_1}, \dots, x_{i_n}], & 1 \leq i_1, \dots, i_n \leq m; \\ [x_{i_1}, \dots, \underbrace{x^{-1}}_k, \dots, x_{i_n}]_0 = 0, & 0 \leq i_1, \dots, i_n \leq m, \\ [x_{i_1}, \dots, x_{i_n}, x_{i_{n+1}}]_0 = B_g([x_{i_1}, \dots, x_{i_n}], x_{i_{n+1}})x^{-1}, & 1 \leq i_1, \dots, i_{n+1} \leq m, \end{cases} \quad (2.3)$$

$$B_0 : \mathfrak{g}_0 \otimes \mathfrak{g}_0 \rightarrow \mathbb{F} : \begin{cases} B_0(x, y) = B_g(x, y), \\ B_0(x_0, x_0) = 1, \\ B_0(x^{-1}, x_0) = (-1)^{n-1}, \\ B_0(x^{-1}, y) = B_0(x^{-1}, x^{-1}) = B_0(x_0, y) = 0, \quad \forall x, y \in \mathfrak{g}. \end{cases} \quad (2.4)$$

**Lemma 2.2** (see [25]) *Let  $(\mathfrak{g}, [\dots])$  be an  $n$ -Lie algebra and  $f \in \mathfrak{g}^*$  the dual space of  $\mathfrak{g}$ . If  $f \neq 0$  and  $f(\mathfrak{g}^1) = 0$ , then  $(\mathfrak{g}, [\dots]_f)$  is an  $(n+1)$ -Lie algebra, where  $[\dots]_f$  is defined as follows: for all  $x_1, \dots, x_{n+1} \in \mathfrak{g}$ ,*

$$[x_1, \dots, x_{n+1}]_f = \sum_{i=1}^{n+1} (-1)^{i-1} f(x_i) [x_1, \dots, \widehat{x}_i, \dots, x_{n+1}]. \quad (2.5)$$

### 3 One Dimensional Extensions of Metric $n$ -Lie Algebras

Let  $(\mathfrak{g}, [\dots], B_g)$  be an  $m$ -dimensional metric  $n$ -Lie algebra. If  $f \in \mathfrak{g}^*$  and  $f(\mathfrak{g}^1) = 0$ , we construct  $(m+1)$ -dimensional  $(n+1)$ -Lie algebras.

**Theorem 3.1** *Let  $(\mathfrak{g}, [\dots], B_g)$  be a non-abelian metric  $n$ -Lie algebra. If  $0 \neq f \in \mathfrak{g}^*$  and  $f(\mathfrak{g}^1) = 0$ , then  $B_g$  is not ad-invariant on the  $(n+1)$ -Lie algebra  $(\mathfrak{g}, [\dots]_f)$ , where  $[\dots]_f$  is defined as Equation (2.5).*

**Proof** If for all  $x_1, \dots, x_n, y, z \in \mathfrak{g}$ ,  $B_g$  satisfies  $B_g([x_1, \dots, x_n, y]_f, z) + B_g(z, [x_1, \dots, x_n, z]_f) = 0$ , then by Equation (2.5)

$$\begin{aligned} & B_g([x_1, \dots, x_n, y]_f, z) + B_g(y, [x_1, \dots, x_n, z]_f) \\ &= B_g\left(\sum_{i=1}^n (-1)^{i-1} f(x_i) [x_1, \dots, \widehat{x}_i, \dots, x_n, y] + (-1)^n f(y) [x_1, \dots, x_n, z]\right) \\ & \quad + B_g\left(y, \sum_{i=1}^n (-1)^{i-1} f(x_i) [x_1, \dots, \widehat{x}_i, \dots, x_n, z] + (-1)^n f(z) [x_1, \dots, x_n]\right) \\ &= B_g((-1)^n f(y) [x_1, \dots, x_n, z] + B_g(y, (-1)^n f(z) [x_1, \dots, x_n])) \\ &= (-1)^n B_g([x_1, \dots, x_n], f(z)y + f(y)z) = 0. \end{aligned}$$

Since  $f \neq 0$ , there is a basis  $\{v_1, \dots, v_m\}$  of  $\mathfrak{g}$  such that  $f(v_1) = 1$  and  $f(v_i) = 0$  for  $2 \leq i \leq m$ . It follows that  $v_1 \notin \mathfrak{g}^1$  and

$$\begin{aligned} & B_g([v_{i_1}, \dots, v_{i_n}], f(v_1)v_k + f(v_k)v_1) \\ &= B_g([v_{i_1}, \dots, v_{i_n}], v_k) = 0, \quad 1 \leq i_1, \dots, i_n \leq m, \quad k \geq 2. \end{aligned}$$

Since  $B_g([v_{i_1}, \dots, v_{i_n}], v_1) = -B_g(v_{i_n}, [v_{i_1}, \dots, v_{i_{n-1}}, v_1]) = 0$ ,  $B_g(\mathfrak{g}^1, \mathfrak{g}) = 0$ . Therefore,  $\mathfrak{g}^1 = 0$ , a contradiction. The desired result follows.

**Theorem 3.2** *Let  $(\mathfrak{g}, [\dots], B_g)$  be a metric  $n$ -Lie algebra and  $\mathfrak{g}^1 \neq \mathfrak{g}$ . Suppose that  $c$  is an element not in  $\mathfrak{g}$ , and suppose that  $\mathfrak{L} = \mathfrak{g} \dot{+} \mathbb{F}c$  is the one-dimensional extension of the vector space  $\mathfrak{g}$ . Then there is a nonzero  $f \in \mathfrak{g}^*$  such that  $f(\mathfrak{g}^1) = 0$  and  $(\mathfrak{L}, [\dots], \cdot)_{cf}$  is an  $(n+1)$ -Lie algebra, where the multiplication  $[\dots]_{cf}$  is defined as follows:*

$$\begin{cases} [x_1, \dots, x_{n+1}]_{cf} = [x_1, \dots, x_{n+1}]_f + cB_g([x_1, \dots, x_n], x_{n+1}) \\ \quad = \sum_{i=1}^{n+1} (-1)^{i-1} f(x_i) [x_1, \dots, \widehat{x}_i, \dots, x_{n+1}] + cB_g([x_1, \dots, x_n], x_{n+1}), \\ [x_1, \dots, x_n, c]_{cf} = 0, \quad \forall x_1, \dots, x_{n+1} \in \mathfrak{g}. \end{cases} \quad (3.1)$$

Furthermore, if the center  $Z(\mathfrak{g})$  is non-isotropic, then there is a metric  $B$  on  $(\mathfrak{L}, [\dots], \cdot)_{cf}$  such that  $B(v, w) = B_g(v, w)$  for all  $v, w \in \mathfrak{g}$ .

**Proof** By Equations (2.2) and (2.5), we only need to prove that  $[\dots]_{cf}$  satisfies Equation (2.1). For all  $x_1, \dots, x_{2n+1} \in \mathfrak{g}$ , by Equation (3.1),

$$\begin{aligned} & [[x_1, \dots, x_{n+1}]_{cf}, x_{n+2}, \dots, x_{2n+1}]_{cf} \\ &= [[x_1, \dots, x_{n+1}]_f, x_{n+2}, \dots, x_{2n+1}]_{cf} \\ &= [[x_1, \dots, x_{n+1}]_f, x_{n+2}, \dots, x_{2n+1}]_f + cB_g([x_1, \dots, x_{n+1}]_f, x_{n+2}, \dots, x_{2n+1}) \\ &= [[x_1, \dots, x_{n+1}]_f, x_{n+2}, \dots, x_{2n+1}]_f + (-1)^n cB_g([x_1, \dots, x_{n+1}]_f, [x_{n+2}, \dots, x_{2n+1}]), \\ & \quad \sum_{i=1}^{n+1} [x_1, \dots, [x_i, x_{n+2}, \dots, x_{2n+1}]_{cf}, \dots, x_{n+1}]_{cf} \\ &= \sum_{i=1}^{n+1} [x_1, \dots, [x_i, x_{n+2}, \dots, x_{2n+1}]_f, \dots, x_{n+1}]_{cf} \\ &= \sum_{i=1}^{n+1} [x_1, \dots, [x_i, x_{n+2}, \dots, x_{2n+1}]_f, \dots, x_{n+1}]_f \\ & \quad + c \sum_{i=1}^{n+1} (-1)^{n-i+1} B_g([x_i, x_{n+2}, \dots, x_{2n+1}]_f, [x_1, \dots, \widehat{x}_i, \dots, x_{n+1}]) \\ &= \sum_{i=1}^{n+1} [x_1, \dots, [x_i, x_{n+2}, \dots, x_{2n+1}]_f, \dots, x_{n+1}]_f \\ & \quad + c \sum_{i=1}^{n+1} (-1)^{n-i+1} f(x_i) B_g([x_{n+2}, \dots, x_{2n+1}], [x_1, \dots, \widehat{x}_i, \dots, x_{n+1}]) \\ & \quad + c \sum_{i=1}^{n+1} \sum_{j=2}^{n+1} (-1)^{n+i+j} f(x_{n+j}) B_g([x_i, \dots, \widehat{x}_{n+j}, \dots, x_{2n+1}], [x_1, \dots, \widehat{x}_i, \dots, x_{n+1}]) \end{aligned}$$

$$\begin{aligned}
 &= \sum_{i=1}^{n+1} [x_1, \dots, [x_i, x_{n+2}, \dots, x_{2n+1}]_f, \dots, x_{n+1}]_f \\
 &\quad + (-1)^n c B_{\mathfrak{g}}([x_{n+2}, \dots, x_{2n+1}], [x_1, \dots, x_{n+1}]_f) \\
 &\quad + c \sum_{i=1}^{n+1} \sum_{j=2}^{n+1} (-1)^{n+i+j} f(x_{n+j}) B_{\mathfrak{g}}([x_i, \dots, \widehat{x}_{n+j}, \dots, x_{2n+1}], [x_1, \dots, \widehat{x}_i, \dots, x_{n+1}]), \\
 &\quad \sum_{i=1}^{n+1} \sum_{j=2}^{n+1} (-1)^{n+i+j} f(x_{n+j}) B_{\mathfrak{g}}([x_i, \dots, \widehat{x}_{n+j}, \dots, x_{2n+1}], [x_1, \dots, \widehat{x}_i, \dots, x_{n+1}]) \\
 &= \sum_{i=1}^n \sum_{j=2}^{n+1} (-1)^{n+i+j} f(x_{n+j}) B_{\mathfrak{g}}([x_i, x_{n+2}, \dots, \widehat{x}_{n+j}, \dots, x_{2n+1}], [x_1, \dots, \widehat{x}_i, \dots, x_{n+1}]) \\
 &\quad + \sum_{j=2}^{n+1} (-1)^{j-1} f(x_{n+j}) B_{\mathfrak{g}}([x_{n+1}, x_{n+2}, \dots, \widehat{x}_{n+j}, \dots, x_{2n+1}], [x_1, \dots, x_n]) \\
 &= \sum_{i=1}^n \sum_{j=2}^{n+1} (-1)^{n+i+j-1} f(x_{n+j}) B_{\mathfrak{g}}([x_1, \dots, \widehat{x}_i, \dots, x_n, [x_i, x_{n+2}, \dots, \widehat{x}_{n+j}, \dots, x_{2n+1}]], x_{n+1}) \\
 &\quad + \sum_{j=2}^{n+1} (-1)^j f(x_{n+j}) B_{\mathfrak{g}}([x_1, \dots, x_n, x_{n+2}, \dots, \widehat{x}_{n+j}, \dots, x_{2n+1}], x_{n+1}) \\
 &= \sum_{j=2}^{n+1} (-1)^{j+1} f(x_{n+j}) B_{\mathfrak{g}}([x_1, \dots, x_n, x_{n+2}, \dots, \widehat{x}_{n+j}, \dots, x_{2n+1}], x_{n+1}) \\
 &\quad + \sum_{j=2}^{n+1} (-1)^j f(x_{n+j}) B_{\mathfrak{g}}([x_1, \dots, x_n, x_{n+2}, \dots, \widehat{x}_{n+j}, \dots, x_{2n+1}], x_{n+1}) = 0.
 \end{aligned}$$

Therefore,  $(\mathfrak{L}, [\dots]_{cf})$  is an  $(n+1)$ -Lie algebra.

If the center  $Z(\mathfrak{g})$  is non-isotropic, by [21, Lemma 2.3],  $Z(\mathfrak{g}) \not\subseteq Z(\mathfrak{g})^\perp = \mathfrak{g}^1$ . There is a non-zero vector  $v_1 \in Z(\mathfrak{g}) - \mathfrak{g}^1$  such that  $\mathfrak{g} = \mathbb{F}v_1 \oplus \mathfrak{g}_1$ , where  $\mathfrak{g}_1$  is an ideal of  $\mathfrak{g}$  and  $\mathfrak{g}^1 \subseteq \mathfrak{g}_1$ , and  $[v_1, \mathfrak{g}_1, \dots, \mathfrak{g}_1] = 0$ . Then,  $B_g|_{\mathfrak{g}_1 \times \mathfrak{g}_1}$  is non-degenerate and  $B_g(v_1, \mathfrak{g}_1) = 0$ . We can choose vectors  $v_2, \dots, v_m \in \mathfrak{g}_1$  such that  $\{v_1, \dots, v_m\}$  is a basis of  $\mathfrak{g}$ , and choose  $f \in \mathfrak{g}^*$  satisfying

$$\begin{cases} f(v_1) = 1 \\ f(v_k) = 0, \quad 2 \leq k \leq m. \end{cases} \quad (3.2)$$

Then  $\{v_1, \dots, v_m, c\}$  is a basis of  $\mathfrak{L}$ . Define the symmetric bilinear form  $B : \mathfrak{L} \otimes \mathfrak{L} \rightarrow \mathbb{F}$  by

$$\begin{cases} B(v_i, v_j) = B_g(v_i, v_j), \quad 1 \leq i, j \leq m, \\ B(v_1, c) = -1, \\ B(v_k, c) = 0, \quad 2 \leq k \leq m, \\ B(c, c) = 0, \end{cases} \quad (3.3)$$

where  $B$  is non-degenerate, and by Equations (3.2)–(3.3), for  $1 \leq i_1, \dots, i_{n+2} \leq m$ ,

$$\begin{aligned}
 &B([v_{i_1}, \dots, v_{i_{n+1}}]_{cf}, v_{i_{n+2}}) + B(v_{i_{n+1}}, [v_{i_1}, \dots, v_{i_n}, v_{i_{n+2}}]_{cf}) \\
 &= \sum_{t=1}^{n+1} f(v_{i_t}) B_g([v_{i_1}, \dots, \widehat{v}_{i_t}, \dots, v_{i_{n+1}}], v_{i_{n+2}}) + B_g([v_{i_1}, \dots, v_{i_n}], v_{i_{n+1}}) B(c, v_{i_{n+2}})
 \end{aligned}$$

$$\begin{aligned}
& + \sum_{t=1}^n f(v_{i_t}) B_g(v_{i_{n+1}}, [v_{i_1}, \dots, \widehat{v_{i_t}}, \dots, v_{i_n}, v_{i_{n+2}}]) \\
& + f(v_{i_{n+2}}) B_g(v_{i_{n+1}}, [v_{i_1}, \dots, v_{i_n}]) + B_g([v_{i_1}, \dots, v_{i_n}], v_{i_{n+2}}) B(c, v_{i_{n+1}}) \\
& = B_g([v_{i_1}, \dots, v_{i_n}], (f(v_{i_{n+1}}) + B(c, v_{i_{n+1}})) v_{i_{n+2}} + (f(v_{i_{n+2}}) + B(c, v_{i_{n+2}})) v_{i_{n+1}}) = 0.
\end{aligned}$$

Note also that for  $\lambda \in \mathbb{F}$ ,

$$\begin{aligned}
& B([v_1, v_{i_1}, \dots, v_{i_n}]_{cf}, c) + B(v_{i_n}, [v_1, v_{i_1}, \dots, v_{i_{n-1}}, c]_{cf}) \\
& = (-1)^n \lambda B_g(v_1, [v_{i_1}, \dots, v_{i_n}]) = 0.
\end{aligned}$$

Therefore,  $B$  is a metric on the  $(n+1)$ -Lie algebra  $(\mathfrak{L}, [\dots]_{cf})$  and satisfies  $B(v, w) = B_g(v, w)$  for all  $v, w \in \mathfrak{g}$ .

Let  $A, C$  be  $n$ -Lie algebras. An  $n$ -Lie algebra  $B$  is called a central extension of  $A$  by  $C$ , if the sequence of  $n$ -Lie algebras

$$0 \longrightarrow C \xrightarrow{i} B \xrightarrow{\pi} A \longrightarrow 0$$

is exact and  $C$  is in the center of  $B$ . From Theorem 3.2 and Lemma 2.2, the  $(n+1)$ -Lie algebra  $(\mathfrak{L}, [\dots]_{cf})$  is the one-dimensional central extension of the  $(n+1)$ -Lie algebra  $(\mathfrak{g}, [\dots]_f)$  by the one-dimensional abelian  $(n+1)$ -Lie algebra  $Fc$ .

**Remark 3.1** Let  $(\mathfrak{g}, [\dots], B_g)$  be a metric  $n$ -Lie algebra. If the center  $Z(\mathfrak{g})$  is isotropic, then the  $(n+1)$ -Lie algebra  $(\mathfrak{L}, [\dots]_f)$  in Theorem 3.2 may not be a metric  $(n+1)$ -Lie algebra.

**Example 3.1** Let  $(\mathfrak{g}, [, ], B_g)$  be a metric Lie algebra with a basis  $\{x_1, x_2, x_3, x_4, x_5\}$ , and

$$\begin{cases} [x_1, x_2] = x_3, \\ [x_2, x_3] = x_5, \\ [x_3, x_1] = x_4; \end{cases} \quad \begin{cases} B_g(x_1, x_5) = 1, \\ B_g(x_4, x_2) = 1, \\ B_g(x_3, x_3) = 1. \end{cases}$$

Then the center  $Z(\mathfrak{g}) = \mathbb{F}x_4 + \mathbb{F}x_5$  is a maximal isotropic ideal. For  $f \in V^*$  with  $f(x_1) = 1$  and  $f(x_i) = 0$ ,  $2 \leq i \leq 5$ , by Theorem 3.2, we obtain a six-dimensional 3-Lie algebra  $(\mathfrak{L}, [, ],_{cf})$ , with the multiplication  $[x_1, x_2, x_3]_{cf} = x_5 + c$ . By a direct computation,  $(\mathfrak{L}, [, ],_{cf}, B)$  is a metric 3-Lie algebra, and  $Z(\mathfrak{L}) = \mathbb{F}x_4 + \mathbb{F}x_5 + \mathbb{F}c = Z(\mathfrak{g}) + \mathbb{F}c$  is coisotropic.

**Example 3.2** Let  $(\mathfrak{g}, [, ], B_g)$  be a metric 3-Lie algebra with a basis  $\{x_1, x_2, x_3, x_4, x_5\}$ , and

$$\begin{cases} [x_2, x_3, x_4] = x_1, \\ [x_5, x_2, x_3] = x_4, \\ [x_5, x_3, x_4] = x_2, \\ [x_5, x_2, x_4] = x_3. \end{cases} \quad \begin{cases} B(x_1, x_5) = -1, \\ B(x_2, x_2) = 1, \\ B(x_3, x_3) = -1, \\ B(x_4, x_4) = 1, \\ B(x_5, x_5) = 1. \end{cases}$$

Then  $Z(\mathfrak{g}) = \mathbb{F}x_1$  is isotropic. For  $f \in \mathfrak{g}^*$ ,  $f(x_5) = 1$  and  $f(x_i) = 0$ ,  $1 \leq i \leq 4$ , by Theorem 3.2, we obtain a six-dimensional 4-Lie algebra  $(\mathfrak{L}, [, ],_{cf})$  with the multiplication  $[x_5, x_2, x_3, x_4]_{cf} = x_1 - c$ . By a direct computation, there does not exist a metric on  $(\mathfrak{L}, [, ],_{cf})$ .

## 4 Two-Dimensional Extension of Metric $n$ -Lie Algebras

In this section we discuss the two-dimensional extensions of metric  $n$ -Lie algebras.

**Lemma 4.1** (see [27]) *Let  $(\mathfrak{g}, [\cdot, \dots, \cdot], B_g)$  be an  $m$ -dimensional metric  $n$ -Lie algebra with a basis  $\{x_1, \dots, x_m\}$  and let  $x_0, x_{-1}$  be not contained in  $\mathfrak{g}$ . Then the vector space  $\mathfrak{g}_0 = \mathfrak{g} \oplus \mathbb{F}x^0 \oplus \mathbb{F}x^{-1}$  is an  $(n+1)$ -Lie algebra under the following multiplication  $[\cdot, \dots, \cdot]_0$ , for all natural numbers  $k$ ,  $1 \leq k \leq n+1$ ,*

$$\begin{cases} [x_{i_1}, \dots, \underbrace{x_0}_{k-1}, \dots, x_{i_n}]_0 = (-1)^{k-1} [x_{i_1}, \dots, x_{i_n}], & 1 \leq i_1, \dots, i_n \leq m; \\ [x_{i_1}, \dots, \underbrace{x_{-1}}_k, \dots, x_{i_n}]_0 = 0, & 0 \leq i_1, \dots, i_n \leq m; \\ [x_{i_1}, \dots, x_{i_n}, x_{i_{n+1}}]_0 = B([x_{i_1}, \dots, x_{i_n}], x_{i_{n+1}})x^{-1}, & 1 \leq i_1, \dots, i_{n+1} \leq m. \end{cases} \quad (4.1)$$

**Lemma 4.2** *Let  $(\mathfrak{g}, [\cdot, \dots, \cdot], B_g)$  be an  $m$ -dimensional metric  $n$ -Lie algebra. Then for all  $x_1, \dots, x_{n+1}, y_1, \dots, y_{n-1} \in \mathfrak{g}$ , we have*

$$\sum_{j=1}^{n+1} (-1)^j B_g([x_j, y_1, \dots, y_{n-1}], [x_1, \dots, \hat{x}_j, \dots, x_{n+1}]) = 0. \quad (4.2)$$

**Proof** By Equations (2.1)–(2.2), for all  $x_1, \dots, x_{n+1}, y_1, \dots, y_{n-1} \in \mathfrak{g}$ ,

$$\begin{aligned} & \sum_{j=1}^{n+1} (-1)^j B_g([x_j, y_1, \dots, y_{n-1}], [x_1, \dots, \hat{x}_j, \dots, x_{n+1}]) \\ &= \sum_{j=1}^n (-1)^j B_g([x_j, y_1, \dots, y_{n-1}], [x_1, \dots, \hat{x}_j, \dots, x_{n+1}]) \\ & \quad + (-1)^{n+1} B_g([x_{n+1}, y_1, \dots, y_{n-1}], [x_1, \dots, x_n]), \\ & \quad \sum_{j=1}^n (-1)^j B_g([x_j, y_1, \dots, y_{n-1}], [x_1, \dots, \hat{x}_j, \dots, x_{n+1}]) \\ &= \sum_{j=1}^n (-1)^{j+1} B_g(x_j, [[x_1, \dots, \hat{x}_j, \dots, x_{n+1}], y_1, \dots, y_{n-1}]) \\ &= \sum_{j=1}^n (-1)^{j+1} B_g(x_j, \sum_{k \neq j, k=1}^{n+1} [x_1, \dots, \hat{x}_j, \dots, [x_k, y_1, \dots, y_{n-1}], \dots, x_{n+1}]) \\ &= \sum_{j=1}^n (-1)^{j+1} B_g(x_j, \sum_{k \neq j, k=1}^n [x_1, \dots, \hat{x}_j, \dots, [x_k, y_1, \dots, y_{n-1}], \dots, x_{n+1}]) \\ & \quad + \sum_{j=1}^n (-1)^{j+1} B_g(x_j, [x_1, \dots, \hat{x}_j, \dots, x_n, [x_{n+1}, y_1, \dots, y_{n-1}]) \\ &= \sum_{j=1}^n (-1)^n \sum_{k \neq j, k=1}^n B_g([x_1, \dots, x_j, \dots, [x_k, y_1, \dots, y_{n-1}], \dots, x_n], x_{n+1}) \\ & \quad + \sum_{j=1}^n (-1)^n B_g([x_1, \dots, x_j, \dots, x_n], [x_{n+1}, y_1, \dots, y_{n-1}]) \\ &= (n-1)(-1)^n B_g([x_1, \dots, x_n], y_1, \dots, y_{n-1}), x_{n+1}) \end{aligned}$$

$$\begin{aligned}
& + n(-1)^n B_g([x_1, \dots, x_n], [x_{n+1}, y_1, \dots, y_{n-1}]) \\
& = (-1)^n B_g([x_1, \dots, x_n], [x_{n+1}, y_1, \dots, y_{n-1}]).
\end{aligned}$$

The result follows.

**Theorem 4.1** *Let  $(\mathfrak{g}, [\dots], B_g)$  be an  $m$ -dimensional metric  $n$ -Lie algebra with a basis  $\{x_1, \dots, x_m\}$ . Let  $0 \neq f \in \mathfrak{g}^*$  and  $f(\mathfrak{g}^1) = 0$ . Suppose  $x^0, x^{-1} \notin \mathfrak{g}$ . Then the vector space  $\mathfrak{g}_0 = \mathfrak{g} \oplus \mathbb{F}x^0 \oplus \mathbb{F}x^{-1}$  is an  $(m+2)$ -dimensional  $(n+1)$ -Lie algebra in the following multiplication, for all  $x_1, \dots, x_{n+1} \in \mathfrak{g}$ ,  $1 \leq k \leq n+1$ ,*

$$\left\{ \begin{aligned} [x_1, \dots, x_{n+1}]_1 &= [x_1, \dots, x_{n+1}]_f + B_g([x_1, \dots, x_n], x_{n+1})x^{-1} \\ &= \sum_{j=1}^{n+1} (-1)^{j-1} f(x_j) [x_1, \dots, \widehat{x}_j, \dots, x_{n+1}] \\ &\quad + B_g([x_1, \dots, x_n], x_{n+1})x^{-1}, \\ [x_1, \dots, \underbrace{x^0}_k, \dots, x_n]_1 &= (-1)^{k-1} [x_1, \dots, x_n], \\ [x_1, \dots, \underbrace{x^{-1}}_k, \dots, x_n]_1 &= 0. \end{aligned} \right. \quad (4.3)$$

Moreover, if the center  $Z(\mathfrak{g})$  is non-isotropic, then there is a metric  $B$  on the  $(n+1)$ -Lie algebra  $(\mathfrak{g}_0, [\dots, \dots]_1)$  such that  $B(v, w) = B_g(v, w)$  for all  $v, w \in \mathfrak{g}$ .

**Proof** For all  $x_1, \dots, x_{n+1} \in \mathfrak{g}$ , by Equations (3.1) and (4.3), we have

$[x_1, \dots, x_{n+1}]_1 = [x_1, \dots, x_{n+1}]_{x^{-1}f}$ , where  $[x_1, \dots, x_{n+1}]_{x^{-1}f}$  is defined as in Equation (3.1).

Then for all  $y_1, \dots, y_n \in \mathfrak{g}$ ,

$$\begin{aligned}
& [[x_1, \dots, x_{n+1}]_1, y_1, \dots, y_n]_1 \\
&= [[x_1, \dots, x_{n+1}]_{x^{-1}f}, y_1, \dots, y_n]_{x^{-1}f} \\
&= \sum_{j=1}^{n+1} [x_1, \dots, [x_j, y_1, \dots, y_n]_{x^{-1}f}, \dots, x_{n+1}]_{x^{-1}f} \\
&= \sum_{j=1}^{n+1} [x_1, \dots, [x_j, y_1, \dots, y_n]_1, \dots, x_{n+1}]_1, \\
&\quad [[x_1, \dots, x_n, x^0]_1, y_1, \dots, y_n]_1 \\
&= [[x_1, \dots, x_n], y_1, \dots, y_n]_1 \\
&= \sum_{j=1}^n (-1)^j f(y_j) [[x_1, \dots, x_n], y_1, \dots, \widehat{y}_j, \dots, y_n] \\
&\quad + x^{-1}(-1)^n B_g([x_1, \dots, x_n], [y_1, \dots, y_n]) \\
&= [[x_1, \dots, x_n], y_1, \dots, y_n]_f \\
&\quad + x^{-1}(-1)^n B_g([x_1, \dots, x_n], [y_1, \dots, y_n]), \\
&\quad \sum_{j=1}^n [x_1, \dots, [x_j, y_1, \dots, y_n]_1, \dots, x_n, x^0]_1
\end{aligned}$$

$$\begin{aligned}
 & + [x_1, \dots, x_n, [x^0, y_1, \dots, y_n]_1]_1 \\
 & = \sum_{j=1}^n [x_1, \dots, [x_j, y_1, \dots, y_n]_f, \dots, x_n] \\
 & \quad + (-1)^n [x_1, \dots, x_n, [y_1, \dots, y_n]]_1 \\
 & = \sum_{j=1}^n f(x_j) [x_1, \dots, \widehat{x_j}, [y_1, \dots, y_n], \dots, x_n] \\
 & \quad + (-1)^n [x_1, \dots, x_n, [y_1, \dots, y_n]]_f \\
 & \quad + \sum_{j,k=1}^n (-1)^k f(y_k) [x_1, \dots, [x_j, y_1, \dots, \widehat{y_k}, \dots, y_n], \dots, x_n] \\
 & \quad + (-1)^n B_g([x_1, \dots, x_n], [y_1, \dots, y_n]) \\
 & = \sum_{k=1}^n f(y_k) [[x_1, \dots, x_n], y_1, \dots, \widehat{y_k}, \dots, y_n] \\
 & \quad + (-1)^n B_g([x_1, \dots, x_n], [y_1, \dots, y_n]) \\
 & = [[x_1, \dots, x_n], y_1, \dots, y_n]_f + (-1)^n B_g([x_1, \dots, x_n], [y_1, \dots, y_n]) \\
 & = [[x_1, \dots, x_n, x^0]_1, y_1, \dots, y_n]_1.
 \end{aligned}$$

By Lemma 4.2,

$$\begin{aligned}
 & \sum_{j=1}^{n+1} [x_1, \dots, [x_j, y_1, \dots, y_{n-1}, x^0]_1, \dots, x_{n+1}]_1 \\
 & = \sum_{j=1}^{n+1} [x_1, \dots, [x_j, y_1, \dots, y_{n-1}], \dots, x_{n+1}]_1 \\
 & = \sum_{j=1}^{n+1} \sum_{k \neq j, k=1}^{n+1} (-1)^{k-1} f(x_k) [x_1, \dots, \widehat{x_k}, \dots, [x_j, y_1, \dots, y_{n-1}], \dots, x_{n+1}] \\
 & \quad + x^{-1} \left( \sum_{j=1}^{n+1} (-1)^{n+1-j} B_g([x_j, y_1, \dots, y_{n-1}], [x_1, \dots, \widehat{x_j}, \dots, x_{n+1}]) \right) \\
 & = [[x_1, \dots, x_{n+1}]_f, y_1, \dots, y_{n-1}] \\
 & \quad + x^{-1} \left( \sum_{j=1}^{n+1} (-1)^{n+1-j} B_g([x_j, y_1, \dots, y_{n-1}], [x_1, \dots, \widehat{x_j}, \dots, x_{n+1}]) \right) \\
 & = [[x_1, \dots, x_{n+1}]_1, y_1, \dots, y_{n-1}, x^0]_1 \\
 & \quad + x^{-1} \left( \sum_{j=1}^{n+1} (-1)^{n+1-j} B_g([x_j, y_1, \dots, y_{n-1}], [x_1, \dots, \widehat{x_j}, \dots, x_{n+1}]) \right), \\
 & = [[x_1, \dots, x_{n+1}]_1, y_1, \dots, y_{n-1}, x^0]_1 \\
 & \quad + x^{-1} (-1)^{n+1} \left( \sum_{j=1}^{n+1} (-1)^j B_g([x_j, y_1, \dots, y_{n-1}], [x_1, \dots, \widehat{x_j}, \dots, x_{n+1}]) \right), \\
 & = [[x_1, \dots, x_{n+1}]_1, y_1, \dots, y_{n-1}, x^0]_1.
 \end{aligned}$$

Thanks to Equation (4.3),

$$\begin{aligned}
& [[x_1, \dots, x_n, x^0]_1, y_1, \dots, y_{n-1}, x^0]_1 \\
&= [[x_1, \dots, x_n], y_1, \dots, y_{n-1}] \\
&= \sum_{j=1}^n [[x_1, \dots, [x_j, y_1, \dots, y_{n-1}], \dots, x_n] \\
&= \sum_{j=1}^n [[x_1, \dots, [x_j, y_1, \dots, y_{n-1}, x^0], \dots, x_n, x^0] + [[x_1, \dots, x_n, [x^0, y_1, \dots, y_{n-1}, x^0].
\end{aligned}$$

Therefore,  $(\mathfrak{g}_0 = \mathfrak{g} \oplus \mathbb{F}x^0 \oplus \mathbb{F}x^{-1}, [\dots, ]_1)$  is an  $(n+1)$ -Lie algebra in the multiplication defined by Equation (4.3).

If the center  $Z(\mathfrak{g})$  of the metric  $n$ -Lie algebra  $(\mathfrak{g}, [\dots, ], B_g)$  is non-isotropic, we denote  $\mathfrak{g}_1 = \mathfrak{g} \oplus \mathbb{F}x^{-1}$ . Then by Equations (4.3) and (3.1),  $(\mathfrak{g}_1, [\dots, ]_1)$  is a subalgebra of the  $(n+1)$ -Lie algebra  $(\mathfrak{g}_0, [\dots, ]_1)$ . Define a linear isomorphism

$$\sigma : \mathfrak{g}_1 = \mathfrak{g} \oplus \mathbb{F}x^{-1} \rightarrow \mathfrak{L} = \mathfrak{g} \oplus \mathbb{F}c : \begin{cases} \sigma(x) = x, & x \in \mathfrak{g}, \\ \sigma(x^{-1}) = c. \end{cases}$$

By Equations (3.1) and (4.3),  $\sigma$  is an algebraic isomorphism from  $(\mathfrak{g}_1, [\dots, ]_1)$  to  $(\mathfrak{L}, [\dots, ]_{cf})$ . By Theorem 3.2 and Equation (3.3), there is a metric  $B_1 : \mathfrak{g}_1 \times \mathfrak{g}_1 \rightarrow \mathbb{F}$  such that  $B_1|_{\mathfrak{g} \times \mathfrak{g}} = B_g$ . Now define  $B : \mathfrak{g}_0 \times \mathfrak{g}_0 \rightarrow \mathbb{F}$ , for all  $x_1, x_2 \in \mathfrak{g}$ ,

$$\begin{cases} B(x_1, x_2) = B_1(x_1, x_2), \\ B(x_1, x^{-1}) = B_1(x_1, x^{-1}), \\ B(x^{-1}, x^{-1}) = B_1(x^{-1}, x^{-1}), \\ B(x^0, x^{-1}) = -1, \\ B(x^0, x^0) = B(x^0, \mathfrak{g}) = 0. \end{cases}$$

Then  $B$  is non-degenerate on  $\mathfrak{g}_0$ . According to Equations (4.3)–(4.4) and a direct computation, we get that for all  $x_1, \dots, x_{n+2} \in \mathfrak{g}$ ,

$$\begin{aligned}
& B([x_1, \dots, x_{n+1}]_1, x^0) = B_g([x_1, \dots, x_n], x_{n+1})B(x^{-1}, x^0) \\
&= -B_g([x_1, \dots, x_n], x_{n+1}) = -B([x_1, \dots, x_n, x^0]_1, x_{n+1}), \\
& B([x_1, \dots, x_{n+1}]_1, x_{n+2}) = B_1([x_1, \dots, x_{n+1}]_f, x_{n+2}) \\
&= -B_1([x_1, \dots, x_n, x_{n+2}]_1, x_{n+1}) = -B([x_1, \dots, x_n, x_{n+2}]_1, x_{n+1}).
\end{aligned}$$

Therefore,  $(\mathfrak{g}, [\dots, ]_1, B)$  is a metric  $(n+1)$ -Lie algebra and satisfies  $B|_{\mathfrak{g} \otimes \mathfrak{g}} = B_g$ .

**Remark 4.1** Let  $(\mathfrak{g}, [\dots, ], B_g)$  be a metric  $n$ -Lie algebra. If the center  $Z(\mathfrak{g})$  is isotropic, then the  $(n+1)$ -Lie algebra in Theorem 4.3 may not be a metric  $(n+1)$ -Lie algebra. The counterexample can be seen in Section 5.

Let  $(\mathfrak{g}, [\dots, ], B_g)$  be the five-dimensional metric Lie algebra in Example 3.1, and  $f \in \mathfrak{g}^*$ ,  $f(x_1) = 1$  and  $f(x_i) = 0$  for  $2 \leq i \leq 5$ . Then the center  $Z(\mathfrak{g}) = \mathbb{F}x_4 + \mathbb{F}x_5$  is a maximal isotropic ideal. Suppose that  $x^0, x^{-1}$  are not contained in  $\mathfrak{g}$ , and  $\mathfrak{g}_0 = \mathfrak{g} \oplus \mathbb{F}x^0 \oplus \mathbb{F}x^{-1}$ . By

Theorem 4.3,  $(\mathfrak{g}_0, [\cdot, \cdot, \cdot]_1)$  is an  $(n+1)$ -Lie algebra with the multiplication

$$\begin{cases} [x^0, x_1, x_2]_1 = x_3, \\ [x^0, x_2, x_3]_1 = x_5, \\ [x^0, x_3, x_1]_1 = x_4, \\ [x_1, x_2, x_3]_1 = x_5 + x^{-1}. \end{cases}$$

Define  $B : \mathfrak{g}_0 \otimes \mathfrak{g}_0 \rightarrow \mathbb{F}$ ,

$$\begin{cases} B(x_1, x_5) = 1, \\ B(x_2, x_4) = 1, \\ B(x_3, x_3) = 1, \\ B(x_1, x^{-1}) = -1, \\ B(x^0, x^{-1}) = -1, \\ B(x^0, x_1) = B(x^0, x_i) = B(x^{-1}, x_i) = 0, \quad 2 \leq i \leq 5. \end{cases}$$

By the direct computation,  $(\mathfrak{g}_0, [\cdot, \cdot, \cdot]_1, B)$  is a metric 3-Lie algebra, and  $Z(\mathfrak{g}_0) = \mathbb{F}x_4 + \mathbb{F}x_5 + \mathbb{F}x^{-1} = Z(\mathfrak{g}) + \mathbb{F}x^{-1}$  is isotropic.

## 5 The Extensions of $(n+2)$ -Dimensional Metric $n$ -Lie Algebras

In this section, we give applications of Section 3 and Section 4. We provide the extensions of all  $(n+2)$ -dimensional metric  $n$ -Lie algebras.

By the paper [21] and Theorem 3.2 in [29], if  $(\mathfrak{g}, [\cdot, \cdot, \cdot], B_g)$  is an  $(n+2)$ -dimensional metric  $n$ -Lie algebra, then  $(\mathfrak{g}, [\cdot, \cdot, \cdot], B_g)$  is isomorphic to one and only one of the following:

$$(r^1) \begin{cases} [x_2, \dots, x_{n+1}] = x_1, \\ [x_{n+2}, x_2, \dots, \widehat{x_i}, \dots, x_{n+1}] = x_i, \quad 2 \leq i \leq n+1, \\ B_g(x_i, x_j) = (-1)^{n-i+1} \lambda \delta_{ij}, \quad 2 \leq i, j \leq n+1, \\ B_g(x_1, x_{n+2}) = (-1)^n \lambda, \quad \lambda \in \mathbb{F}, \lambda \neq 0, \\ B(x_{n+2}, x_{n+2}) = \mu, \quad \mu \in \mathbb{F}, \mu \neq 0, \\ B_g(x_1, x_i) = 0, \quad 1 \leq i \leq n+1, \\ B_g(x_{n+2}, x_i) = 0, \quad 2 \leq i \leq n+1, \end{cases} \quad (5.1)$$

$$(r^2) \begin{cases} [x_1, \dots, \widehat{x_i}, \dots, x_{n+1}] = x_i, \quad 1 \leq i \leq n+1, \\ B(x_i, x_j) = (-1)^{n-i+1} \lambda \delta_{ij}, \quad \lambda \in \mathbb{F}, \lambda \neq 0, \quad 1 \leq i, j \leq n+1, \\ B_g(x_{n+2}, x_{n+2}) = \mu, \quad \mu \in \mathbb{F}, \mu \neq 0, \\ B_g(x_{n+2}, x_i) = 0, \quad 1 \leq i \leq n+1, \end{cases} \quad (5.2)$$

where  $\{x_1, \dots, x_{n+1}, x_{n+2}\}$  is a basis of  $\mathfrak{g}$  and

$$\delta_{ij} = \begin{cases} 1, & i = j, \\ 0, & i \neq j. \end{cases}$$

Now we discuss the extensions of the cases  $(r^1)$  and  $(r^2)$ , respectively.

(a) Let  $(\mathfrak{g}, [\cdot, \dots, \cdot], B_g)$  be isomorphic to the case  $(r^1)$ . Then by Equation (5.1),  $Z(\mathfrak{g}) = \mathbb{F}x_1$  is isotropic.

(i<sub>a</sub>) Let  $c$  not be contained in  $\mathfrak{g}$ . Set

$$\mathfrak{L} = \mathfrak{g} \oplus \mathbb{F}c$$

and

$$f \in \mathfrak{g}^*, \quad f(x_{n+2}) = 1$$

and

$$f(x_k) = 0, \quad 1 \leq k \leq n+1.$$

Then by Theorem 3.2 and Equations (3.1) and (5.1), we obtain an  $(n+3)$ -dimensional  $(n+1)$ -Lie algebra  $(\mathfrak{L}, [\cdot, \dots, \cdot]_{cf})$  with the multiplication

$$\begin{cases} [x_{n+2}, x_2, \dots, x_{n+1}]_{cf} = x_1 + \lambda c, \\ [x_{n+2}, x_1, x_2, \dots, \widehat{x}_i, \dots, x_{n+1}]_{cf} = 0, & 2 \leq i \leq n+2, \\ [c, x_1, \dots, \widehat{x}_i, \dots, \widehat{x}_j, \dots, x_{n+2}]_{cf} = 0, & 1 \leq i, j \leq n+2. \end{cases}$$

The center  $Z(\mathfrak{L}) = \mathbb{F}x_1 \oplus \mathbb{F}c$ .

If a symmetric bilinear form  $B : \mathfrak{L} \times \mathfrak{L} \rightarrow \mathbb{F}$  satisfies Equation (2.2), then by a direct computation we get  $B(x_1 + \lambda c, \mathfrak{L}) = 0$ , that is,  $B$  is degenerate. Therefore, there does not exist a metric on  $(\mathfrak{L}, [\cdot, \dots, \cdot]_{cf})$ .

(ii<sub>a</sub>) Let  $x^0, x^{-1}$  be not contained in  $\mathfrak{g}$ . Set

$$\mathfrak{g}_0 = \mathfrak{g} \oplus \mathbb{F}x^0 \oplus \mathbb{F}x^{-1}$$

and

$$f \in \mathfrak{g}^*, \quad f(x_{n+2}) = 1$$

and

$$f(x_k) = 0, \quad 1 \leq k \leq n+1.$$

Then by Theorem 4.3 and Equations (4.3) and (5.1), the multiplication of the  $(n+4)$ -dimensional  $(n+1)$ -Lie algebra  $(\mathfrak{g}_0, [\cdot, \dots, \cdot]_1)$  is as follows:

$$\begin{cases} [x^0, x_2, \dots, x_{n+1}]_1 = x_1, \\ [x^0, x_{n+2}, x_2, \dots, \widehat{x}_i, \dots, x_{n+1}]_1 = x_i, & 2 \leq i \leq n+1, \quad Z(\mathfrak{g}_0) = \mathbb{F}x_1 \oplus \mathbb{F}x^{-1}, \\ [x_{n+2}, x_2, \dots, x_{n+1}]_1 = x_1 + \lambda x^{-1}. \end{cases}$$

For every symmetric bilinear form  $B : \mathfrak{g}_0 \otimes \mathfrak{g}_0 \rightarrow \mathbb{F}$  satisfying  $B|_{\mathfrak{g} \otimes \mathfrak{g}} = B_g$  and Equation (2.2), we have  $B(x_1, \mathfrak{g}_0) = 0$ , that is,  $B$  is degenerate. Therefore, there does not exist a metric on the  $(n+1)$ -Lie algebra  $(\mathfrak{g}_0, [\cdot, \dots, \cdot]_1)$ .

(b) Let  $(\mathfrak{g}, [\cdot, \dots, \cdot], B_g)$  be isomorphic to the case  $(r^2)$ . Then by Equation (5.2),  $Z(\mathfrak{g}) = \mathbb{F}x_{n+2}$  is non-isotropic.

(i<sub>b</sub>) Let  $c$  not be contained in  $\mathfrak{g}$ . Set

$$\mathfrak{L} = \mathfrak{g} \oplus \mathbb{F}c$$

and

$$f \in \mathfrak{g}^*, \quad f(x_{n+2}) = 1$$

and

$$f(x_k) = 0, \quad 1 \leq k \leq n+1.$$

Then by Theorem 3.2 and Equations (3.1) and (5.2), the multiplication and the metric of the  $(n+3)$ -dimensional metric  $(n+1)$ -Lie algebra  $(\mathfrak{L}, [\cdot, \cdot, \cdot]_{cf}, B)$  are as follows:

$$\begin{cases} [x_1, \dots, x_{n+1}]_{cf} = c, \\ [x_{n+2}, x_1, \dots, \widehat{x}_i, \dots, x_{n+1}]_{cf} = x_i, \quad 1 \leq i \leq n+1, \\ [c, x_{i_1}, \dots, x_{i_n}]_{cf} = 0, \quad 0 \leq i_1, \dots, i_{n+1} \leq n+2, \\ B(x_i, x_j) = (-1)^{n-i+1} \lambda \delta_{ij}, \quad 1 \leq i, j \leq n+1, \lambda \in \mathbb{F}, \lambda \neq 0, \\ B(x_{n+2}, x_{n+2}) = \mu, \quad \mu \in \mathbb{F}, \mu \neq 0, \\ B(c, x_{n+2}) = (-1)^{n+1} \lambda, \\ B(c, x_k) = B(c, c) = 0, \quad 1 \leq k \leq n+1. \end{cases}$$

The center  $Z(\mathfrak{L}) = \mathbb{F}c$  is isotropic.

(ii<sub>b</sub>) Let  $x^0, x^{-1}$  not be contained in  $\mathfrak{g}$ . Set

$$\mathfrak{g}_0 = \mathfrak{g} \oplus \mathbb{F}x^0 \oplus \mathbb{F}x^{-1}$$

and

$$f \in \mathfrak{g}^*, \quad f(x_{n+2}) = 1$$

and

$$f(x_k) = 0, \quad 1 \leq k \leq n+1.$$

Then by Theorem 4.3 and Equations (4.3)–(4.4) and (5.2), the multiplication and the metric of  $(\mathfrak{g}_0, [\cdot, \cdot, \cdot]_1, B)$  are as follows:

$$\begin{cases} [x^0, x_1, \dots, \widehat{x}_i, \dots, x_{n+1}]_1 = x_i, \quad 1 \leq i \leq n+1, \\ [x_{n+2}, x_1, \dots, \widehat{x}_i, \dots, x_{n+1}]_1 = x_i, \quad 1 \leq i \leq n+1, \\ [x_1, \dots, x_{n+1}]_1 = \lambda x^{-1}, \\ [x^{-1}, x_{i_1}, \dots, x_{i_n}]_1 = 0, \quad 0 \leq i_1, \dots, i_{n+1} \leq n+2, \\ B(x_i, x_j) = (-1)^{n-i+1} \lambda \delta_{ij}, \quad 1 \leq i, j \leq n+1, \lambda \in \mathbb{F}, \lambda \neq 0, \\ B(x_{n+2}, x_{n+2}) = \mu, \quad \mu \in \mathbb{F}, \mu \neq 0, \\ B(x^{-1}, x_{n+2}) = (-1)^{n+1} \lambda, \\ B(x^{-1}, x^0) = (-1)^{n+1} \lambda, \\ B(x^{-1}, x_k) = 0, \quad 1 \leq k \leq n+1, \\ B(x^{-1}, x^{-1}) = B(x^0, x^0) = B(x^0, x_k) = 0, \quad 1 \leq k \leq n+2, \end{cases}$$

and  $Z(\mathfrak{g}_0) = \mathbb{F}x^{-1} + \mathbb{F}(x_{n+2} - x^0)$  is non-isotropic.

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